

1 **Modal analysis of historical masonry**
2 **structures: linear perturbation and software**
3 **benchmarking**

4 Daniele Pellegrini^a, Maria Girardi^a, Paulo B. Lourenço^b, Maria Giovanna
5 Masciotta^b, Nuno Mendes^b, Cristina Padovani^a, Luis F. Ramos^b

6 ^a*Institute of Information Science and Technologies "A. Faedo", ISTI-CNR, Pisa, Italy*

7 ^b*ISISE, University of Minho, Department of Civil Engineering, Guimarães, Portugal*

8 **Abstract**

9 The mechanical behavior of masonry materials has a common feature: a non-
10 linear behavior with high compressive strength and very low tensile strength.
11 As a consequence, old masonry buildings generally present cracks due to per-
12 manent loads and/or accidental events. Therefore, the characterization of
13 the global dynamic behavior of masonry structures should take into account
14 the presence of existing cracks. This paper presents a numerical approach
15 coupling linear perturbation and modal analysis in order to estimate the dy-
16 namic properties of masonry constructions, taking into account the existence
17 of structural damage. First, the approach is validated on a masonry arch
18 subjected to increasing loads, via three FE codes. Then, the same procedure
19 is applied to a real masonry structure affected by a severe crack distribution.
20 *Keywords:* Masonry-like materials, masonry constructions, modal analysis,
21 numerical methods, nonlinear elasticity, linear perturbation

22 1. Introduction

23 Safeguarding of cultural heritage is an acquired principle nowadays, widely
24 shared by all communities. Preservation of the past is an indispensable re-
25 quirement for our society to foster knowledge, awareness of identity, and
26 ability to think of and plan the future. With regard to architectural her-
27 itage, age-old buildings and monuments need to be preserved not only from
28 damage mechanisms and deterioration processes induced by anthropogenic
29 and environmental actions, but also from the aging effects they are exposed
30 to during their lifetime. Furthermore, ancient structures are particularly
31 vulnerable to seismic actions, whose consequences should be prevented - or
32 at least mitigated - with effective strengthening measures and maintenance
33 plans. For this purpose, Structural Health Monitoring (SHM) and Finite El-
34 ement (FE) analysis represent complementary techniques which may help to
35 understand the complex dynamic behavior of ancient buildings and estimate
36 the mechanical properties of their constituent materials with use of limited
37 invasive testing procedures. In addition, if long-term monitoring protocols
38 are conducted, important information can be caught on the interactions be-
39 tween the structure under consideration and the surrounding environment
40 [4], [44], as well as on the evolution of the structural health over time. In
41 fact, significant changes in the structure's dynamic properties can reveal the
42 presence of structural damage, as pointed out in [21], [40], [43], where de-
43 creasing values of natural frequencies were measured at the onset of damage.
44 Moreover, dynamic monitoring can represent a valuable tool to assess the ef-

45 fectiveness of strengthening interventions, as shown in [33], [34], [44], where
46 evident rising in the natural frequencies was observed in the monitored his-
47 torical structures after restoration works.

48 Structural health monitoring is usually coupled with FE analysis via
49 model updating procedures [1], [2], [5], [10], [12], [45], [51], in order to de-
50 rive realistic information about the boundary conditions and the mechani-
51 cal properties of the structure's constituent materials, especially when more
52 invasive techniques are not viable as in case of heritage buildings. These
53 procedures typically consist in tuning some parameters of the FE model in
54 order to minimize the distance between numerical and experimental modal
55 properties (natural frequencies and mode shapes).

56 In this regard, it is worth noting that modal analysis is carried out within
57 the framework of linear elasticity. This setting could be unsuited for masonry
58 buildings, which may exhibit nonlinear behavior even for the self-weight and
59 sometimes show extended crack patterns. Therefore, the dynamic behavior
60 of these constructions should be analyzed by taking into account the existing
61 damage so as to avoid erroneous evaluations of the parameters, which may
62 in turn compromise the outcome of further numerical simulations. A common
63 approach to this problem consists in simulating the actual damage observed
64 on the structure by reducing the stiffness of those finite elements belonging
65 to the cracked or damaged parts [7], [10], [41], [43].

66 In [23] a numerical procedure implemented in the non commercial FE
67 software NOSA-ITACA (www.nosaitaca.it) is described. Here, the masonry

68 material is modeled via the masonry-like constitutive equation [14], [30].
69 This procedure allows evaluating the natural frequencies and mode shapes
70 of masonry buildings in the presence of cracks, via linear perturbation anal-
71 ysis and consists of the following steps: first, the initial loads and boundary
72 conditions are applied to the FE model and the resulting nonlinear equilib-
73 rium problem is solved through an iterative scheme. Then, a modal analysis
74 about the equilibrium solution is performed, by using the tangent stiffness
75 matrix calculated in the last iteration before convergence is reached, thereby
76 allowing the user to automatically take into account the effects of the stress
77 distribution on the structure's stiffness.

78 Other applications of linear perturbation, sometimes referred to as pre-
79 stressed modal analysis, are in the framework of large deformation problems
80 [13], [24], [36], [52]. With regard to masonry buildings, an example is shown
81 in [18], where linear perturbation is applied via a commercial code to a his-
82 toric masonry building.

83 This paper focuses on the use of linear perturbation to evaluate modal
84 properties of ancient masonry buildings in the presence of cracks. The
85 method is described in Section 2 and applied to a masonry arch in Section 3,
86 where the results obtained via different constitutive equations and FE codes
87 (DIANA, MARC, NOSA-ITACA) are compared and discussed. Then, a real
88 case application is presented in Section 4, where the Mogaduro clock tower is
89 analyzed via the NOSA-ITACA code, before and after the restoration works
90 carried out in 2005. The paper demonstrates that, by adopting the appro-

91 priate constitutive model, different FE codes do provide the same modal
92 features in the presence of a damaged structure. Moreover, making use of
93 the experimental results at the authors' disposal [44], it is shown that linear
94 perturbation analysis combined with finite element modal updating allows
95 identifying the tower's material properties (i.e. Young's modulus and tensile
96 strength) that consistently reflect the damaged condition of the structure
97 before restoration as well as the increase of the structural stiffness resulting
98 from the subsequent strengthening intervention.

99 **2. Constitutive equations, linear perturbation and modal analysis**

100 In recent years the advancement of computer technology and introduc-
101 tion of innovative mathematical models made it possible to assess the struc-
102 tural safety of complex ancient masonry buildings by taking into account
103 the nonlinear behavior of masonry materials, whose response to tension is
104 completely different from that to compression and whose mechanical char-
105 acteristics are the result of both their constituent elements and the building
106 techniques used. The numerous studies conducted in the last decades, aimed
107 at modeling the behavior of masonry structures, led to the formulation of
108 different constitutive laws that can be grouped into two main classes. The
109 first class includes those models in which the macroscopic behavior of the
110 masonry material is obtained from the micro-mechanical behavior of its sin-
111 gular components [37], [49], [47], [26], [16], [17]. The second class contains
112 instead the so-called macro-mechanical models, in which the masonry mate-

113 rial is modeled either as an equivalent continuum [6], [14], [30], [50], [35], or
114 as an assembly of macro elements with few degrees of freedom characterized
115 by certain global behaviors [25], [39], [48]. Models originally formulated for
116 concrete and subsequently applied to masonry structures [9], [46], [11] can be
117 included in this latter group. A comprehensive review of constitutive models
118 for masonry falls outside the scope of this paper and the reader is referred
119 to [27], [28], [29] and [42] for a thorough discussion.

120 When dealing with the analysis of ancient masonry buildings, constitutive
121 equations belonging to the second class are preferable. In fact, the applica-
122 tion of micro-mechanical models is not straightforward, since it is difficult
123 to identify a homogeneous and/or periodic structure in historical masonries.
124 Moreover, the use of micro-mechanical models requires accurate knowledge
125 of several parameters related to mechanical properties of the masonry con-
126 stituent elements, which can not be easily determined; furthermore, the em-
127 ployment of the micro-mechanical models to complex structures calls for high
128 computational cost. On the other hand, the application of macro-mechanical
129 models does require the knowledge of a few parameters, which can be ob-
130 tained from experimental tests, literature values or even from indications
131 provided by national building codes and regulations.

132 Among macro-mechanical models, the constitutive equation for low ten-
133 sion materials, implemented in MARC [32], and the Rankine model, im-
134 plemented in DIANA [15], are largely adopted to simulate the structural
135 behavior of masonry constructions. Along with these models, both based

136 on the theory of infinitesimal plasticity, the nonlinear elastic equation of
 137 masonry-like materials [30] is able to realistically describe the behavior of
 138 masonry buildings by taking into consideration their zero or low tensile
 139 strength. This constitutive equation has been implemented in NOSA-ITACA
 140 [8], [22], a finite element code developed and freely distributed by ISTI-CNR
 141 (www.nosaitaca.it). Here, masonry is modeled as an isotropic nonlinear elas-
 142 tic material with zero tensile strength and infinite compressive strength [14].
 143 It is possible to prove that for every infinitesimal strain tensor \mathbf{E} , there exists
 144 a unique triplet $(\mathbf{T}, \mathbf{E}^e, \mathbf{E}^f)$ of symmetric tensors such that \mathbf{E} is the sum of
 145 an elastic strain \mathbf{E}^e and a positive semidefinite fracture strain \mathbf{E}^f , and the
 146 Cauchy stress \mathbf{T} , negative semidefinite and orthogonal to \mathbf{E}^f , depends lin-
 147 early and isotropically on \mathbf{E}^e , through the Young's modulus E and Poisson's
 148 ratio ν [14], [30].

149 Masonry-like materials are then characterized by the stress function \mathbb{T}
 150 given by $\mathbb{T}(\mathbf{E}) = \mathbf{T}$, whose explicit expression is reported in [30], along with
 151 its properties. In particular, \mathbb{T} is differentiable in an open dense subset of
 152 the set of all strains [38] and the derivative $D_E \mathbb{T}(\mathbf{E})$ of $\mathbb{T}(\mathbf{E})$ with respect
 153 to \mathbf{E} is a positive semidefinite symmetric fourth-order tensor, whose explicit
 154 expression is reported in [30]. The equation of masonry-like materials has
 155 been then generalized in order to take into account a weak tensile strength
 156 $\sigma_t \geq 0$ [30].

157 The constitutive law of low tensile materials implemented in MARC [32]
 158 is based on the nonlinear concrete cracking formulation described in [9]. Ma-

159 masonry is modeled as a nonlinear isotropic material in which a crack can de-
160 velop orthogonal to the direction of the maximum principal stress, when it
161 exceeds the strength of the material σ_t . After the occurrence of the first
162 crack, a second crack may arise orthogonal to the first. In the same way, a
163 third crack could open perpendicularly to the first two. In this situation the
164 material loses all its load-carrying capacity across the crack, except when a
165 tension softening behavior is considered, which can have a linear trend with
166 slope equal to E_g .

167 The Rankine plasticity model implemented in DIANA [15] employs the
168 Rankine yield criterion to simulate tensile cracking in concrete and rock
169 under monotonic loading conditions. The yield function depends on both the
170 maximum principal stress and a yield value $\tilde{\sigma}_t$ that describes the nonlinear
171 exponential tensile softening behavior of the material, involving the tensile
172 strength σ_t and the fracture energy G_f^I [19].

