



On the Differentiation of Integrals in Measure Spaces Along Filters

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Received: 26 July 2022 / Accepted: 10 August 2022 / Published online: 15 November 2022
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Abstract

It is known that the study of the boundary behavior of (harmonic or) holomorphic functions, to which N. Sibony has contributed with penetrating work, is linked to the differentiation of integrals. In 1936, R. de Possel observed that, in the general setting of a measure space *with no metric structure*, certain phenomena, relative to the differentiation of integrals, which are familiar in the Euclidean setting *precisely because of the presence of a metric*, are devoid of actual meaning. In the first part of this work, we introduce the concept of *functional convergence class* that provides a unifying framework for various limiting processes and enables us to establish a hierarchy between them, and show that, within this hierarchy, the notion of *filter* (introduced by H. Cartan just a year after De Possel's contribution) occupies the position of wider scope. In the second part of this work, we show how to reformulate some of the contributions of de Possel in the language of filters.

Keywords Differentiation of integrals · Almost everywhere convergence · Filters · Moore–Smith sequences · Liftings

Mathematics Subject Classification 28A15 · 28A51 · 18F99

Contents

1	Introduction	3
1.1	Background	3
1.1.1	The Mean-Value Operator	4

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1.1.2	The Problem of the Differentiation of Integrals	5
1.1.3	René de Possel's Approach	6
1.1.4	Notation from Category Theory	7
1.2	Foundational Results	8
1.2.1	Functional Convergence Classes	8
1.2.2	Examples of Functional Convergence Classes	10
1.2.3	The Notion of Filter	11
1.2.4	The Category of Filtered Sets	11
1.2.5	Limiting Values Along a Filter	12
1.2.6	The Functional Convergence Class Induced by a Filter	13
1.3	A Hierarchy of Limiting Processes	13
1.4	Applications to the Problem of the Differentiation of Integrals (I)	14
1.4.1	The Set-Up Based on Filters	14
1.4.2	On the Differentiation of the Class of All Measurable Sets (I)	15
1.4.3	Measurability Issues (I)	15
1.4.4	A Criterion for the Differentiation of Integrable Functions	16
1.4.5	On the Differentiation of the Class of All Measurable Sets (II)	17
2	Notation	17
2.1	Sets, Collections, and Families	17
2.1.1	Direct Image and Inverse Image Notation	18
2.2	Measure-Theoretic Notation	18
2.2.1	Null Sets and Derived Notions	18
3	Functional Convergence Classes	19
3.1	Functional Convergence Classes	19
3.2	A Representation Theorem for Functional Convergence Classes	20
3.3	Moore–Smith Sequences	22
3.4	Limiting Values of Moore–Smith Sequences	24
3.5	The Functional Convergence Class Associated to a Direction	26
3.6	A Comparison of the Two Notions	26
3.7	The Functional Convergence Class Associated to a Family of Moore–Smith Sequences	29
4	Preliminary Results on Filters	30
4.1	Basic Lattice-Theoretic Properties of $\mathcal{F}(A)$	30
4.2	The Operator A^\uparrow	31
4.3	Bases and Subbases	33
4.3.1	Generating Bases for a Filter	34
4.3.2	Filter Subbases	35
4.4	Ultrafilters and Compactness	35
4.5	Functorial Properties of Direct Images and Application to Limiting Values	37
4.6	Extension of Filters from a Subset and Restriction to a Subset	38
4.7	Separable Filters	39
5	Proof of Theorem 3.29	40
6	Applications to Set-Valued Moore–Smith Sequences	44
6.1	Functorial Properties of the Filter of Tails	45
6.2	Set-Valued Moore–Smith Sequences	47
7	Proof of Theorem 3.33	50
8	Proof of Theorem 3.37	50
9	A Natural Topology on the Collection of Filters	50
9.1	Topological Preliminaries	50
9.2	Further Lattice-Theoretic Properties of $\mathcal{F}(A)$	53
9.3	Boolean Algebras	55
9.3.1	Examples of Boolean Algebras	56
9.3.2	Filters, Ultrafilters, and Boolean Algebras	56
9.4	The Natural Topology on $\mathcal{F}(A)$	57
9.5	Basic Properties of the Natural Topology on $\mathcal{F}(A)$	58
9.6	Compactness Properties of the Natural Topology	60
9.7	Other Properties of the Natural Topology	62
10	Applications of the Natural Topology to Cluster Points of Filters	63

10.1 Application to Compactness	64
11 Filters on the Real Line	65
11.1 The Structure of the Cluster Set of Filters on the Real Line (I)	66
11.2 Cluster Set and Limiting Points	68
11.3 The Filters $N_{\mathbb{R}}(\pm\infty)$ from the Viewpoint of the Natural Topology on $\mathcal{F}(\mathbb{R})$	68
11.4 The Structure of the Cluster Set of Filters on the Real Line (II)	69
12 Applications of the Natural Topology to Moore–Smith Sequences of Sets	73
12.1 Cofinal Subsets in a Directed Set	73
12.2 The Cluster Set of a Moore–Smith Sequence of Points	74
12.3 The Cluster Set of Set-Valued Moore–Smith Sequences	74
12.4 Applications to the Notion of Moore–Smith Subsequence	75
13 Applications to the Problem of the Differentiation of Integrals (II)	77
13.1 Measurability Issues (II)	78
13.2 Proof of Theorem 1.27	78
13.3 The Maximal Operator Associated to a Family of Filters	79
14 Miscellaneous Notes	80
References	81

1 Introduction

In 1936, R. de Possel observed that, in the general setting of a measure space *with no metric structure*, certain phenomena, relative to the differentiation of integrals, which are familiar in the Euclidean setting *precisely because of the presence of a metric*, are devoid of actual meaning. In his work, de Possel introduced an axiomatic approach based on a limiting process centered on the preliminary choice of certain *sequences* of sets. The notion of *filter*, due to Cartan [8], appeared 1 year after de Possel's work, and yields another limiting process, which, in the context of the problem of the differentiation of integrals, turns out to be preferable, for specific reasons that will be outlined momentarily.

