# Using the Alpha Geodesic Distance in Shapes K-Means Clustering 

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#### Abstract

This paper is based mainly on the relevant work [1]. In that paper the authors studied the problem of clustering of different shapes using Information Geometry tools including, among others, the Fisher Information and the resulting distance. Here we are using the same methods but for the geodesics of the alpha connection for three different values of the alpha parameter.


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## 1. The alpha connection and the

 equations of the alpha geodesicsWe are considering the $2 D$ normal distribution:

$$
\begin{align*}
& p\left(x, y, \mu_{1}, \mu_{2}, \sigma_{1}, \sigma_{2}\right) \\
& =\frac{1}{2 \pi \sigma_{1} \sigma_{2}} \exp \left\{-\frac{1}{2}\left(\frac{x-\mu_{1}}{\sigma_{1}}\right)^{2}-\frac{1}{2}\left(\frac{x-\mu_{2}}{\sigma_{2}}\right)^{2}\right\} \tag{1}
\end{align*}
$$

Let $\xi=\left(\mu_{1}, \mu_{2}, \sigma_{1}, \sigma_{2}\right)$. Then, if $\partial_{i} \equiv \frac{\partial}{\partial \xi^{i}}$, the Fisher metric is given by the formula [2] $g_{i j}=$ $E\left(\partial_{i} l \partial_{j} l\right)$ where $l=l\left(x, y, \mu_{1}, \mu_{2}, \sigma_{1}, \sigma_{2}\right)$
$=\log p\left(x, y, \mu_{1}, \mu_{2}, \sigma_{1}, \sigma_{2}\right)$ and the mean value has been computed for the above $2 D$ normal distribution. We have found that

$$
\begin{equation*}
g=\operatorname{diag}\left[\frac{1}{\sigma_{1}^{2}}, \frac{1}{\sigma_{2}^{2}}, \frac{2}{\sigma_{1}^{2}}, \frac{2}{\sigma_{2}^{2}}\right] . \tag{2}
\end{equation*}
$$

Next we have calculated the coefficients of the alpha-connection from the following formula

$$
\begin{equation*}
\Gamma_{i j, k}^{(\alpha)}=E\left[\left(\partial_{i} \partial_{j} l+\frac{1-\alpha}{2} \partial_{i} l \partial_{j} l\right) \partial_{k} l\right], \tag{3}
\end{equation*}
$$

[^0]and consequently
\[

$$
\begin{equation*}
\Gamma_{a b}^{(\alpha) d}=g^{c d} \Gamma_{a b, c}^{(\alpha)}, \tag{4}
\end{equation*}
$$

\]

where $g^{c d}$ are the corresponding elements of the inverse matrix $g^{-1}$. Then the equations of the alpha geodesics $c^{i}=c^{i}(t)$ are

$$
\begin{equation*}
\frac{d^{2} c^{i}}{d t^{2}}+\Gamma_{j k}^{(\alpha) i} \frac{d c^{j}}{d t} \frac{d c^{k}}{d t}=0 \tag{5}
\end{equation*}
$$

and the distance from one point $\xi=\left(\mu_{1}, \mu_{2}, \sigma_{1}, \sigma_{2}\right)$ to $\xi^{\prime}=\left(\mu_{1}^{\prime}, \mu_{2}^{\prime}, \sigma_{1}^{\prime}, \sigma_{2}^{\prime}\right)$ along a geodesic is given by the formula

$$
\begin{equation*}
d\left(\xi, \xi^{\prime}\right)=\int_{c} d s=\int_{t}^{t^{\prime}} \sqrt{g_{i j} \frac{d c^{i}}{d t} \frac{d c^{j}}{d t}} d t \tag{6}
\end{equation*}
$$

where $c(t)=\xi$ and $c\left(t^{\prime}\right)=\xi^{\prime}$.

## 2. Finding the geodesics

 numericallyIn order to find the geodesic $c=c^{i}(t)$ from the point $\xi=\left(\mu_{1}, \mu_{2}, \sigma_{1}, \sigma_{2}\right)$ to the point $\xi^{\prime}=\left(\mu_{1}^{\prime}, \mu_{2}^{\prime}, \sigma_{1}^{\prime}, \sigma_{2}^{\prime}\right)$, we suppose

$$
\begin{equation*}
c^{i}(t)=c^{i}(0)+\left.t \frac{d c^{i}}{d t}\right|_{t=0}+\left.\frac{t^{2}}{2} \frac{d^{2} c^{i}}{d t^{2}}\right|_{t=0} \tag{7}
\end{equation*}
$$

for $i=1,2,3,4$. I.e. we assume the Taylor expansion of $c^{i}$ for up to the second order.