173 Although the mechanical behavior of masonry constructions is clearly
174 nonlinear, modal analysis, which is based on the assumption that masonry
175 constituent materials feature a linear elastic behavior, is widely used in prac-
176 tical applications. Indeed, it provides important qualitative information on
177 the global dynamic behavior of masonry structures, thereby allowing to as-
178 sess their seismic vulnerability in compliance with the Italian and European
179 regulations. On the other hand, traditional modal analysis does not take into
180 account the influence that both the nonlinear behavior of the masonry mate-
181 rial and the presence of cracked regions can have on the natural frequencies

182 of masonry structures. While the effects of cracks on the vibration frequen-
183 cies are taken into account in different fields of mechanical and aerospace
184 engineering through the so-called linear perturbation analysis, such effects
185 are not fully explored yet as far as the civil engineering field is concerned.

186 In this paper the linear perturbation approach is coupled with modal
187 analysis, with the aim of assessing the dependence of the dynamic properties
188 of a masonry structure on the stress field and crack distribution induced by
189 the loads acting on the structure. Apart from the examples described in [23],
190 where a masonry beam, an arch on piers and the San Frediano bell tower in
191 Lucca have been analyzed, coupling linear perturbation and modal analysis is
192 far from being fully investigated, although it allows for calculating the natural
193 frequencies and mode shapes of a masonry body exhibiting a crack distribu-
194 tion due to the applied loads. In this regard, the procedure implemented in
195 the NOSA–ITACA code consists in calculating the numerical solution to the
196 nonlinear equilibrium problem of a masonry structure discretized into finite
197 elements, subjected to given boundary and loading conditions, and then con-
198 sidering the linear equation governing the undamped free vibrations of the
199 structure about the equilibrium state

$$M\ddot{u} + K_T u = 0. \tag{1}$$

200 In equation (1) u is the displacement vector, which belongs to \mathbb{R}^n and
201 depends on time t , \ddot{u} is the second-derivative of u with respect to t , and

202 K_T and $M \in \mathbb{R}^{n \times n}$ are the tangent stiffness and mass matrices of the finite-
 203 element assemblage. Note that K_T is symmetric and positive semidefinite,
 204 M is symmetric and positive definite. Equation (1) is similar to the equation
 205 of the motion of a linear elastic body, though here the elastic stiffness matrix,
 206 calculated using the elasticity tensor, is replaced by the tangent stiffness ma-
 207 trix K_T , calculated using the solution to the equilibrium problem and then
 208 takes into account the presence of cracks in body.

209

210 By assuming that

$$u = \phi \sin(\omega t), \quad (2)$$

211 with ϕ a vector of \mathbb{R}^n and ω a real scalar, equation (1) can be transformed
 212 into the constrained generalized eigenvalue problem

$$K_T \phi = \omega^2 M \phi, \quad (3)$$

213

$$T \phi = 0, \quad (4)$$

214 with $T \in \mathbb{R}^{m \times n}$ and $m \ll n$.

215

216 Condition (4) expresses the fixed constraints and the master-slave rela-
 217 tions assigned to displacement u , written in terms of vector ϕ . The restriction
 218 of the matrix K_T to the null subspace of \mathbb{R}^n defined by (4) is positive definite.

219 Therefore, given the structure under examination, discretized into finite
220 elements, and given the mechanical properties of the constituent materials
221 together with the kinematic constraints and loads acting on the structure,
222 the procedure implemented in NOSA-ITACA consists of the following steps.

223 Step 1. A preliminary modal analysis is conducted by assuming the struc-
224 ture's constituent material to be linear elastic, with stiffness matrix K . The
225 generalized eigenvalue problem (3)-(4) is then solved, with K in place of K_T ,
226 and the natural frequencies $f_{i,E} = \omega_{i,E}/2\pi$ and mode shapes ϕ_i^l calculated.

227 Step 2. The solution of the nonlinear equilibrium problem of the structure
228 is found and the derivative of the stress function needed to calculate the
229 tangent stiffness matrix K_T to be used in the next step is evaluated.

230 Step 3. The generalized eigenvalue problem (3)-(4) is finally solved and
231 the natural frequencies $f_i = \omega_i/2\pi$ of the structure in the presence of cracks
232 are estimated.

233 Similar procedures based on linear perturbation followed by modal analy-
234 sis are implemented in MARC and DIANA. The three codes NOSA-ITACA,
235 MARC and DIANA, which adopt different constitutive equations for ma-
236 sonry, have been used with the twofold aim of (1) studying the static behavior
237 of a masonry arch subjected to its own weight and a vertical concentrated
238 load and, after a linear perturbation, (2) assessing the dependence of the
239 natural frequencies and mode shapes on the crack distribution. The results
240 of this comparative study are reported in Section 3 and show that, in spite of

241 the different constitutive equations adopted, the dependence of the dynami-
242 cal properties of the arch on the loads is very similar for the three codes.

243 **3. Application to a masonry arch and software benchmarking**

244 The numerical method for modal analysis described in Section 2 is here
245 applied to the semi-circular masonry arch shown in Figure 1. The system is
246 fully clamped at the springings and its geometry features a mean radius of
247 0.77 m, a span of 1.50 m, a cross section of 0.16 m \times 1 m and a springing angle
248 of about 13°. The arch is subjected to a plane stress state due to its self-
249 weight and to a concentrated load P applied at the extrados at a quarter of
250 the span. The arch is discretized into 784 8-node isoparametric quadrilateral
251 elements with quadratic shape functions (corresponding to element 2, 26
252 and CQ16M of the NOSA-ITACA [8], MARC [32] and DIANA [15] libraries,
253 respectively), for a total of 2565 nodes. Figure 2 shows the mesh generated
254 by NOSA-ITACA, later converted in the MARC and DIANA format.

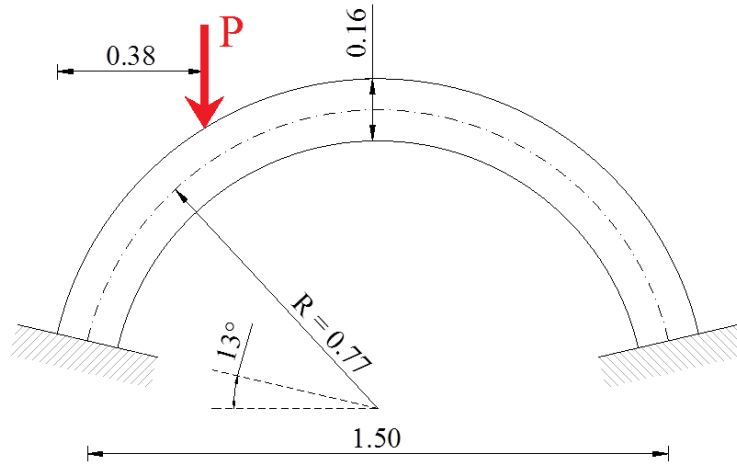


Figure 1: Geometry of the arch (length in meters).

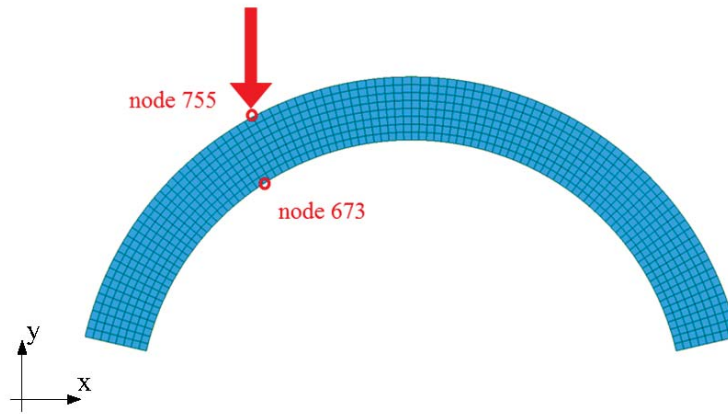


Figure 2: Mesh of the arch created by NOSA-ITACA code.

255 The numerical analyses conducted with NOSA-ITACA, MARC and DI-
 256 ANA have manifold goals. Firstly, they are aimed at analysing the static

257 behavior of the arch modeled by adopting three different constitutive equa-
258 tions. Secondly they allow comparing the natural frequencies of the arch in
259 the linear elastic case with those in the presence of the damage induced by
260 the increasing vertical load. Several parametric numerical experiments have
261 been carried out, as the tensile strength σ_t of the material varies, revealing
262 that, in the presence of cracks, the values of the frequencies calculated by
263 the three codes are comparable.

264 A preliminary modal analysis (step 1, Section 2) was performed by as-
265 suming the arch made of a linear elastic material with Young's modulus
266 $E = 3 \cdot 10^9$ Pa, Poisson's ratio $\nu = 0.2$ and mass density $\rho = 1930$ kg/m³.
267 The first four corresponding natural frequencies $f_{i,E}$ ($i = 1..4$) (calculated
268 by the three codes) are

269

$$270 \quad f_{1,E} = 92.33 \text{ Hz}; f_{2,E} = 163.64 \text{ Hz}; f_{3,E} = 266.95 \text{ Hz}; f_{4,E} = 297.95 \text{ Hz}.$$

271 Then, by following the procedure outlined in Section 2, step 2, damage
272 was induced in the arch by applying the self-weight along with an incremen-
273 tal vertical load. At each increment the frequencies $f_{i,j}$ (the i -th frequency
274 calculated by j -th code: N (NOSA-ITACA), M (MARC) and D(DIANA))
275 and the corresponding mode shapes were calculated.

276 In order to perform nonlinear static analysis in DIANA and MARC, the
277 parameters G_f^I and E_s (see Section 2) have to be assigned, in addition to the
278 tensile strength σ_t , set to vary from 0 Pa to $5 \cdot 10^4$ Pa. The Mode-I fracture

279 energy with $G_f^I = 25 \text{ Nm/m}^2$ was assumed in DIANA, while E_s was calcu-
280 lated, for each analysis performed in MARC, by imposing the equivalence
281 between the areas below the softening curves of both codes.

282 The value of the vertical load applied to the arch was increased through eight
283 increments from 0 kN to 4 kN. Each analysis was repeated by decreasing the
284 value of σ_t from $5 \cdot 10^4 \text{ Pa}$ to $5 \cdot 10^3 \text{ Pa}$. For values of σ_t lower than $5 \cdot 10^3 \text{ Pa}$,
285 only NOSA-ITACA and DIANA reach the convergence for any value of the
286 vertical load.

287 It is pointed out that in terms of displacement, stress and cracking fields,
288 the results provided by the three codes show very good agreement for each
289 value of the vertical load up to a tensile stress of $5 \cdot 10^3 \text{ Pa}$. Figures 3, 4,
290 5, 6 and 7 display for the three codes the plots relevant to the norm of dis-
291 placements, the components of the Cauchy stress tensor and the maximum
292 eigenvalue of the fracture strain, calculated for $\sigma_t = 5 \cdot 10^3 \text{ Pa}$ and $P = 4 \text{ kN}$.
293 Despite the different constitutive equations adopted, NOSA-ITACA and DI-
294 ANA provide the same results, whereas the values obtained in MARC exhibit
295 an increment of about 5 – 10% with respect to the afore-mentioned codes.