The purpose of this paper is, first of all, to show that the language of filters yields a notion of limiting process that has wider scope, with respect to other limiting processes. On the basis of this preliminary groundwork, we show how to reinterpret in the language of filters some of the contributions given by de Possel to the problem of the differentiation of integrals in measure spaces.

In order to achieve the first goal, we introduce the concept of *functional convergence class* and systematize the results on convergence along filters by using a topology on the space of all filters. Moreover, we present a self-contained and fairly complete treatment of the notions centered around the relation between filters and Moore–Smith sequences, encompassing various results not all of which appear to be known, or as well known as they ought to be.

1.1 Background

Let $X \equiv (X, \mathcal{M}, \omega)$ be a measure space, where ω is a measure defined on a σ -algebra \mathcal{M} of subsets of X . The vector space of measurable real-valued functions defined a.e. on X , whose p th-power is integrable ($p > 0$), is denoted by $\mathcal{L}^p(X)$. The quotient of

$\mathcal{L}^p(X)$ under a.e. equality is denoted by $L^p(X)$. The corresponding projection

$$\mathcal{L}^p(X) \rightarrow L^p(X)$$

maps $f \in \mathcal{L}^p(X)$ to the class of functions which are a.e. equal to f . We denote this class by \mathbf{f} (in bold font), and say that $f \in \mathcal{L}^p(X)$ is a *representative* of $\mathbf{f} \in L^p(X)$. The spaces $\mathcal{L}^\infty(X)$ and $L^\infty(X)$ are also defined in the familiar way [29, p. 244].

Similarly, the quotient of \mathcal{M} under a.e. equality of measurable sets is denoted by M and is called the measure algebra of (X, \mathcal{M}, ω) . The corresponding projection

$$\pi : \mathcal{M} \rightarrow M \tag{1.1}$$

is called the canonical projection associated to (X, \mathcal{M}, ω) , and is a homomorphism of Boolean algebras.

1.1.1 The Mean-Value Operator

Consider the subcollection of \mathcal{M} defined as follows:

$$\mathcal{A}(X) \stackrel{\text{def}}{=} \{Q \in \mathcal{M} : 0 < \omega(Q) < +\infty\}. \tag{1.2}$$

The sets in (1.2) are called *averageable*, since for each $f \in L^1(X)$ and $Q \in \mathcal{A}(X)$ the mean-value of f over Q may be defined in the familiar way, as follows:

$$f_\omega[Q] \stackrel{\text{def}}{=} \frac{1}{\omega(Q)} \int_Q f \, d\omega \tag{1.3}$$

(where $f \in \mathcal{L}^1(X)$ is any representative of \mathbf{f}). Hence (1.3) defines a function

$$f_\omega : \mathcal{A}(X) \rightarrow \mathbb{R}. \tag{1.4}$$

The *mean-value operator* for (X, \mathcal{M}, ω) is the linear operator:

$$\tilde{\omega} : L^1(X) \rightarrow \text{hom}_{\text{Set}}(\mathcal{A}(X), \mathbb{R}) \tag{1.5}$$

defined by

$$\tilde{\omega}(f) \stackrel{\text{def}}{=} f_\omega$$

where $\text{hom}_{\text{Set}}(\mathcal{A}(X), \mathbb{R})$ is the collection of all functions from $\mathcal{A}(X)$ to \mathbb{R} . If $S \subset Q$ then

$$\mathbb{1}_S : S \rightarrow \{0, 1\}$$

is the *indicator function* of S : $\mathbb{1}_S(x) = 1$ if $x \in S$ and $\mathbb{1}_S(x) = 0$ otherwise. Recall that the vertical bar notation is well established in probability theory to denote *conditional*

expectation, of which (1.3) is a particular case. Indeed, if f is the indicator function of $R \in \mathcal{A}(X)$, i.e., $f = \mathbb{1}_R$, then $\mathbb{1}_R \in \mathcal{L}^1(X)$ and instead of $(\mathbb{1}_R)_\omega[Q]$ we write $\tilde{\omega}(R|Q)$. Hence

$$\tilde{\omega}(R|Q) = \frac{\omega(Q \cap R)}{\omega(Q)}.$$

1.1.2 The Problem of the Differentiation of Integrals

The following preliminary observation will help us make a precise statement of the problem.

- (i) The function

$$f_\omega \in \text{hom}_{\text{set}}(\mathcal{A}(X), \mathbb{R}) \tag{1.6}$$

defined in (1.3) encodes all the mean-values of f .

- (ii) The Radon–Nykodim theorem says that f is uniquely determined by f_ω [29, p. 238].

Observe that $f_\omega : \mathcal{A}(X) \rightarrow \mathbb{R}$ is a bona fide function, defined on $\mathcal{A}(X)$, while f is an equivalence class of functions, and that the values $f(x)$ of a representative of f may be recovered only up to a set of measure zero (called the *exceptional set of f*).

The problem of the differentiation of integrals may be described in the following terms:

Find a limiting process that enables us to recapture (a representative of) $f \in L^1(X)$ from f_ω (i.e., from the mean-values of f).

Observe that the notion of *limiting process* appears in the formulation of the problem in an informal fashion. One of the goals of the present paper is to establish a formal framework for the concept of “limiting process”: This will be achieved by means of the notion of *functional convergence class*. Another goal, subordinate to the first one, is to identify, within this framework, the notion of limiting process that has wider scope: We will show that the concept of *filter* has precisely this property.