From the equations of geodesics we have

$$
\begin{equation*}
\left.\frac{d^{2} c^{i}}{d t^{2}}\right|_{t=0}=-\left.\Gamma_{j k}^{(\alpha) i} \frac{d c^{j}}{d t} \frac{d c^{k}}{d t}\right|_{t=0} \tag{8}
\end{equation*}
$$

so the above expansion takes the form

$$
\begin{equation*}
c^{i}(t)=c^{i}(0)+\left.t \frac{d c^{i}}{d t}\right|_{t=0}-\left.\frac{t^{2}}{2}\left(\Gamma_{j k}^{(\alpha) i} \frac{d c^{j}}{d t} \frac{d c^{k}}{d t}\right)\right|_{t=0} \tag{9}
\end{equation*}
$$

with $c(0)=\xi$.
In order to have an approximate expression for the geodesic $c^{i}$ we want to know the first order derivatives at $t=0$. These can be computed if we demand

$$
\begin{equation*}
c^{i}(1)=\xi^{\prime}=\left(\mu_{1}^{\prime}, \mu_{2}^{\prime}, \sigma_{1}^{\prime}, \sigma_{2}^{\prime}\right) \tag{10}
\end{equation*}
$$

so we have a non-linear system of four equations with four unknowns which we solve numerically. Finally,

$$
\begin{equation*}
d\left(\xi, \xi^{\prime}\right)=\int_{0}^{1} \sqrt{g_{i j} \frac{d c^{i}}{d t} \frac{d c^{j}}{d t}} d t \tag{11}
\end{equation*}
$$

## 3. Numerical study

The use of Information geometry tools for clustering shapes has already been considered in several papers [3, 4] However, so far only the Fisher Information and the Wasserstein distance has been evaluated. In order to evaluate the cluster recovery and to test our algorithms using the alpha-geodesic and the corresponding distance defined on the statistical manifold, we consider a modified Gaussian perturbation model where the $j$ th configuration is obtained as follows:

$$
\begin{equation*}
X_{j}=\left(\mu_{g_{j}}+E_{j}\right) \Gamma_{j}+1_{8} \gamma_{j}^{T} \tag{12}
\end{equation*}
$$

where $j=1, \ldots, 40$ and

- $\mu_{g_{j}}=\mu_{1}$ for $j=1, \ldots, 20, \mu_{g_{j}}=\mu_{2}$ for $j=21, \ldots, 40$ are mean values from the data of the rat calvarial data set [5], corresponding to the skull midsagittal section of 21 rats collected at ages of $7\left(\mu_{1}\right)$ and $14\left(\mu_{2}\right)$ days;
- $E_{j}$ are $8 \times 2$ random error matrices simulated from the multivariate Normal distribution with mean value zero and covariance structure $\Sigma_{E}$;
- $\Gamma_{j}$ is an orthogonal rotation matrix with angle $\theta_{j}=j \frac{2 \pi}{40}$;
- $1_{8}=(1,1,1,1,1,1,1,1)^{T}$;
- $\gamma_{j}^{T}=\left(\gamma_{1 j}, \gamma_{2 j}\right)$ with $\gamma_{1 j}, \gamma_{2 j}$ real numbers uniformly produced in the range $[-2,2]$.

Three types of covariance matrix $\Sigma_{E}$ are considered as described in [1]:

- Isotropic with $\Sigma_{E}=\sigma I_{8} \otimes \sigma I_{2} ;$
- Heteroscedastic
$\Sigma_{E}=\operatorname{diag}\left(\sigma_{1}, \ldots, \sigma_{8}\right) \bigotimes \sigma I_{2} ;$
- Anisotropic with $\Sigma_{E}=\sigma I_{8} \bigotimes \operatorname{diag}\left(\sigma_{x}, \sigma_{y}\right)$ with $\sigma_{x} \neq \sigma_{y}$.

The two types of algorithms (type I and type II) are described in [1] in details. In type 0 algorithm we have considered constant covariances (equal to 13 ) for the calculation of alpha distances. For each covariant structure we simulated only 5 samples and, for each sample, we computed the adjusted rand index.

In Figures 1, 2, 3 we can see the adjusted rand index for three different clustering algorithms, an index close to 1 for the best clustering results or to 0 otherwise. In the socalled round case we have the same constant covariance when measuring the length of the alpha geodesic. In type I and type II we allow the variances to vary during the clustering procedure. We see that the best clustering method is for type I algorithm [1], in which the covariance over the rat data is taken into account and for the values 0.7 and 0.8 of alpha. The picture is similar for all cases, that is, for the isotropic, the heteroscedastic and the anisotropic case.


FIG. 1: (color online)


FIG. 2: (color online)


FIG. 3: (color online)

## 4. Further extensions of this work

This is a preliminary study. Obviously, to have better results, we need a bigger number of samples. Besides, a better Taylor expansion probably would help. Finally we have to study the behaviour of the above geodesics and the related distance under similarity transformations. All these will be an object of a future work.
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