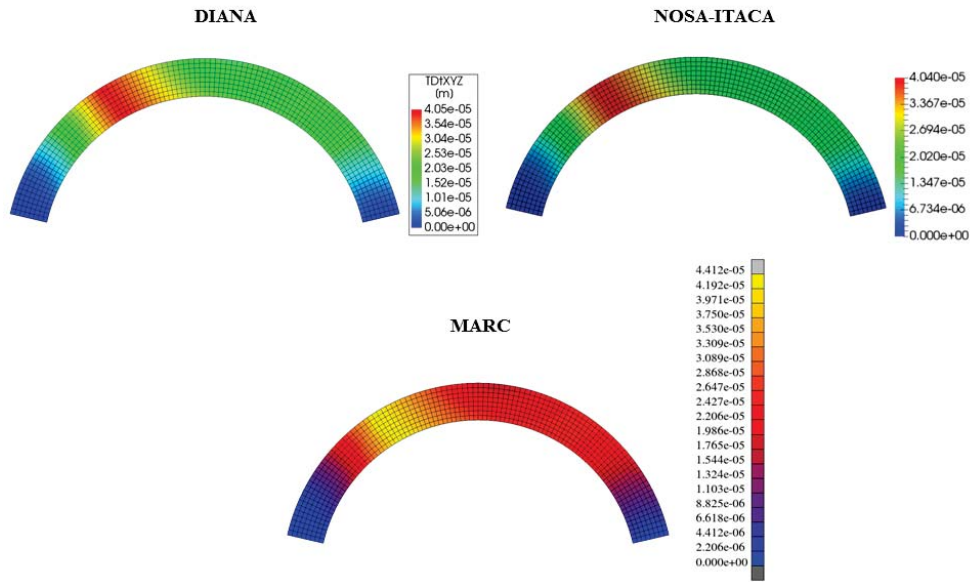


Figure 3: Norm of displacement [m] ($P = 4 \text{ kN}$, $\sigma_t = 5 \cdot 10^3 \text{ Pa}$).

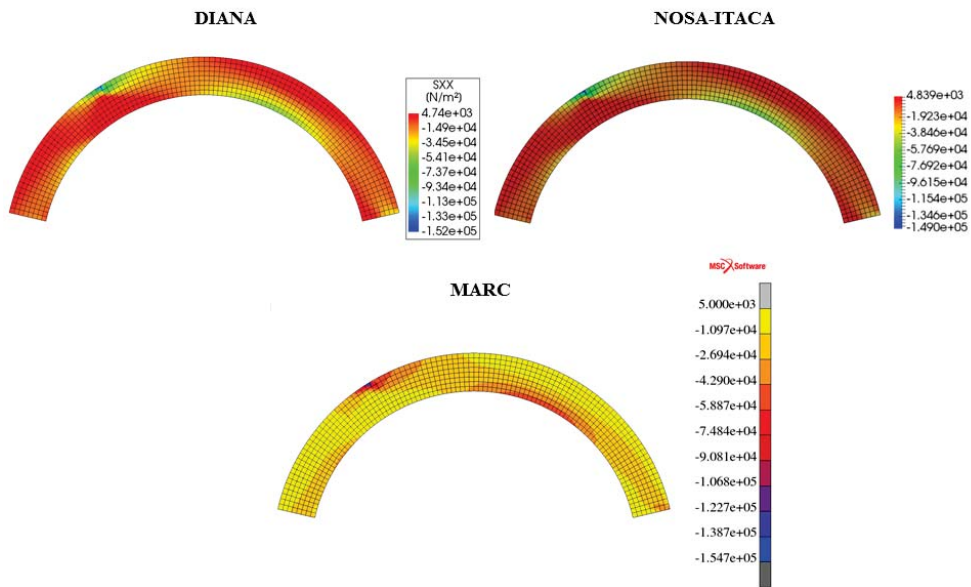


Figure 4: Cauchy stress component σ_x [Pa] ($P = 4 \text{ kN}$, $\sigma_t = 5 \cdot 10^3 \text{ Pa}$).

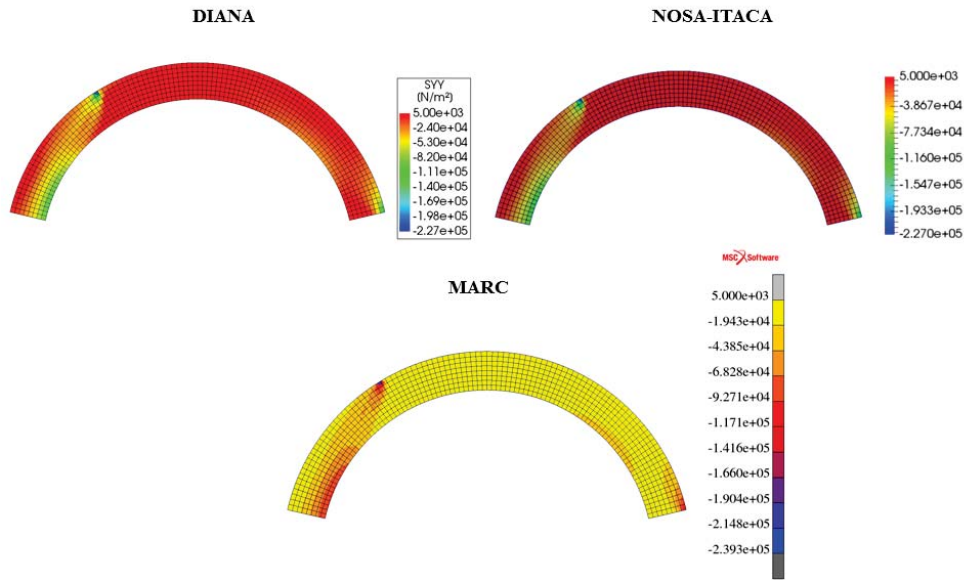


Figure 5: Cauchy stress component σ_y [Pa] ($P = 4 \text{ kN}$, $\sigma_t = 5 \cdot 10^3 \text{ Pa}$).

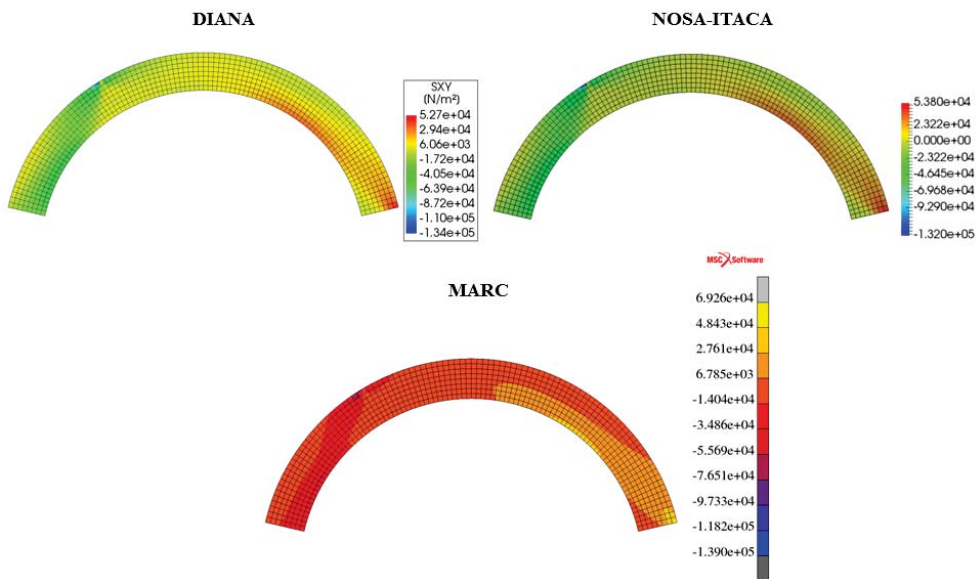


Figure 6: Cauchy stress component τ_{xy} [Pa] ($P = 4 \text{ kN}$, $\sigma_t = 5 \cdot 10^3 \text{ Pa}$).

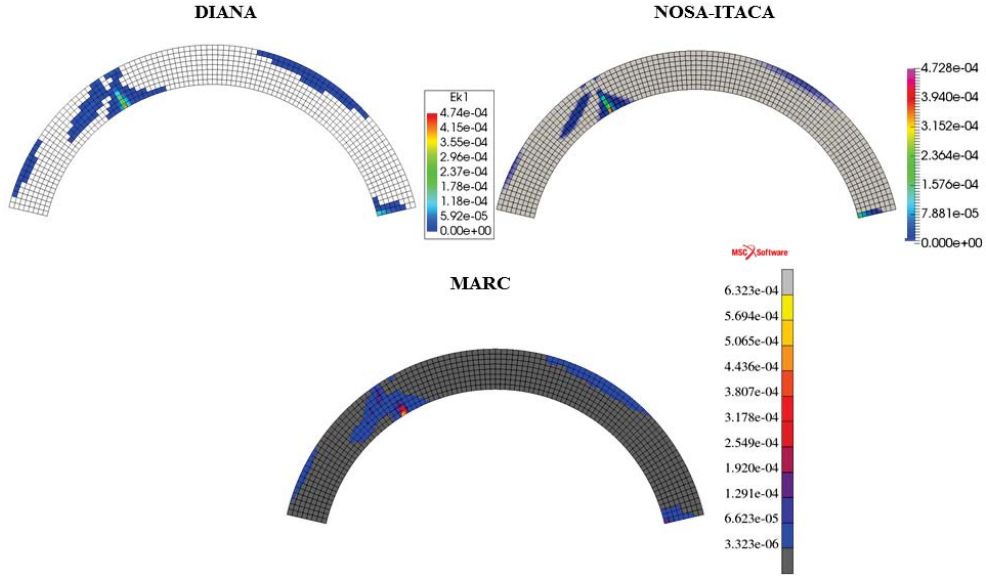


Figure 7: Maximum eigenvalue of the fracture strain tensor ($P = 4 \text{ kN}$, $\sigma_t = 5 \cdot 10^3 \text{ Pa}$).

296 Figures 8, 9, 10, 11 show the variation of the first four frequencies $f_{i,j}$
 297 of the arch, calculated in the three codes via linear perturbation analysis,
 298 versus decreasing values of tensile strength σ_t for $P = 3 \text{ kN}$ (continuous line)
 299 and $P = 4 \text{ kN}$ (dashed line). The corresponding mode shapes for the linear
 300 elastic case are also shown. Tables 1, 2, and 3, 4 report, for the same load
 301 conditions P , the values of σ_t used in the different analyses along with the
 302 corresponding relative frequency errors $\delta_{i,j}$ defined by

$$\delta_{i,j} = \frac{(f_{i,E} - f_{i,j})}{f_{i,E}}, \quad \text{for } i = 1 \dots 4 \quad \text{and } j = \text{N, M, D} \quad (5)$$

303 where $f_{i,E}$ is the i -th frequency calculated by standard modal analysis and
 304 $f_{i,j}$ the i -th frequency calculated by j -th code via linear perturbation analysis,

305 (N stands for NOSA-ITACA, M for MARC and D for DIANA).