A solution to the problem of the differentiation of integrals is called a *Generalized Lebesgue Differentiation Theorem*. Indeed, the Lebesgue differentiation theorem solves the problem of the differentiation of integrals in the case $X = (\mathbb{R}, \mathcal{M}, \omega)$, where ω is Lebesgue measure and \mathcal{M} is the σ -algebra of Lebesgue-measurable subsets of \mathbb{R} , and says that, if $f \in \mathcal{L}^1(\mathbb{R})$, then, for a.e. $x \in \mathbb{R}$, its value $f(x)$ is approximately equal to the mean-value of f over balls which are, in a certain sense, “close to” x . The prototype result is that, for a.e. $x \in \mathbb{R}$,

$$f(x) = \lim_{r \rightarrow 0} f_\omega[I_x(r)], \tag{1.7}$$

where $I_x(r)$ is the open interval in \mathbb{R} of center x and radius r . Observe that *the limiting process used in (1.7), to which the function f_ω is subject, rests on the metric structure of \mathbb{R} .*

Lebesgue himself has given deep generalizations of his one-dimensional results to higher-dimensional Euclidean space \mathbb{R}^n , where he considered mean-values $f_\omega[B]$ of f over balls $B \subset \mathbb{R}^n$ which are not centered at x , or even balls which do not contain the point x , provided the balls B get “close to” x in a certain manner (which may be described as being of a “nontangential” nature; see [33]). Once more, the metric structure of the ambient space is used to obtain a “limiting value” from the function $f_\omega \in \text{hom}_{\text{Set}}(\mathcal{A}(X), \mathbb{R})$ defined in (1.3).

In order to achieve his results, Lebesgue had to solve two problems. Firstly, he had to describe what it means for a ball to be “close to” the point x . Secondly, he had to understand which *manners of approach* of balls to x are compatible with the intended convergence result. The first task, in the context of a metric measure space, such as \mathbb{R}^n , is indeed not a difficult one, since the metric itself, which is used to define the balls, endows the collection of all its nonempty subsets with a pseudometric: The Hausdorff pseudometric. Indeed, in this context, we may say that a *sequence*

$$Q : \mathbb{N} \rightarrow \mathcal{A}(X)$$

converges to a point $x \in X$ if, for each ball $B_x(r)$ of center x and radius $r > 0$, the set $Q(n)$ is eventually contained in $B_x(r)$. A similar approach may be adapted, at least in principle, in the context of a topological measure space $(X, \mathcal{M}, \omega, \Theta)$ (where ω is the measure, defined on a σ -algebra \mathcal{M} of subsets of X , and Θ is a topology with $\Theta \subset \mathcal{M}$).

1.1.3 René de Possel’s Approach

If (X, \mathcal{M}, ω) is a measure space with no further structure, then, although it makes sense to consider mean values, as in (1.3), it does not seem possible to define, in this degree of generality, what it means for a sequence $Q : \mathbb{N} \rightarrow \mathcal{A}(X)$ to converge to a point x , especially if the sets $Q(n)$ are not assumed to contain x . This difficulty was perceived already in 1936 by René de Possel, who observed that only some of the main properties of Lebesgue measure admit *d’une manière évidente* (in evident ways) an extension to the case of an arbitrary measure space, but others *semblent perdre toute signification dès que l’espace n’est plus métrique* (appear to lose their meaning as soon as the space is not metric) [9]. Among the latter, he listed the properties related to differentiation of integrals.

It is useful to present the particular solution devised by de Possel in the context of the general underlying problem, which may be formulated by replacing the space $\mathcal{A}(X)$ with a generic set A with no further structure. If $\text{hom}_{\text{Set}}(A, \mathbb{R})$ denotes the collection of all functions from A to \mathbb{R} , then the general underlying problem is that of finding the *limiting processes* to which the elements φ of $\text{hom}_{\text{Set}}(A, \mathbb{R})$ may be subjected, which yield as a result a “limiting value” $y \in \mathbb{R}$ and enable us to write

$$y = \lim \varphi, \tag{1.8}$$

(where *lim* denotes the limiting process). Formally, whatever “limiting process” we may be able to devise, its end result is the selection of a collection \mathcal{F} of pairs $(y, \varphi) \in$

$\mathbb{R} \times \text{hom}_{\text{Set}}(A, \mathbb{R})$, where

$$(y, \varphi) \in \mathcal{F} \text{ if and only if (1.8) holds.} \tag{1.9}$$

The particular limiting process devised by de Possel is based on the choice of a nonempty subset V of the collection $\text{hom}_{\text{Set}}(\mathbb{N}, A)$ of all A -valued sequences, i.e.,

$$V \subset \text{hom}_{\text{Set}}(\mathbb{N}, A). \tag{1.10}$$

The limiting process associated to the choice of V in (1.10) is then a natural one: to wit, it is the convergence of φ to y along each sequence q in the collection, i.e.,

$$\lim_{n \rightarrow +\infty} \varphi(q(n)) = y \quad \text{for each } q \in V. \tag{1.11}$$

The application of this limiting process to the case where $A = \mathcal{A}(X)$ led de Possel to adopt an axiomatic approach based on the preliminary choice of a function \mathcal{V} of the following form:

$$X \ni x \mapsto \mathcal{V}(x) \subset \text{hom}_{\text{Set}}(\mathbb{N}, \mathcal{A}(X)), \tag{1.12}$$

where $\text{hom}_{\text{Set}}(\mathbb{N}, \mathcal{A}(X))$ is the collection of all $\mathcal{A}(X)$ -valued sequences, with the understanding that the sequences in the collection $\mathcal{V}(x)$ are axiomatically assumed to be “convergent” to a given point $x \in X$. In this set-up, de Possel had to solve the following problem: specify conditions on the function \mathcal{V} in (1.12) which ensure that

$$f(x) = \lim_{n \rightarrow +\infty} f_{\omega}[Q(n)] \quad \forall Q \in \mathcal{V}(x) \tag{1.13}$$

for each $f \in \mathcal{R}$, where $\mathcal{R} \subset L^1(X)$ is a specified class of functions, and a.e. $x \in X$.