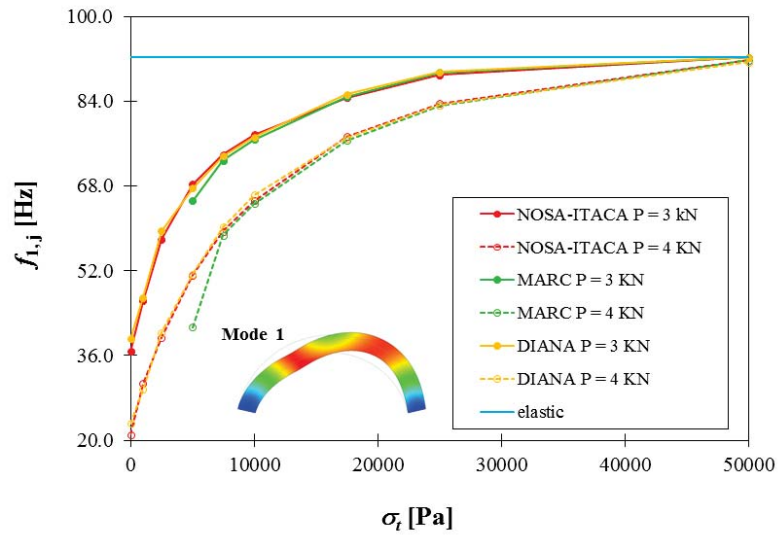


Figure 8: First frequency $f_{1,j}$ versus tensile strength σ_t for $P = 3$ kN (continuous line) and $P = 4$ kN (dashed line).

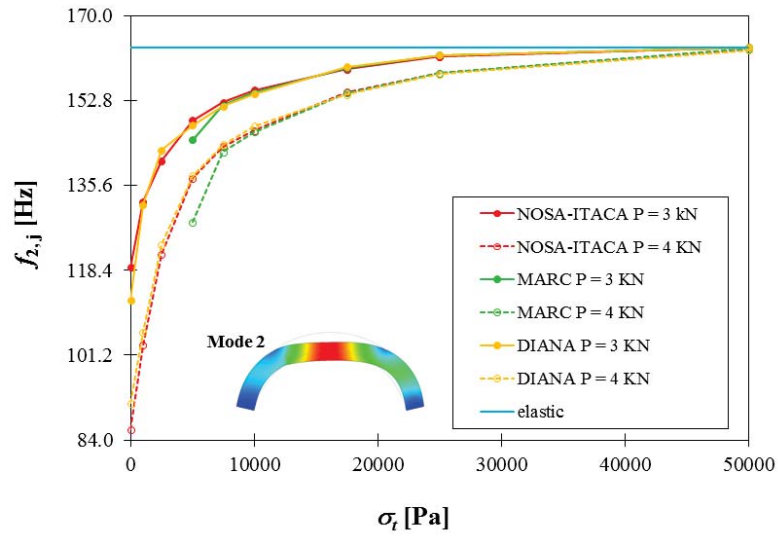


Figure 9: Second frequency $f_{2,j}$ versus tensile strength σ_t for P = 3 kN (continuous line) and P = 4 kN (dashed line).

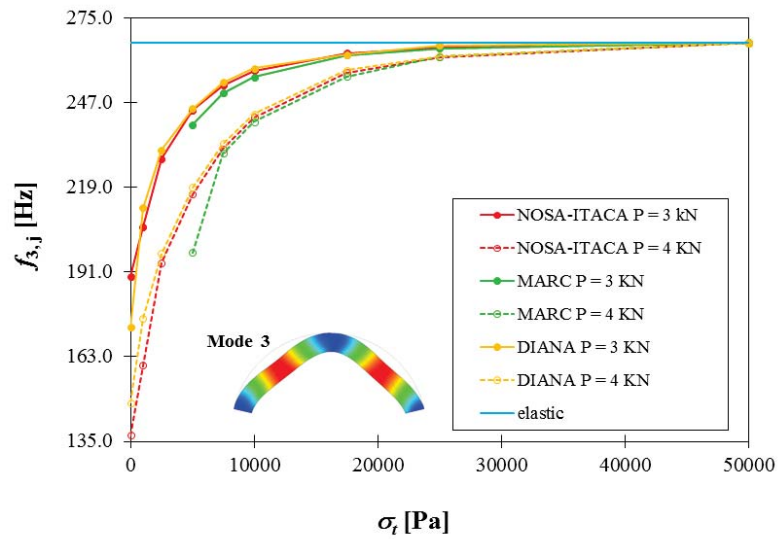


Figure 10: Third frequency $f_{3,j}$ versus tensile strength σ_t for P = 3 kN (continuous line) and P = 4 kN (dashed line).

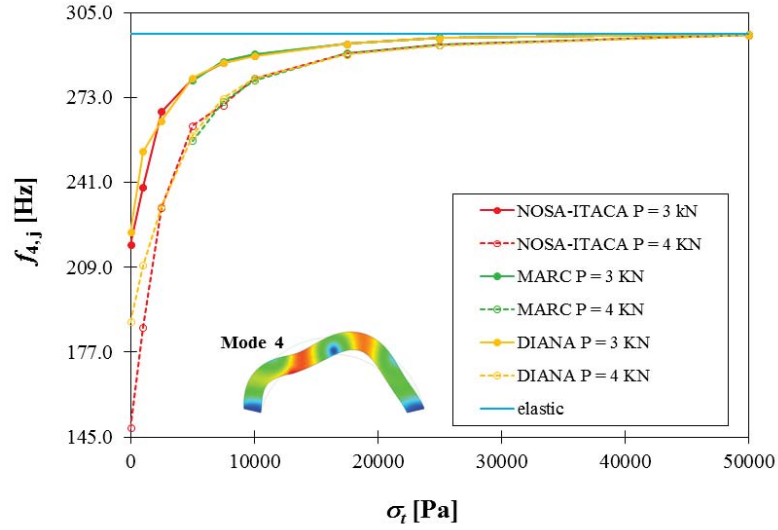


Figure 11: Fourth $f_{4,j}$ versus tensile strength σ_t for $P = 3$ kN (continuous line) and $P = 4$ kN (dashed line).

σ_t [Pa]	$\delta_{1,N}$ [%]	$\delta_{1,M}$ [%]	$\delta_{1,D}$ [%]	$\delta_{2,N}$ [%]	$\delta_{2,M}$ [%]	$\delta_{2,D}$ [%]
0	60.20	–	57.61	27.28	–	31.28
1000	49.80	–	49.13	19.09	–	19.47
2500	37.21	–	35.52	14.03	–	12.74
5000	25.93	29.35	26.68	9.06	11.45	9.63
7500	19.81	21.07	20.19	6.79	7.15	7.26
10000	15.80	16.77	16.26	5.32	5.60	5.75
17500	8.20	8.06	7.57	2.67	2.51	2.38
25000	3.56	3.06	2.89	1.14	0.95	0.95
50000	0.00	0.00	0.00	0.00	0.00	0.00

Table 1: $\delta_{i,j}$, $i = 1, 2$; $j = N, M, D$; $P = 3$ kN.

σ_t [Pa]	$\delta_{3,N}$ [%]	$\delta_{3,M}$ [%]	$\delta_{3,D}$ [%]	$\delta_{4,N}$ [%]	$\delta_{4,M}$ [%]	$\delta_{4,D}$ [%]
0	28.95	–	35.24	26.71	–	25.08
1000	22.86	–	20.45	19.43	–	14.92
2500	14.42	–	13.31	9.81	–	10.99
5000	8.36	10.21	8.17	5.66	5.88	5.56
7500	5.29	6.24	4.92	3.63	3.47	3.65
10000	3.52	4.30	3.19	2.69	2.54	2.77
17500	1.35	1.57	1.47	1.21	1.19	1.21
25000	0.60	0.70	0.39	0.50	0.41	0.45
50000	0.00	0.00	0.00	0.00	0.00	0.00

Table 2: $\delta_{i,j}$, $i = 3,4$; $j = N, M, D$; $P = 3$ kN.

σ_t [Pa]	$\delta_{1,N}$ [%]	$\delta_{1,M}$ [%]	$\delta_{1,D}$ [%]	$\delta_{2,N}$ [%]	$\delta_{2,M}$ [%]	$\delta_{2,D}$ [%]
0	77.20	–	74.92	47.38	–	44.10
1000	66.79	–	67.90	36.94	–	35.28
2500	57.29	–	56.32	25.63	–	24.42
5000	44.50	55.15	44.38	16.19	21.67	15.91
7500	35.57	36.42	34.72	12.32	12.95	12.03
10000	29.27	29.94	28.12	10.32	10.50	9.76
17500	16.15	17.01	16.45	5.53	5.62	5.81
25000	9.42	9.80	9.66	3.19	3.20	3.28
50000	0.56	0.51	0.95	0.19	0.17	0.34

Table 3: $\delta_{i,j}$, $i = 1,2$; $j = N, M, D$; $P = 4$ kN.

σ_t [Pa]	$\delta_{3,N}$ [%]	$\delta_{3,M}$ [%]	$\delta_{3,D}$ [%]	$\delta_{4,N}$ [%]	$\delta_{4,M}$ [%]	$\delta_{4,D}$ [%]
0	48.70	–	44.65	50.06	–	36.55
1000	40.01	–	34.17	37.21	–	29.39
2500	27.26	–	26.15	22.03	–	21.90
5000	18.79	26.05	17.98	11.59	13.52	12.88
7500	13.17	13.71	12.54	9.02	8.58	8.16
10000	9.26	9.82	8.84	5.62	5.83	5.60
17500	3.72	4.24	3.45	2.46	2.40	2.55
25000	1.79	1.76	1.70	1.35	1.34	1.43
50000	0.08	0.08	0.04	0.08	0.07	0.13

Table 4: $\delta_{i,j}$, $i = 3,4$; $j = N, M, D$; $P = 4$ kN.

306 As expected, the figures highlight that the frequencies of the arch decrease
307 as the vertical load increases and the tensile strength decreases. As outlined
308 in Tables 1, 2, 3 and 4, regardless of the value of the vertical load, the
309 fundamental frequency falls faster than the other frequencies; approximately
310 27% against 9%, when $P = 3$ kN and $\sigma_t = 5 \cdot 10^3$ Pa, and 50% against 20%,
311 when $P = 4$ kN and $\sigma_t = 5 \cdot 10^3$ Pa. This is due to the chosen vertical load
312 position, which induces a deformation in the arch similar to the first mode
313 shape (Figure 12, 13).

314 Figure 12 shows the mode shapes corresponding to the first four frequencies
315 of the arch for $\sigma_t = 5 \cdot 10^3$ Pa and $P = 3$ kN. Figure 13 shows the same
316 four mode shapes but for $\sigma_t = 5 \cdot 10^3$ Pa and $P = 4$ kN. The figures report
317 the degree of consistency, expressed in terms of MAC, viz. Modal Assurance
318 Criterion [31], calculated between the i -th mode shape of the damaged arch
319 and the corresponding mode shape calculated via standard modal analysis.
320 It is noticed that frequencies are much more sensitive than mode shapes to

321 damage; for example when $\sigma_t = 5 \cdot 10^3$ Pa and $P = 3$ kN, the first frequency
 322 shows a relative variation of about 25% while the MAC value is equal to
 323 0.99, whereas when $\sigma_t = 5 \cdot 10^3$ Pa and $P = 4$ kN, the first frequency has
 324 a relative downshift of about 50% (which indeed corresponds to a severe
 325 damage condition), but the MAC still continues to be rather high, showing
 326 values not lower than 0.90.

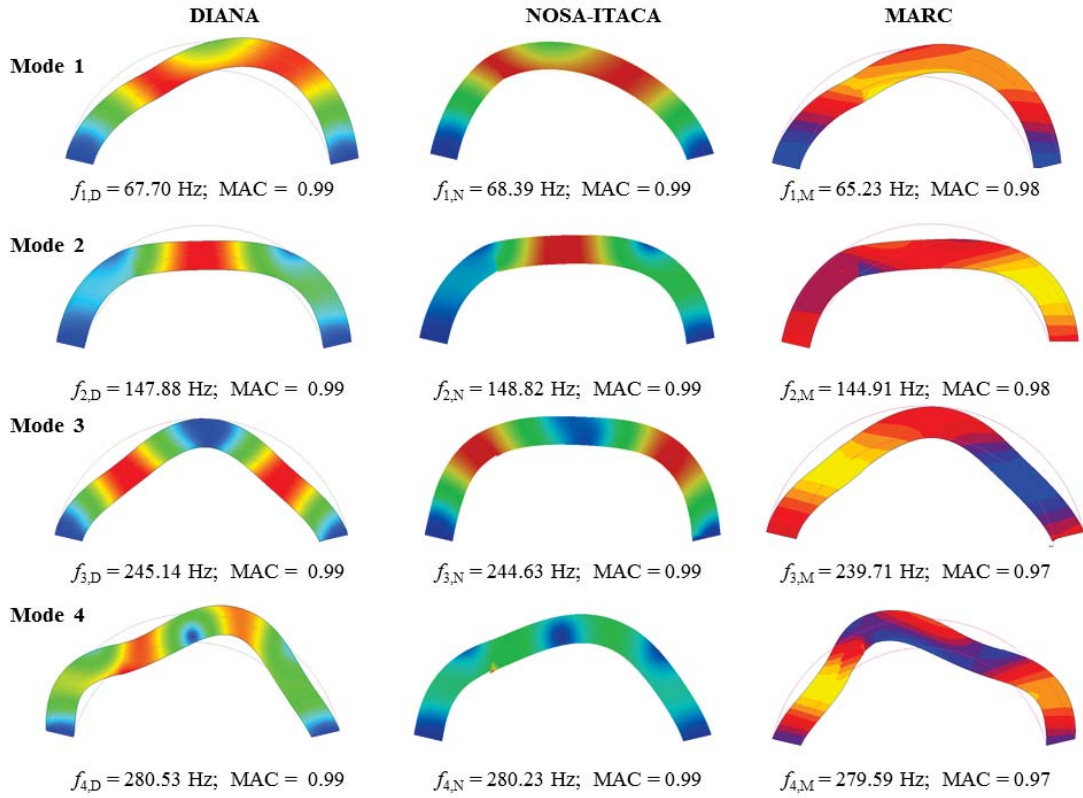


Figure 12: First four mode shapes of the damaged arch ($P = 3$ kN, $\sigma_t = 5 \cdot 10^3$ Pa).

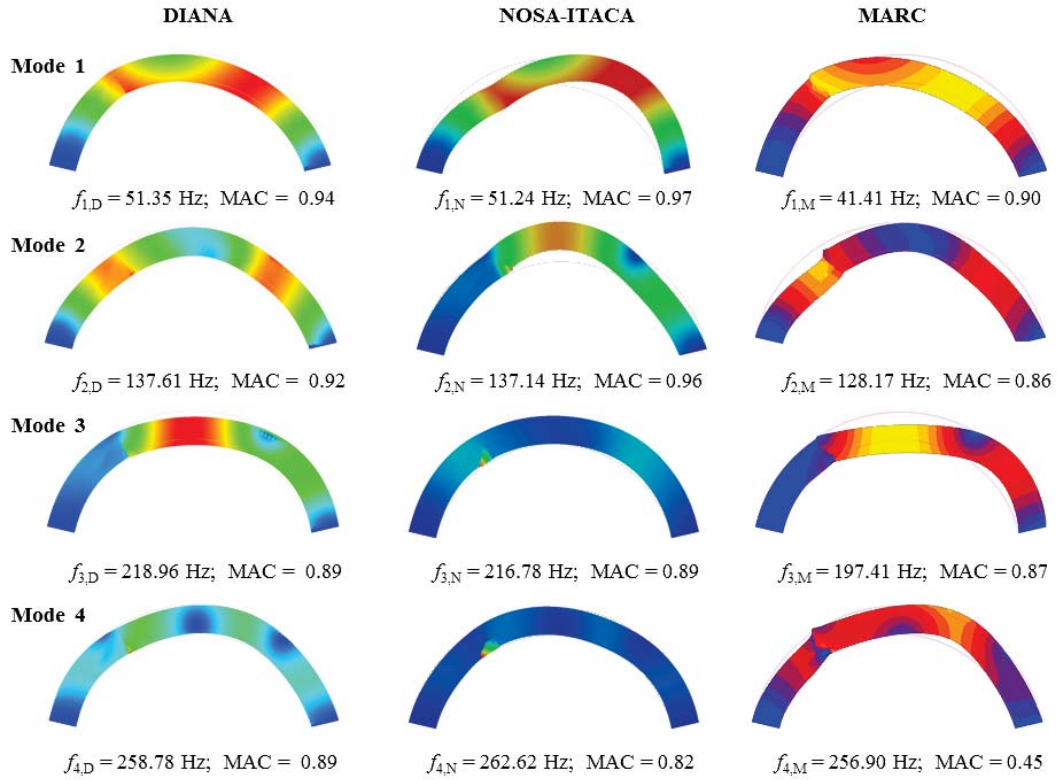


Figure 13: First four mode shapes of the damaged arch ($P = 4 \text{ kN}$, $\sigma_t = 5 \cdot 10^3 \text{ Pa}$).

327 In order to validate the frequencies values calculated by the three FE
 328 codes, the load-displacement curves corresponding to $\sigma_t = 5 \cdot 10^3 \text{ Pa}$ were
 329 plotted (Figure 14) for nodes 755 and 673, positioned respectively at the
 330 application point of vertical load and the corresponding point at the intrados
 331 of the arch (Figure 2).

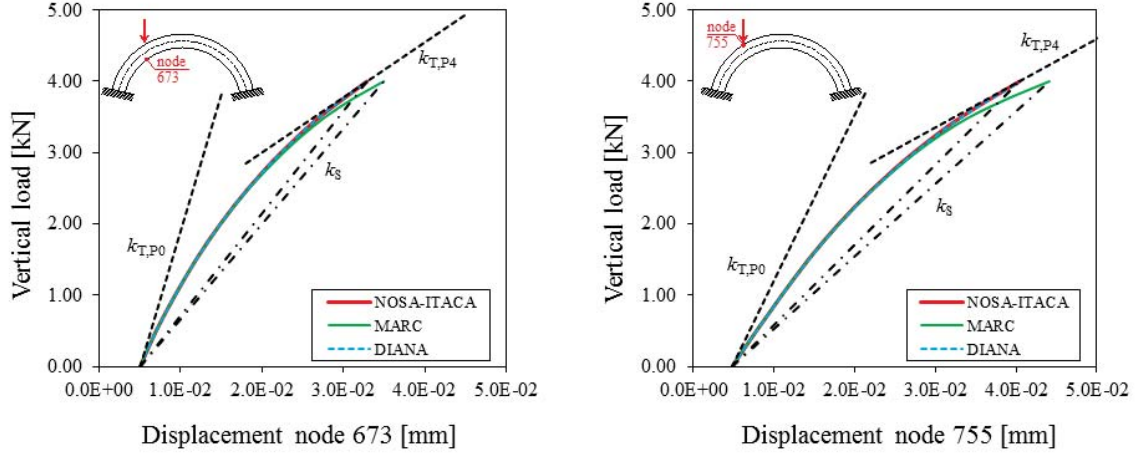


Figure 14: Vertical load versus displacement magnitude of node 673 (on the left) and node 755 (on the right), $\sigma_t = 5 \cdot 10^3$ Pa.

332 For each curve, its fourth-degree interpolating polynomial is determined
 333 and then the slopes $k_{T,P0}$ and $k_{T,P4}$ of the tangents at the origin and at P =
 334 4 kN, (dashed lines in Figure 14) are calculated. The slope k_S of the secant
 335 passing for those points (dashed-dot lines in Figure 14) is also calculated.
 336 Since the loss of frequency is expected to be related to the square root of the
 337 loss of stiffness (mass being equal), the following quantities were calculated as
 338 for the first frequency, i.e. the one suffering a major decrease due to damage

$$\tilde{f}_{1,T} = f_{1,E} \cdot \sqrt{\frac{k_{T,P4}}{k_{T,P0}}}, \quad (6)$$

$$\tilde{f}_{1,S} = f_{1,E} \cdot \sqrt{\frac{k_S}{k_{T,P0}}}, \quad (7)$$

339 The results obtained are summarized in Tables 5 and 6 for all the three
 340 codes. It is worth noting that the first frequency $\tilde{f}_{1,T}$ calculated by using the
 341 tangent stiffness is a good approximation of the frequency $f_{1,j}$ computed via
 342 linear perturbation analysis, whereas the choice of the secant stiffness matrix
 343 would lead to an overestimation of the frequency of the damaged structure.

Code	P [kN]	k_T [kN/m]	k_S [kN/m]	$\tilde{f}_{1,T}$ [Hz]	$\tilde{f}_{1,S}$ [Hz]	$f_{1,j}$ [Hz]
N	0	254.48	143.52	50.87	69.34	51.24
	4	77.26				
M	0	260.23	133.68	41.76	66.18	41.41
	4	53.23				
D	0	254.48	143.55	50.88	69.34	51.35
	4	77.28				

Table 5: Comparison of the first frequency of arch using the tangent stiffness k_T and the secant stiffness k_S evaluated in node 673 with the numerical frequency obtained via linear perturbation analysis.

Code	P [kN]	k_T [kN/m]	k_S [kN/m]	$\tilde{f}_{1,T}$ [Hz]	$\tilde{f}_{1,S}$ [Hz]	$f_{1,j}$ [Hz]
N	0	180.68	112.31	54.16	72.79	51.24
	4	62.16				
M	0	173.20	133.68	46.54	70.75	41.41
	4	53.23				
D	0	180.68	114.69	54.78	73.56	51.35
	4	63.61				

Table 6: Comparison of the first frequency of arch using the tangent stiffness k_T and the secant stiffness k_S evaluated in node 755 with the numerical frequency obtained via linear perturbation analysis.