1.1.4 Notation from Category Theory

We find it convenient to adapt to our needs the notation from category theory employed in [17], and, whenever it is helpful, we append to an object or a morphism a subscript that specifies in which category it is located. Hence if C is a given category, we denote by $\text{hom}_C(A, Z)$ the collection of morphisms in C from A to Z . For example, $\text{hom}_{\text{Set}}(A, Z)$ [resp. $\text{hom}_{\text{BA}}(A, Z)$] denotes the collection of functions from a set A to a set Z (resp. the collection of Boolean algebra homomorphisms between Boolean algebras A and Z). Moreover, this subscript device will be used as a shorthand for the so-called forgetful functors. For example, if A is a topological space, then A_{Set} denotes the underlying set. However, we will depart from strict observance of these notational devices whenever they lead to unnecessary notational clutter. For example, we find it useful to write, with a slight abuse of notation, $\text{hom}_{\text{Set}}(A, Z)$ instead of $\text{hom}_{\text{Set}}(A_{\text{Set}}, Z_{\text{Set}})$, whenever A and Z are objects in some concrete category [recall that an object $A \equiv (A_{\text{Set}}, S_A)$ in a concrete category is a set A_{Set} , called the *underlying set*, endowed with additional structure S_A]. In the same vein, whenever the

precise meaning can be gathered from context, the same symbol will denote an object in a concrete category or its underlying set.

1.2 Foundational Results

The limiting process adopted by de Possel is but one of many that have been conceived. We have already observed that every “limiting process” (1.8) yields, via (1.9), a relation between \mathbb{R} and $\text{hom}_{\text{Set}}(A, \mathbb{R})$, i.e., a subset

$$\mathcal{F} \subset \mathbb{R} \times \text{hom}_{\text{Set}}(A, \mathbb{R}). \tag{1.14}$$

1.2.1 Functional Convergence Classes

The first contribution of the present paper is the introduction of a set of axioms which describe the properties which a relation \mathcal{F} between \mathbb{R} and $\text{hom}_{\text{Set}}(A, \mathbb{R})$ should satisfy in order to be the outcome of some “reasonable” limiting process which acts, so to say, in the “background.” Indeed, one would hardly expect that every relation \mathcal{F} between \mathbb{R} and $\text{hom}_{\text{Set}}(A, \mathbb{R})$ as in (1.14) will be of interest.

A relation \mathcal{F} between \mathbb{R} and $\text{hom}_{\text{Set}}(A, \mathbb{R})$ is called a functional convergence class if it has some specific, natural properties, encoded in certain axioms, that will be described momentarily. As far as we know, the notion of *functional convergence class* is new, although it is inspired by the notion of *convergence class* [18, p. 73], which has, however, a different character.

The output of a limiting process for real-valued functions is a subset

$$\mathcal{F} \subset \mathbb{R} \times \text{hom}_{\text{Set}}(A, \mathbb{R}), \tag{1.15}$$

i.e., a collection of pairs $(y, \varphi) \in \mathbb{R} \times \text{hom}_{\text{Set}}(A, \mathbb{R})$, where $(y, \varphi) \in \mathcal{F}$ precisely if $y = \lim \varphi$ according to the limiting process acting on the background and encoded in \mathcal{F} . The aim of the abstract notion of *functional convergence class* is precisely to recapture the natural properties that are expected from \mathcal{F} .

The Filter of Neighborhoods of a Point in a Topological Space

Let A be a topological space. If $x \in A$, a *neighborhood of x in A* is a subset of A which contains an open set containing x . The set of all neighborhoods of x in A is denoted by

$$N_A(x) \stackrel{\text{def}}{=} \{Q : Q \subset A \text{ and } Q \text{ is a neighborhood of } x \text{ in } A\}. \tag{1.16}$$

For example, $N_{\mathbb{R}}(\pi)$ is the collection

$$\{Q : Q \subset \mathbb{R} \text{ and } \exists \epsilon > 0 \text{ such that } (\pi - \epsilon, \pi + \epsilon) \subset Q\}.$$

We define (with a slight abuse of language)

$$N_{\mathbb{R}}(+\infty) \stackrel{\text{def}}{=} \{Q : Q \subset \mathbb{R} \text{ and } \exists a \in \mathbb{R} \text{ such that } (a, +\infty) \subset Q\} \tag{1.17}$$

and $N_{\mathbb{R}}(-\infty) \stackrel{\text{def}}{=} \{Q : Q \subset \mathbb{R} \text{ and } \exists a \in \mathbb{R} \text{ such that } (-\infty, a) \subset Q\}$.

Definition 1.1 If A is nonempty set, a *functional convergence relation* for real-valued functions on A is a subset \mathcal{F} of $\mathbb{R} \times \text{hom}_{\text{Set}}(A, \mathbb{R})$ such that, for each $y \in \mathbb{R}$,

$$\varphi \in \text{hom}_{\text{Set}}(A, \mathbb{R}) \text{ and } \varphi(x) = y \text{ for each } x \in A \Rightarrow (y, \varphi) \in \mathcal{F} \tag{1.18}$$

and

$$\mathcal{F} \subsetneq \mathbb{R} \times \text{hom}_{\text{Set}}(A, \mathbb{R}). \tag{1.19}$$

The meaning of (1.18) is that constant functions ought to converge to the constant. The meaning of (1.19) is that it is meant to exclude that every function converges to each value $y \in \mathbb{R}$.