344 4. Application to a real case study: the Mogadouro clock tower

345 4.1. Description of the case study

346 The Mogadouro clock tower (Figure 15) is a historic masonry structure
347 located inside the castle perimeter of the homonymous town in the Northeast
348 of Portugal and likely built after 1559 to serve the neighbouring church as
349 a bell tower. The fabric features a rectangular cross section of $4.7 \times 4.7 \text{ m}^2$,
350 with masonry walls of about 1 m thickness, and a height of 20.4 m. The
351 central part of the walls is built of rubble stones with thick mortar joints,
352 whereas the corners are made of large granite units with dry joints. Eight
353 masonry columns support the roof body, forming two rectangular openings
354 of about $0.9 \times 2.0 \text{ m}^2$ per façade.



Figure 15: Clock tower and castle of Mogadouro.

355 Due to the lack of maintenance, the tower did appear in very poor condi-
356 tions. Beyond material degradation and biological growth, out-of-plane dis-
357 placements and cracks could be clearly observed. The most damaged parts
358 were the East and West façades, where two deep passing cracks were about
359 to separate the box cross section of the tower into two U halves (Figures 16,
360 17). As the structural safety was jeopardized, rehabilitation works aimed at
361 reinstating the sound condition of the structure were carried out in 2005.
362 The intervention included: lime grout injections for sealing and walls consol-
363 idation, substitution of deteriorated material, and installation of pre-stressed
364 tie-rods to restrain cracks from possible reopening.

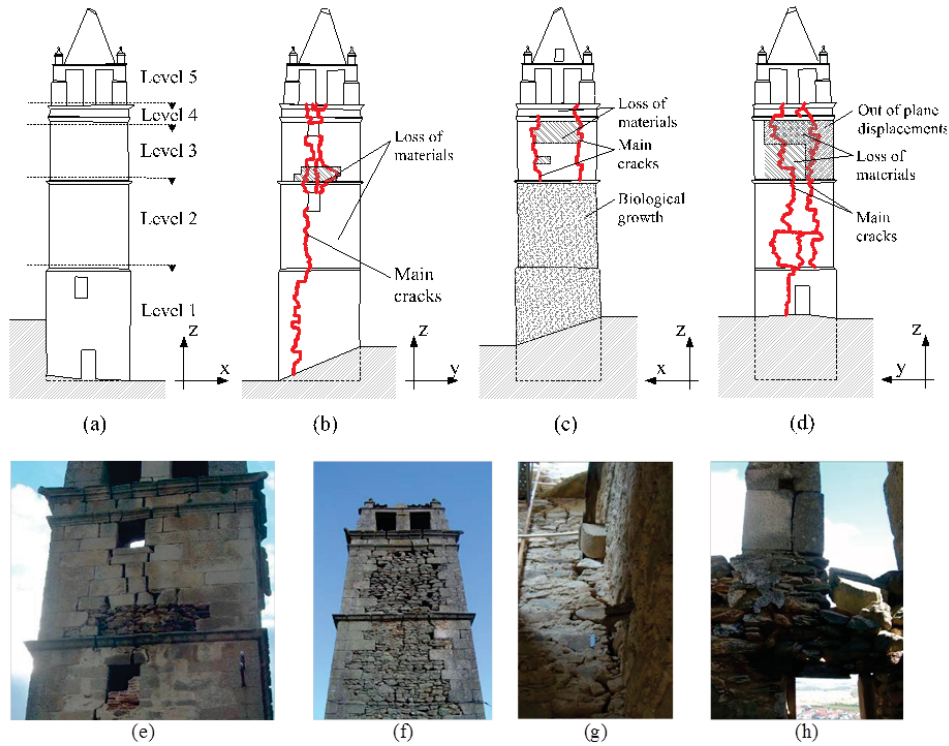


Figure 16: Damage in the tower: (a) South, (b) East, (c) North and (d) West façades; cracks on the (e) East and (f) West fronts; (g) inner crack in the West façade; and (h) example of material loss [44].

365 *4.2. Dynamic identification of the tower before and after rehabilitation*

366 To evaluate the structural response pre- and post-rehabilitation, two cam-
 367 paigns of Ambient Vibrations Tests (AVTs) were carried out making use of
 368 ambient excitation sources, such as wind and traffic [44]. The response of
 369 the tower was measured in 54 selected points distributed along three lev-
 370 els, according to the layout displayed in Figure 17. The dynamic equipment
 371 consisted of 4 uniaxial piezoelectric accelerometers with a bandwidth rang-
 372 ing from 0.15 to 1000 Hz (5%), a dynamic range of $\pm 0.5g$, a sensitivity of

373 10 V/g, $8\mu\text{g}$ of resolution and 0.21 kg of weight, connected by coaxial cables
374 to a front-end data acquisition system with a 24-bit ADC, provided with
375 anti-aliasing filters. The front-end was connected to a laptop by an Ethernet
376 cable. The accelerometers were bolted to aluminium plates, which were in
377 turn glued to the stones through an epoxy layer. As the acquisition system
378 was composed only by 4 channels, 27 test setups were necessary to record
379 the accelerations in all selected measurement points. A preliminary FE dy-
380 namic analysis assisted in the selection of the acquisition parameters. Thus,
381 to ensure an acquisition time window 2000 times larger than the estimated
382 fundamental period of the structure, the output signals were recorded with
383 a sampling frequency of 256 Hz for a duration of about 11 minutes. Same
384 test planning and measurement points were adopted before and after the
385 reinstatement works.

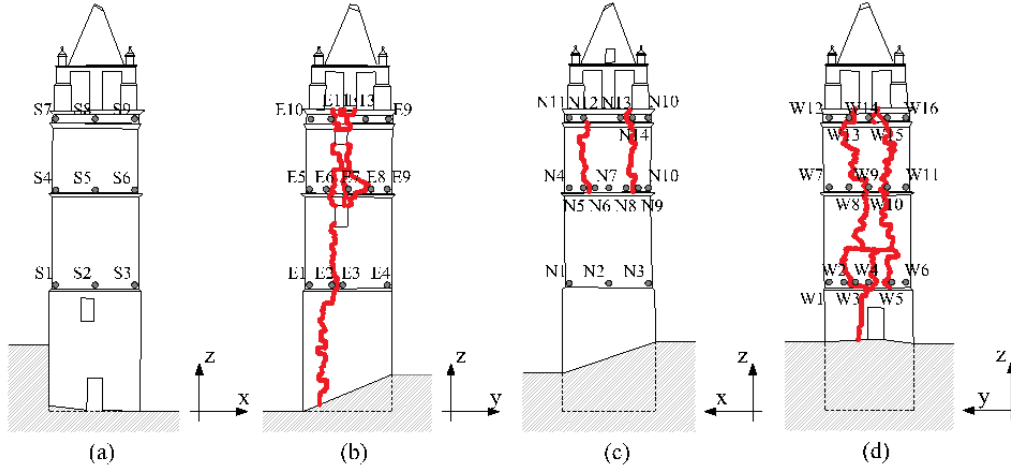


Figure 17: Sensor layout for AVTs: (a) South, (b) East, (c) North and (d) West façades [44].

386 For each structural condition (before and after rehabilitation), the modal
 387 parameters were estimated by comparing the results from two established and
 388 complementary OMA techniques: the Enhanced Frequency Domain Decom-
 389 position (EFDD) method and the Stochastic Subspace Identification (SSI)
 390 method, both implemented in ARTeMIS software [3]. In total, seven modes
 391 of vibration were identified in the frequency ranges 2-9 Hz and 2-17 Hz for
 392 the damaged and undamaged conditions, respectively. Tables 7 and 8 sum-
 393 marize the obtained results in terms of natural frequencies f , damping ratios
 394 ξ , Coefficient of Variation CV and percentage differences Δ before and after
 395 rehabilitation. Mode shapes and MAC values are illustrated in Figure 18.

396 For the sake of brevity, only the modal features identified by the SSI are
 397 shown.

Mode	Before		After		Δ_f [%]
	f [Hz]	CV_f [%]	f [Hz]	CV_f [%]	
1	2.15	1.85	2.56	0.21	+19.28
2	2.58	1.05	2.76	0.30	+6.70
3	4.98	0.69	7.15	0.27	+43.67
4	5.74	1.56	8.86	0.47	+54.37
5	6.76	1.13	9.21	0.21	+36.13
6	7.69	2.94	15.21	2.24	+97.87
7	8.98	1.21	16.91	1.40	+88.27
Avg	–	1.49	–	0.73	+49.47

Table 7: Dynamic response of Mogadouro tower before and after rehabilitation: frequencies [44].

Mode	Before		After		Δ_ξ [%]
	ξ [%]	CV_ξ [%]	ξ [%]	CV_ξ [%]	
1	2.68	219.51	1.25	0.13	-53.26
2	1.71	94.02	1.35	0.17	-21.00
3	2.05	65.33	1.20	0.14	-41.32
4	2.40	24.27	1.31	0.13	-45.72
5	2.14	31.74	1.16	0.12	-45.65
6	2.33	55.98	2.54	0.24	+9.11
7	2.30	46.39	1.49	0.23	-35.07
Avg	2.23	76.75	1.47	0.17	-40.34

Table 8: Dynamic response of Mogadouro tower before and after rehabilitation: damping [44].

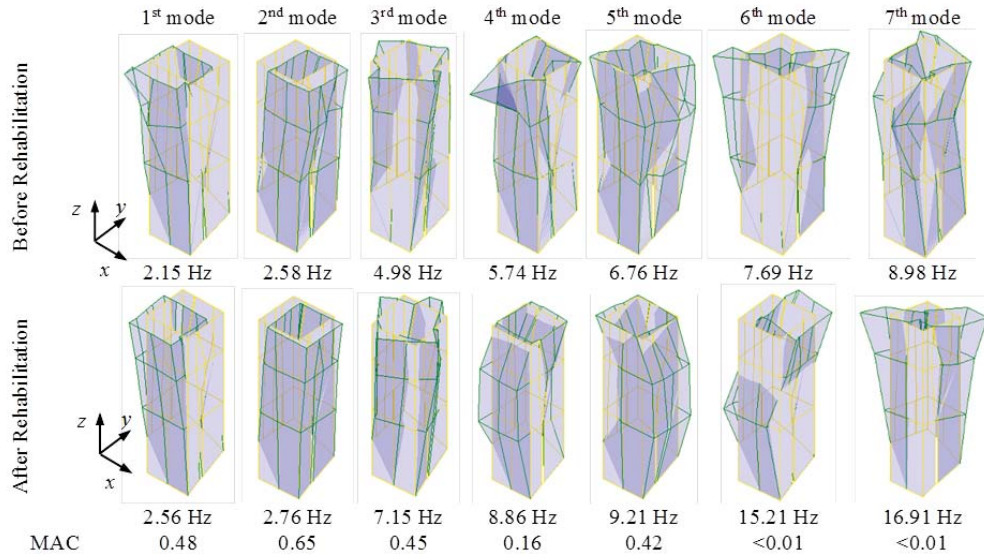


Figure 18: Experimental mode shapes and MAC values before and after rehabilitation works [44].

398 The comparison between the global parameters estimated before and after
 399 the consolidation works revealed a significant increase of frequency values,
 400 reading an average upshift of 50%, and a damping decrease of around 40%.
 401 Such results consistently reflected the actual structural conditions of the
 402 tower, i.e. a lower-stiffness system with ongoing non-linear phenomena effects
 403 before rehabilitation and a higher-stiffness system with reduced non-linear
 404 phenomena effects after rehabilitation. In what concerns the experimental
 405 mode shapes, similar configurations were observed pre- and post-intervention
 406 for the first five modes of vibration, identifying four dominant bending modes
 407 in the two main planes of the tower (modes 1, 2, 4 and 5) and one torsional

408 mode (mode 3), whereas higher-frequency mode shapes (modes 6 and 7)
409 switched order after the works. Although comparable in configuration, the
410 presence of local damage mechanisms before the structural intervention did
411 likely induce local protuberances in the experimental mode shapes of the
412 damaged tower, especially in the upper part of the structure and in the areas
413 close to the cracks. Hence the poor degree of correlation characterizing the
414 mode shape vectors before and after ($MAC < 0.65$). On the contrary, the
415 structure featured a monolithic behaviour after the rehabilitation works.

416 *4.3. Modal analysis with linear perturbation*

417 In this subsection the linear perturbation analysis is applied to the Mo-
418 gadouro clock tower. The analysis is performed by using only NOSA-ITACA
419 code for two reasons: (1) in DIANA, the Rankine plasticity model describing
420 the tensile regime of the material is implemented only for plane stress, plane
421 strain and axisymmetric elements, but not for brick elements, which are the
422 ones employed in modeling the tower; (2) the MARC code turned out to be
423 unable to reach the convergence for $\sigma_t = 0$ Pa, a value that is crucial for a
424 realistic modeling of eastern and western façades, where two passing cracks
425 were present before rehabilitation.

426 In [44] a FE model updating (based on standard modal analysis) is per-
427 formed to tune the Young's modulus of different parts of the structure, in
428 order to minimize the differences between numerical and experimental modal
429 parameters (frequencies and mode shapes) of the tower after rehabilitation;

430 subsequently, the Young's moduli obtained are reduced with the aim of fitting
431 the experimental frequencies and mode shapes of the tower before rehabilita-
432 tion. Here, a different approach is followed, based on model updating aimed
433 at matching both fracture distribution and frequencies of the tower. With
434 the purpose of reproducing numerically the actual crack pattern of the tower
435 before rehabilitation and matching its experimental frequencies as well, **the**
436 **scheme nonlinear static analysis–linear perturbation–modal analy-**
437 **sis has been applied in an iterative way.** In particular, once the solution
438 to the equilibrium problem of the structure subjected to its own weight is
439 calculated along with the corresponding fracture distribution, linear pertur-
440 bation analysis and modal analysis are conducted to estimate frequencies and
441 mode shapes of the tower in the presence of cracks. The materials Young's
442 moduli and tensile strengths are tuned and their optimal values calculated
443 **in such a way as to match the crack distribution and minimize the**
444 **discrepancy between experimental and numerical frequencies.** The
445 same procedure was then repeated to tune the tensile strength of the repaired
446 walls, keeping the Young's moduli fixed and trying to match the experimen-
447 tal natural frequencies and mode shapes of the tower after rehabilitation.
448 The FE mesh of the tower, shown in Figure 19, consists of 18024 isopara-
449 metric 8–node brick elements, 352 thick shell elements, used to discretize
450 the roof, and 23467 nodes; the model includes also two meters of foundation
451 [44], with the same thickness as the façades. The tower is assumed to be
452 clamped at the base and constituted by the materials whose (optimal) me-

453 chanical properties, calculated via model updating, are indicated in Table 9.
 454 The foundation is modeled by a linear elastic material, which is indeed an
 455 acceptable assumption considering the high material compaction at the base
 456 of the tower and the soil confinement. Regarding pillars and roof, the use of
 457 a linear elastic material is suggested by the observation that these elements
 458 do not affect the overall structural behavior of the tower. Indeed, the low
 459 elastic modulus adopted for the roof does allow the tower cross section to
 460 freely deform within its own plane.

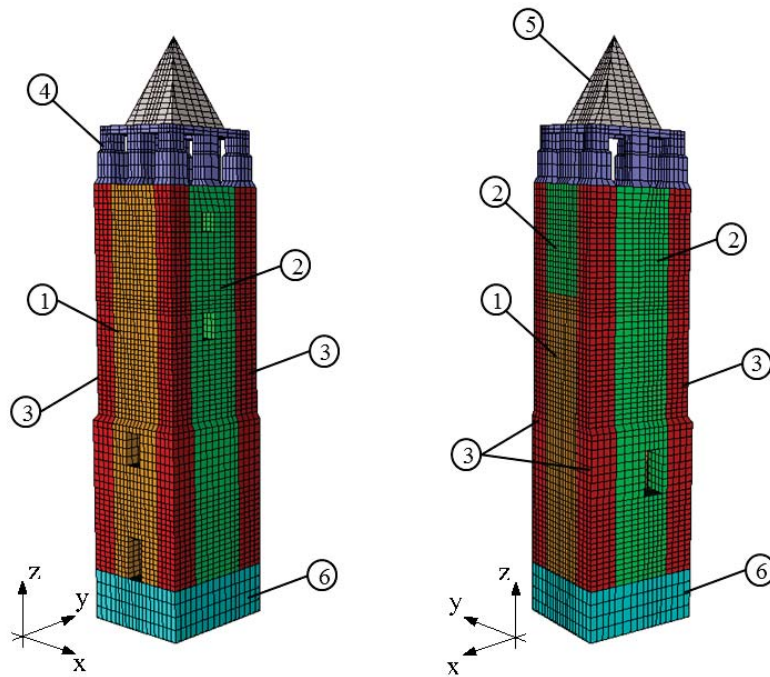


Figure 19: Mogadouro tower: mesh and distribution of material properties (before rehabilitation).

Mat. n°	$\rho[kg/m^3]$	$E[GPa]$	$\sigma_t[kPa]$
1 (orange)	2200	2.500	15.0
2 (green)	2200	2.500	0.0
3 (red)	2400	3.500	15.0
4 (indigo)	2200	1.210	–
5 (grey)	2000	0.195	–
6 (cyan)	2200	3.500	–

Table 9: Optimal values of mechanical properties of the materials before rehabilitation.

461 Numerical solution to the equilibrium problem for the optimal values of
462 the Young's moduli and tensile strengths in Table 9 yields the results reported
463 in Figures 20, 21 and 22 that show, for each façade, the actual (on the left)
464 and numerical (on the right) crack patterns before rehabilitation. The south
465 wall is not reported because it shows no cracks (neither in the numerical
466 model nor in the reality). A very good agreement can be observed between
467 real and numerical fracture strains.

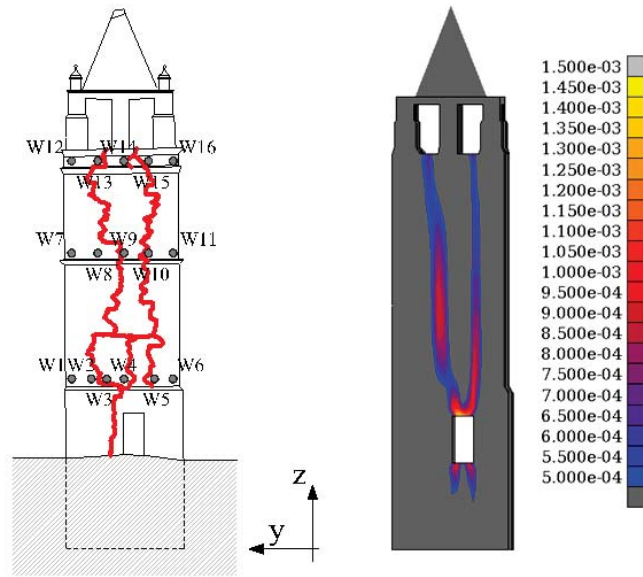


Figure 20: Mogadouro tower west façade: surveyed (on the left) and numerical (on the right) cracking pattern.

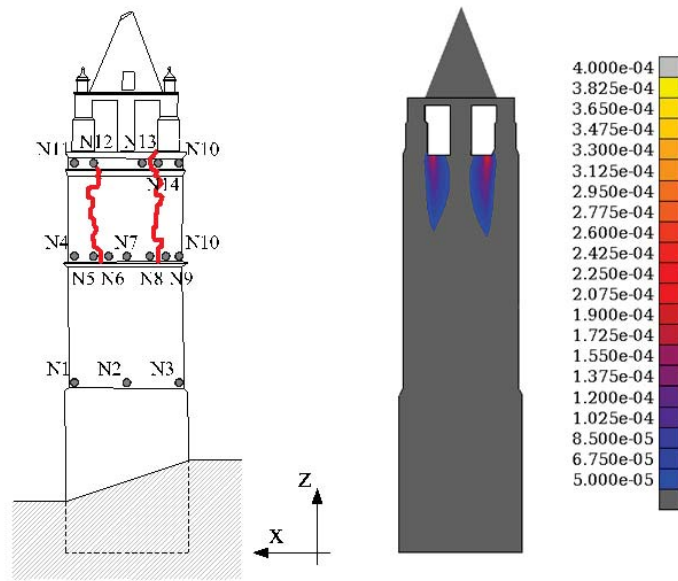


Figure 21: Mogadouro tower north façade: surveyed (on the left) and numerical (on the right) cracking pattern.

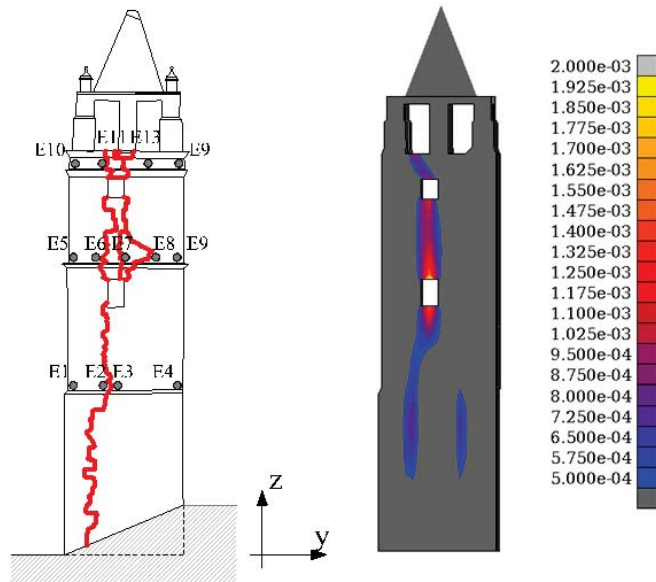


Figure 22: Mogadouro tower east façade: surveyed (on the left) and numerical (on the right) cracking pattern.

468 Table 10 summarizes the results of the modal analysis before rehabilita-
 469 tion in terms of experimental ($f_{i,exp}$) and numerical ($f_{i,N}$) frequencies, relative
 470 frequency error, and MAC values between experimental and numerical mode
 471 shapes (evaluated considering just the nodes monitored during the experi-
 472 mental campaigns [44]). The four frequencies and the first two mode shapes
 473 are very well approximated, while the correlation of the third and fourth
 474 numerical mode shapes with their experimental counterparts is quite low

475 (particularly for the fourth mode).