Definition 1.2 A functional convergence relation \mathcal{F} for real-valued functions defined on A is:

Translation invariant if, whenever $(y, \varphi) \in \mathcal{F}$, for some $(y, \varphi) \in \mathbb{R} \times \text{hom}_{\text{Set}}(A, \mathbb{R})$, and $r \in \mathbb{R}$, it follows that $(r + y, r + \varphi) \in \mathcal{F}$, where $r + \varphi \in \text{hom}_{\text{Set}}(A, \mathbb{R})$ is defined “pointwise” by $(r + \varphi)(x) \stackrel{\text{def}}{=} r + \varphi(x)$.

Local if, for each $\beta \in \text{hom}_{\text{Set}}(A, \mathbb{R})$, if there exists $y \in \mathbb{R}$ such that the following property holds

$$\forall U \in N_{\mathbb{R}}(y) \exists V \in N_{\mathbb{R}}(y) \exists \varphi \in \text{hom}_{\text{Set}}(A, \mathbb{R}), \quad (y, \varphi) \in \mathcal{F} \text{ and } \varphi(x) \in V \Rightarrow \beta(x) \in U \tag{1.20}$$

then $(y, \beta) \in \mathcal{F}$.

Hereditary if, whenever $y \in \mathbb{R}$, $(y, \varphi) \in \mathcal{F}$, and $(y, \beta) \in \mathcal{F}$, if $\gamma \in \text{hom}_{\text{Set}}(A, \mathbb{R})$ and there exists $U \in N_{\mathbb{R}}(y)$ such that

$$\varphi(x) \in U \text{ and } \beta(x) \in U \Rightarrow \gamma(x) \in \{\varphi(x), \beta(x)\} \tag{1.21}$$

then it follows that $(y, \gamma) \in \mathcal{F}$.

Definition 1.3 A *functional convergence class* for real-valued functions on A is a functional convergence relation $\mathcal{F} \subset \mathbb{R} \times \text{hom}_{\text{Set}}(A, \mathbb{R})$ which is local, hereditary, and translation invariant. The collection of all functional convergence classes for real-valued functions on A is denoted by

$$\text{FCC}(A).$$

The following observations should help the reader to assess the meaning of the axioms that describe the notion of *functional convergence class*.

(a) These axioms identify a class of subsets of $\mathbb{R} \times \text{hom}_{\text{Set}}(A, \mathbb{R})$.

(b) As we shall see, each \mathcal{F} in this class arises from a certain “limiting process,” expressed in purely formal terms by (1.8).

(c) The link between the “limiting process” (acting on the background) and \mathcal{F} is given by (1.9).

1.2.2 Examples of Functional Convergence Classes

The following examples will give a first bird’s eye view of the content of this paper and help to clarify the picture. More precisely, we will show that each of the following data entails a limiting process that yields a functional convergence class.

Example (i) The first example of a functional convergence class is the one induced by the choice of a nonempty collection of A -valued sequences. In Theorem 3.33 we show that, if $V \subset \text{hom}_{\text{Set}}(\mathbb{N}, A)$ is such a collection and we define \mathcal{F}_V by

$$\mathcal{F}_V \stackrel{\text{def}}{=} \left\{ (y, \varphi) \in \mathbb{R} \times \text{hom}_{\text{Set}}(A, \mathbb{R}) : \lim_{n \rightarrow +\infty} \varphi(\mathbf{q}(n)) = y \text{ for each } \mathbf{q} \in V \right\},$$

[where $\lim_{n \rightarrow +\infty} \varphi(\mathbf{q}(n)) = y$ is the familiar notion of convergence for the sequence $\varphi \circ \mathbf{q} : \mathbb{N} \rightarrow \mathbb{R}$] then \mathcal{F}_V is a functional convergence class.

Example (ii) The second example of a functional convergence class is the one induced by the choice of a direction on A . In Theorem 3.24 we show that if R is a *direction on* A (i.e., R is a preorder on A such that for each $j, k \in A$, there exists an element $l \in A$ such that jRl and kRl , as explained in Sect. 3.3) and we define \mathcal{F}_R by

$$\mathcal{F}_R \stackrel{\text{def}}{=} \left\{ (y, \varphi) \in \mathbb{R} \times \text{hom}_{\text{Set}}(A, \mathbb{R}) : \lim_{(A,R)} \varphi = y \right\},$$

[where $\lim_{(A,R)} \varphi = y$ denotes *Moore–Smith convergence of* $\varphi : A \rightarrow \mathbb{R}$ *along the direction* R , defined in Sect. 3.4], then \mathcal{F}_R is a functional convergence class.

Example (iii) The third example of a functional convergence class is the one induced by the choice of an A -valued Moore–Smith sequence. Theorem 3.33 implies that if \mathbf{q} is such a sequence (hence \mathbf{q} is a function $\mathbf{q} : D \rightarrow A$ defined on a *directed set*, i.e., a set D which is endowed with a direction R) and we define $\mathcal{F}_{\mathbf{q}}$ by

$$\mathcal{F}_{\mathbf{q}} \stackrel{\text{def}}{=} \left\{ (y, \varphi) \in \mathbb{R} \times \text{hom}_{\text{Set}}(A, \mathbb{R}) : \lim_{(D,R)} \varphi \circ \mathbf{q} = y \right\}, \tag{1.22}$$

[where $\lim_{(D,R)} \varphi \circ \mathbf{q} = y$ denotes Moore–Smith convergence of $\varphi \circ \mathbf{q} : D \rightarrow \mathbb{R}$ along R], then $\mathcal{F}_{\mathbf{q}}$ is a functional convergence class.