Mode	$f_{i,\text{exp}}$ [Hz]	$f_{i,\text{N}}$ [Hz]	Δ_f [%]	MAC
1	2.15	2.15	0.00	0.94
2	2.58	2.60	-0.78	0.96
3	4.98	4.92	1.20	0.32
4	5.74	5.88	2.44	0.01

Table 10: Comparison between experimental ($f_{i,\text{exp}}$) and numerical frequencies ($f_{i,\text{N}}$); relative frequency error $\Delta_f = (f_{i,\text{exp}} - f_{i,\text{N}})/f_{i,\text{exp}}$ and MAC values before rehabilitation.

476 Figure 23 shows the first four experimental and numerical (calculated by
477 NOSA-ITACA) mode shapes of the Mogadouro tower before rehabilitation.

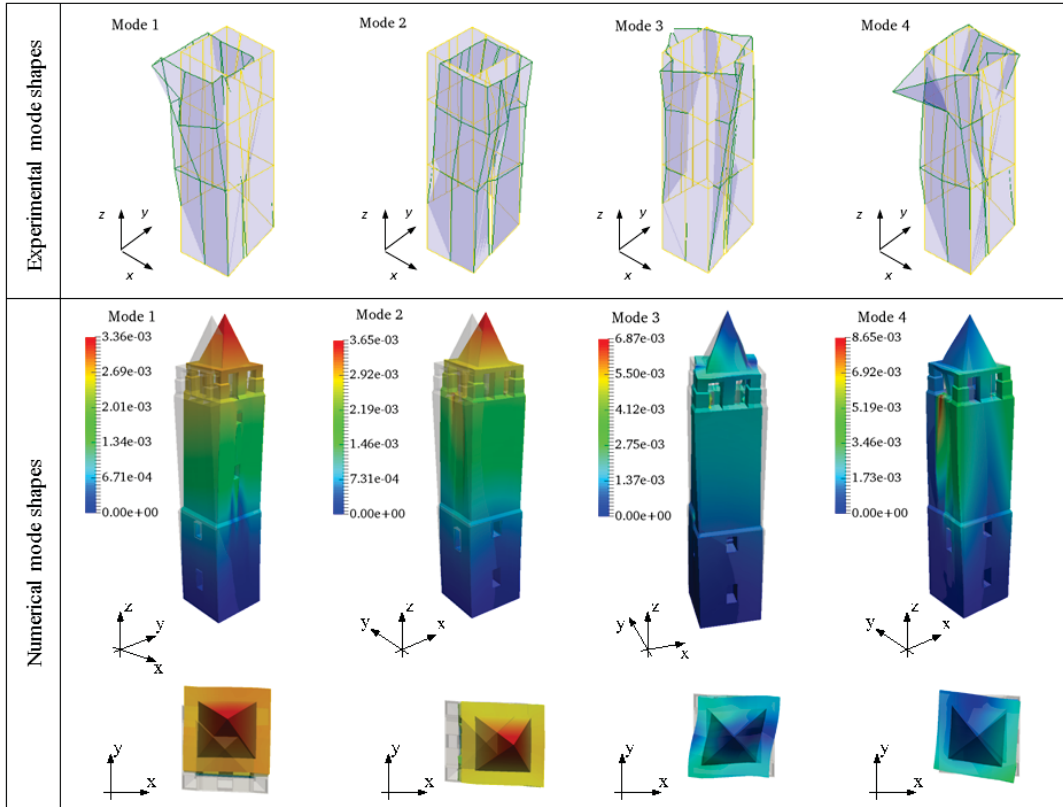


Figure 23: **First four mode shapes of the Mogadouro tower before rehabilitation.**

478 Subsequently, the same FE model is adopted to perform the analysis of
 479 the tower after rehabilitation, considering a tensile strength $\sigma_t = 10$ kPa
 480 for the restored walls (material 2 in Figure 19), while the other mechanical
 481 properties are kept fixed.

482 The results are summarized in table 11; **Figure 24 shows the first four**
 483 **experimental and numerical mode shapes after rehabilitation.** All
 484 frequencies increase with respect to the unreinforced case, consistently with
 485 the experimental results. In this case, a good approximation is achieved for

486 all four mode shapes, and a very great accuracy is obtained in the assessment
 487 of the first two frequencies.

Mode	$f_{i,\text{exp}}$ [Hz]	$f_{i,\text{N}}$ [Hz]	Δ_f [%]	MAC
1	2.56	2.59	-1.17	0.98
2	2.76	2.75	0.36	0.98
3	7.15	8.39	-17.34	0.97
4	8.86	9.32	-5.19	0.74

Table 11: Comparison between experimental ($f_{i,\text{exp}}$) and numerical frequencies ($f_{i,\text{N}}$); relative frequency error $\Delta_f = (f_{i,\text{exp}} - f_{i,\text{N}})/f_{i,\text{exp}}$ and MAC values after rehabilitation.

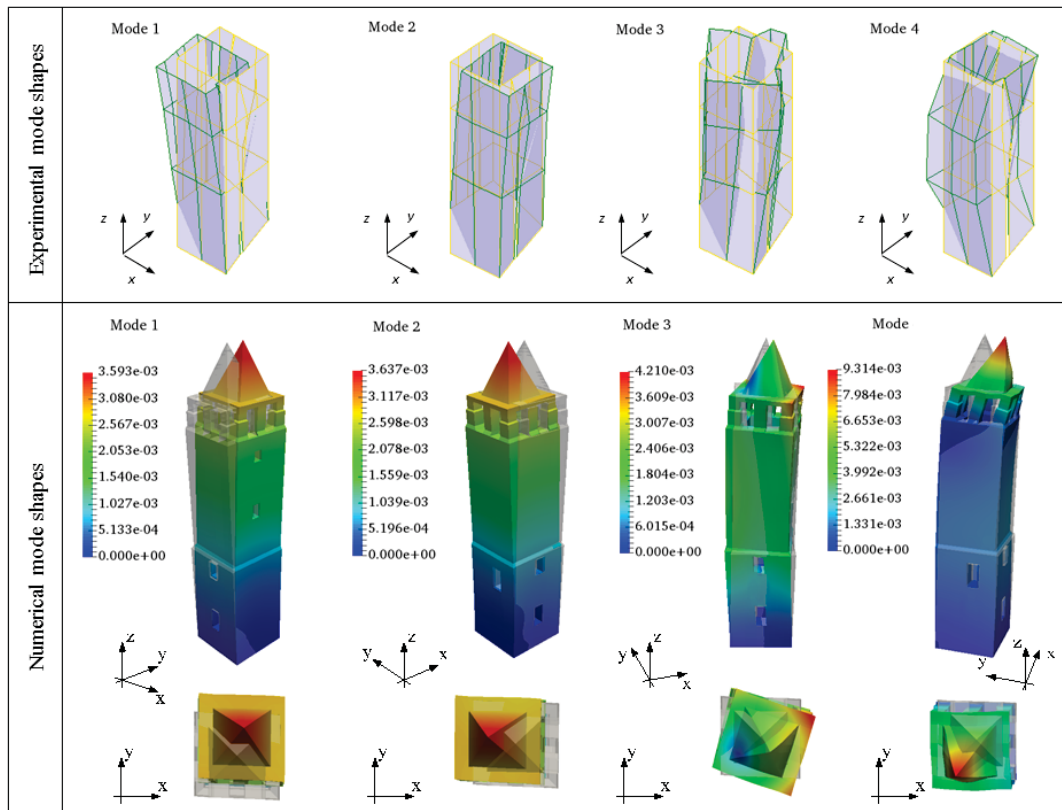


Figure 24: First four mode shapes of the Mogadouro tower after rehabilitation.

488 Table 12 recapitulates experimental and numerical results in terms of
489 natural frequencies, before and after rehabilitation of the tower, pointing out
490 that the linear perturbation analysis allows to catch the dynamic behavior
491 of the structure in damaged conditions with reasonable accuracy. The table
492 shows also that the numerical increase of the natural frequencies, due to
493 restoration of the tower and obtained in the numerical model through an
494 increase of tensile strength of the damaged walls, is in agreement with the
495 experimental results, apart from the third frequency, which is overestimated
496 by the code.

Mode	Before		After		Δ_f [%]	
	$f_{i,\text{exp}}$ [Hz]	$f_{i,\text{N}}$ [Hz]	$f_{i,\text{exp}}$ [Hz]	$f_{i,\text{N}}$ [Hz]	exp	num
1	2.15	2.15	2.56	2.59	+19.28	+20.46
2	2.58	2.60	2.76	2.75	+6.70	+5.77
3	4.98	4.92	7.15	8.39	+43.67	+70.52
4	5.74	5.88	8.86	9.32	+54.37	+58.50

Table 12: Summary of the experimental and numerical results before and after rehabilitation.

497 5. Conclusions

498 The present paper investigated the dependence of the dynamic properties
499 of masonry structures on the nonlinear behavior of the constituent materials.
500 As the mechanical response of masonry constructions is remarkably differ-
501 ent in tension and in compression, and cracks may arise due permanent and
502 accidental loads, standard modal analysis may result unrealistic. In this
503 context, a linear perturbation approach must be used to adequately estimate
504 the dynamic properties of masonry constructions in the presence of cracked
505 regions. After a brief description of the constitutive equations and numer-
506 ical procedures implemented in different FE codes (NOSA-ITACA, DIANA
507 and MARC), the proposed approach, which couples linear perturbation and
508 modal analysis, is described. The numerical procedure is then applied to
509 a masonry arch with the aim of comparing and cross-validating the results
510 obtained from the afore-mentioned FE codes in terms of natural frequencies
511 and mode shapes for decreasing values of tensile strength. It is demonstrated
512 that, despite the different constitutive equations the three codes rely on, the
513 dependence of the dynamic properties of the masonry arch on the applied
514 loads and induced crack distribution is consistent among the three of them,
515 showing comparable frequency downshifts and MAC values over the different
516 damage scenarios. Finally, with the purpose of validating the same approach
517 on a real case-study structure, the procedure is applied to a historic masonry
518 tower affected by a serious crack pattern. After solving the nonlinear equilib-
519 rium problem of the structure subjected to its own weight and reproducing

520 the actual fracture distribution, a modal analysis about the equilibrium so-
521 lution is carried out to estimate frequencies and mode shapes of the tower
522 in the presence of cracks as well as after the rehabilitation works. A FE
523 model updating is used to tune the optimal values for both Young’s modu-
524 lus and tensile strength in the different parts of the tower, according to the
525 observed structural conditions before and after the intervention. **The com-
526 parison between numerical and experimental results showed that
527 the combination of linear perturbation and modal analysis enables
528 to estimate with reasonable accuracy the first two frequencies and
529 mode shapes of the masonry tower in both damaged and reinforced
530 conditions. Further applications are necessary to confirm the reli-
531 ability of the adopted approach for the solution of the dynamic
532 problem in case of structures built with masonry materials.**

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