Example (iv) The fourth example of a functional convergence class is the one induced by the choice of a nonempty collection of A -valued Moore–Smith sequences (where different Moore–Smith sequences in the collection are possibly defined on different directed sets). In Theorem 3.33 we show that if V is such a collection and we define \mathcal{F}_V by

$$\mathcal{F}_V \stackrel{\text{def}}{=} \left\{ (y, \varphi) \in \mathbb{R} \times \text{hom}_{\text{Set}}(A, \mathbb{R}) : \lim_{(D_{\mathbf{q}}, R_{\mathbf{q}})} \varphi \circ \mathbf{q} = y \text{ for each } \mathbf{q} \in V \right\},$$

[where, for each $q \in V$, (D_q, R_q) is the domain of q , and $\lim_{(D_q, R_q)} \varphi \circ q = y$ denotes Moore–Smith convergence of $\varphi \circ q : D_q \rightarrow \mathbb{R}$ along R_q] then \mathcal{F}_V is a functional convergence class.

The fifth example of a functional convergence class is the one induced by the choice of a filter on A .

1.2.3 The Notion of Filter

The notion of *filter*, due to Henri Cartan, is a tool that helps clarify topological phenomena, and acts as a substitute, in case there is no topology; moreover, it is a precious tool in several mathematical areas.

The key observations leading to the notion of *filter* are the following. Firstly, observe that if A is a topological space and $x \in A$ then the set $N_A(x)$, seen as a collection of subset of A , has the following essential properties:

- (F0) It does not contain the empty set.
- (F1) It is closed under finite intersections.
- (F2) It contains every superset of each of its elements.

Secondly, the familiar ϵ – δ description of the existence of a limiting value $\lim_{z \rightarrow x} \varphi(z)$, where φ belongs to $\text{hom}_{\text{Set}}(A, \mathbb{R})$ shows that this notion only depends on the values of φ on (set-theoretically) *small* sets in $N_A(x)$. In view of the following definition, due to Cartan [8], $N_A(x)$ is called the *neighborhood filter associated to A at x* .

Definition 1.4 If A is a set, a *filter on A* (or *filter of subsets of A*) is a collection of subsets of A with the properties (F0), (F1) and (F2). The collection of all filters on A is denoted by $\mathcal{F}(A)$.

Observe that (F1) is equivalent to the conjunction of the following two axioms:

- (F1.a) The collection contains A .
- (F1.b) The intersection of two sets in the collection belong to the collection.

There is no filter on the empty set. If $Z \in \mathcal{F}(A)$ then $A \in Z, \emptyset \notin Z$, and, if $b, c \in Z$, then $b \cap c \neq \emptyset$.

Definition 1.5 (Cartan) A filter $Z \in \mathcal{F}(A)$ is an *ultrafilter* if $W \in \mathcal{F}(A)$ and $Z \subset W$ implies $Z = W$. The collection of all ultrafilters on a set A is denoted by $\mathcal{U}(A)$.

1.2.4 The Category of Filtered Sets

Definition 1.6 A *filtered set* $A = (A_{\text{Set}}, Z_A)$ is a set A_{Set} endowed with a filter $Z_A \in \mathcal{F}(A)$. The set A_{Set} is called the *total space* of the filtered set A . A *filter-homomorphism* $f : A \rightarrow A'$ between the filtered set A and the filtered set A' is a function $f : A_{\text{Set}} \rightarrow A'_{\text{Set}}$ between the underlying sets such that $\{x \in A : f(x) \in b\} \in Z_A$ for each $b \in Z'_{A'}$.

Filtered sets form the objects of a category, denoted $FSet$, where morphisms are filter-homomorphisms. We will return momentarily to the notion of filter-homomorphism, in order to achieve a better understanding of its meaning.

Localization We will see that the seemingly simple hypothesis that a certain set belongs to a given filter has great import, and we use the expression *the filter Z is localized in K* , where $K \subset A$, as synonym for *the set K belongs to the filter $Z \in \mathcal{F}(A)$* .

Definition 1.7 If $K \subset A$, a filter $Z \in \mathcal{F}(A)$ is *weakly localized in K* if $\complement K \notin Z$. We let

$$wloc(Z) \stackrel{\text{def}}{=} \{K : K \subset A, Z \text{ is weakly localized in } K\}. \tag{1.23}$$

Observe that

$$Z \subset wloc(Z) \tag{1.24}$$

and

$wloc(Z)$ satisfies **(F2)**.

Hence if a filter is localized in K then it is weakly localized in K . The converse implication does not hold, unless the given filter is an ultrafilter, as we will see in Lemma 4.26. Indeed, we will see that a filter is an ultrafilter if and only if equality holds in (1.24).

Example 1.8 If A is a topological space and $x \in A$ then $(A, N_A(x))$ is a filtered set.

Example 1.9 The collection

$$f\mathbb{N} \stackrel{\text{def}}{=} \{\mathbf{b} \subset \mathbb{N} : \mathbf{b} \text{ is not empty, } \mathbb{N} \setminus \mathbf{b} \text{ is finite}\} \tag{1.25}$$

is a filter on \mathbb{N} , called the *Fréchet filter on \mathbb{N}* .

Example 1.10 If A is a nonempty set then $\{A\} \in \mathcal{F}(A)$.

Example 1.11 If (X, \mathcal{M}, ω) is a complete probability space then the collection \mathcal{M}_ω^F of measurable sets of full measure in X is a filter on X .

1.2.5 Limiting Values Along a Filter

Observe that the familiar ϵ - δ description of the existence of a limiting value $\lim_{z \rightarrow x} \varphi(z)$, in the case of a real-valued function φ defined on a topological space A , may be immediately adapted to the case where φ is defined on the underlying set of a filtered set A .

Definition 1.12 If A is a filtered set, Y is a topological space, $\varphi \in \text{hom}_{\text{Set}}(A, Y)$, and $y \in Y$, we say that y is the limiting value of φ along the filter Z , and write

$$\lim_Z \varphi = y \tag{1.26}$$

if $\varphi : A \rightarrow (Y, N_Y(y))$ is a filter-homomorphism.

The meaning of the condition that $\varphi : A \rightarrow (Y, N_Y(y))$ is a filter-homomorphism is that for each $U \in N_Y(y)$, the set $\{x \in A : \varphi(x) \in U\}$ belongs to Z .

Definition 1.13 If $\varphi : A \rightarrow \mathbb{R}$ is real-valued, we say that $\lim_Z \varphi = \pm\infty$ if $\varphi : A \rightarrow (\mathbb{R}, N_{\mathbb{R}}(\pm\infty))$ is a filter-homomorphism.

1.2.6 The Functional Convergence Class Induced by a Filter

Example (v) The fifth example of a functional convergence class is the one induced by the choice of a filter on A . In Theorem 3.2 we show that if Z is a filter on A and we define $c_A(Z)$ by

$$c_A(Z) \stackrel{\text{def}}{=} \left\{ (y, \varphi) \in \mathbb{R} \times \text{hom}_{\text{Set}}(A, \mathbb{R}) : \lim_Z \varphi = y \right\}, \tag{1.27}$$

(where $\lim_Z \varphi = y$ denotes convergence of $\varphi : A \rightarrow \mathbb{R}$ along the filter Z , defined in Sect. 1.2.5), then $c_A(Z)$ is a functional convergence class.

1.3 A Hierarchy of Limiting Processes

The second contribution of this paper is the clarification of the hierarchical relations between the limiting processes described in **Examples (i)–(v)**. More precisely, we will prove the following results.

(Theorem 3.7) Each functional convergence class may be uniquely represented in the form (v). In other words, the limiting process associated to filters recaptures the abstract notion of functional convergence class.

(Theorem 3.34) Each functional convergence class may be represented in the form (iv), albeit not uniquely.

(Theorem 3.37) Each functional convergence class may be represented in the form (iii), albeit not uniquely.

(Theorem 3.36) Not every functional convergence class may be represented in the form (i).

(Theorem 3.29) Not every functional convergence class may be represented in the form (ii). For example, nontangential convergence, that plays a leading role in the study of the boundary behavior of harmonic functions, cannot be represented in this form.

1.4 Applications to the Problem of the Differentiation of Integrals (I)

We are now ready to give a second bird’s eye view of the content of this paper, where we present a reformulation of de Possel’s approach in terms of filters. This reformulation is inspired by the following three implications of the results described in Sect. 1.2.

(A) The lack of uniqueness in Theorem 3.37 means that it is preferable to represent a given functional convergence class in terms of convergence along a filter, as in Sect. 1.2.6 [Example (v)], rather than in terms of convergence along a Moore–Smith sequence, as in (1.22) [Example (iii)], since the exceptional set in the Generalized Lebesgue Differentiation Theorem should not depend on the particular representation (i.e., on the particular Moore–Smith sequence) chosen.

(B) There is no gain in generality in the limiting process described in Example (iv), with respect to the one in Example (iii).

(C) The limiting process produced by filters, described in Example (v), has wider scope than the one produced by collections of sequences, described in Example (i).

The following set-up is based on these implications.

1.4.1 The Set-Up Based on Filters

Since the phenomena of interest in the present work are invariant under rescaling, the results we obtain for *complete probability spaces* also hold for *complete measure spaces* endowed with a *finite* measure (see Sect. 2). Hence, unless otherwise stated, we assume that (X, \mathcal{M}, ω) is a *complete probability space*.

Denote by $\mathcal{F}(\mathcal{A}(X))$ the collection of all filters on $\mathcal{A}(X)$.

Definition 1.14 A *family of differentiation filters (based on X)* is a function

$$\mathbf{G} : X \rightarrow \mathcal{F}(\mathcal{A}(X)) \tag{1.28}$$

which associates to each $x \in X$ a filter $\mathbf{G}(x) \in \mathcal{F}(\mathcal{A}(X))$.

Definition 1.15 We say that a family of differentiation filters (1.28) *differentiates a function* $f \in \mathcal{L}^1(X)$ *at* $x \in X$ if

$$f(x) = \lim_{\mathbf{G}(x)} f_\omega. \tag{1.29}$$

A family of differentiation filters \mathbf{G} as in (1.28) *differentiates* $f \in L^1(X)$ if the limiting value

$$\lim_{\mathbf{G}(x)} f_\omega$$

exists for a.e. $x \in X$ and yields a representative of f . If $\mathcal{R} \subset L^1(X)$, we say that \mathbf{G} *differentiates* \mathcal{R} if \mathbf{G} *differentiates* f for each $f \in \mathcal{R}$.

1.4.2 On the Differentiation of the Class of All Measurable Sets (I)

Perhaps the simplest class of integrable functions is given by the following one, associated to the σ -algebra of measurable sets:

$$\{\mathbb{1}_R : R \in \mathcal{M}\}. \tag{1.30}$$

If $R \in \mathcal{M}$ has measure zero, then every family of differentiation filters (1.28) differentiates $\mathbb{1}_R$. Hence it suffices to restrict attention to $\{\mathbb{1}_R : R \in \mathcal{A}(X)\}$.

Definition 1.16 If \mathbf{G} is a family of differentiation filters, as in (1.28), we say that \mathbf{G} differentiates all measurable sets if, for each $R \in \mathcal{A}(X)$, \mathbf{G} differentiates $\mathbb{1}_R$.

Definition 1.17 A lifting of (X, \mathcal{M}, ω) is a Boolean homomorphism $\theta : \mathbf{M} \rightarrow \mathcal{M}$ which is a right inverse of the canonical projection of \mathcal{M} onto \mathbf{M} , described in (1.1).

Hence a lifting $\theta : \mathbf{M} \rightarrow \mathcal{M}$ of (X, \mathcal{M}, ω) amounts to the choice of a representative of the measure class $\pi(Q)$, for each $Q \in \mathcal{M}$, which preserves the Boolean structure of \mathbf{M} , and hence establishes a Boolean isomorphism between the measure algebra of (X, \mathcal{M}, ω) and some subalgebra of \mathcal{M} .

The problem of the differentiation of the class of all integrable functions is clarified by the following result, whose proof may be obtained by adapting the techniques used in [20].

Theorem 1.18 *If (X, \mathcal{M}, ω) is a complete probability space, then a necessary and sufficient condition for the existence of a family of differentiation filters $\mathbf{G} : X \rightarrow \mathcal{F}(\mathcal{A}(X))$, which differentiates all integrable functions, is the existence of a lifting of (X, \mathcal{M}, ω) .*

The following result, coupled with Theorem 1.18, shows that there exists a family of differentiation filters $\mathbf{G} : X \rightarrow \mathcal{F}(\mathcal{A}(X))$ which differentiates all integrable functions.

Theorem 1.19 (Von Neumann–Maharam) *Every complete probability space (X, \mathcal{M}, ω) admits a lifting.*

Theorem 1.19 has a “curious history,” as Fremlin puts it, which is recounted in [15, pp. 162–174], where a proof is given. The proof of Theorem 1.19 must necessarily involve the Axiom of Choice [6].

1.4.3 Measurability Issues (I)

In dealing with a general family of differentiation filters $\mathbf{G} : X \rightarrow \mathcal{F}(\mathcal{A}(X))$, we are faced with certain measurability issues, as we will see in more detail in Sect. 13. We will treat these difficulties using the same devices which de Possel used in his work.

For the collection of all subsets of a set A we use the standard notation

$$\mathcal{P}(A) \stackrel{\text{def}}{=} \{\mathbf{b} : \mathbf{b} \subset A\}.$$

In the study of filters the empty set is a nuisance, and in order to simplify many statements which otherwise would be too involved, we introduce the following notation for the collection of *nonempty* subsets of a given set:

$$\mathcal{P}_\bullet(A) \stackrel{\text{def}}{=} \{b \in \mathcal{P}(A) : b \neq \emptyset\}. \tag{1.31}$$

Definition 1.20 If (X, \mathcal{M}, ω) is a probability space, the *outer measure induced by ω* is defined by

$$\omega^* : \mathcal{P}(X) \rightarrow [0, 1],$$

where, if $Q \in \mathcal{P}(X)$, then

$$\omega^*(Q) \stackrel{\text{def}}{=} \inf\{\omega(R) : R \supset Q, R \in \mathcal{M}\}.$$

The following result is well known.

Lemma 1.21 For each $Q \in \mathcal{P}(X)$ there exists a set $R \in \mathcal{M}$ such that $Q \subset R$ and $\omega^*(Q) = \omega(R)$.

Definition 1.22 If $Q \in \mathcal{P}(X)$ and R has the property described in Lemma 1.21, we say that R is a *measurable representative of Q* , and write

$$\mathcal{M}[Q] \stackrel{\text{def}}{=} \{R \in \mathcal{M} : R \text{ is a measurable representative of } Q\}.$$

Definition 1.23

$$\mathcal{A}^*(X) \stackrel{\text{def}}{=} \{Q \in \mathcal{P}_\bullet(X) : \omega^*(Q) > 0\}$$

and if $Q \in \mathcal{A}^*(X)$ then

$$\mathcal{A}^*(Q) \stackrel{\text{def}}{=} \{R \in \mathcal{P}_\bullet(Q) : \omega^*(R) > 0\}.$$

1.4.4 A Criterion for the Differentiation of Integrable Functions

Assume that $\mathbf{G} : X \rightarrow \mathcal{F}(\mathcal{A}(X))$ is a family of differentiation filters, $f \in \mathcal{L}^1(X)$, $\alpha \in \mathbb{R}$, and $Q \in \mathcal{A}^*(X)$.

Definition 1.24 We say that \mathbf{G} is *adapted to f on Q above α* (resp. *below α*) if

$$\forall x \in Q \ \forall \mathbf{b} \in \mathbf{G}(x) \ \exists R \in \mathbf{b} \ f_\omega[R] > \alpha \text{ [resp. } f_\omega[R] < \alpha] \tag{1.32}$$

Definition 1.25 We say that *the mean-value of f over Q lies above α* (resp. *below α*) if there exists $Q' \in \mathcal{M}[Q]$ such that $f_\omega[Q'] > \alpha$ [resp. $f_\omega[Q'] < \alpha$].

Definition 1.26 We say that $\mathbf{G} : X \rightarrow \mathcal{F}(\mathcal{A}(X))$ and $f \in \mathcal{L}^1(X)$ are *compatible* if

- (a) for all $Q \in \mathcal{A}^*(X)$ and for all $\alpha \in \mathbb{R}$, if \mathbf{G} is adapted to f on Q above α , then the mean-value of f on Q lies above α ,
- (b) for all $Q \in \mathcal{A}^*(X)$ and for all $\alpha \in \mathbb{R}$, if \mathbf{G} is adapted to f on Q below α , then the mean-value of f on Q lies below α .

Theorem 1.27 *If $\mathbf{G} : X \rightarrow \mathcal{F}(\mathcal{A}(X))$ and $f \in \mathcal{L}^1(X)$ are compatible then \mathbf{G} differentiates f .*

Proof The proof is given in Sect. 13. □

1.4.5 On the Differentiation of the Class of All Measurable Sets (II)

The following theorem is akin to a result due to Busemann and Feller in the context of the so-called *differentiation bases* [7].

Theorem 1.28 *If $\mathbf{G} : X \rightarrow \mathcal{F}(\mathcal{A}(X))$ is a family of differentiation filters, then the following conditions are equivalent:*

- (i) \mathbf{G} differentiates $L^\infty(X)$.
- (ii) \mathbf{G} differentiates all measurable sets.
- (iii) $\forall R \in \mathcal{A}(X)$, for a.e. $x \in R$, for each $\epsilon \in (0, 1)$ there exists $\mathbf{b} \in \mathbf{G}(x)$ such that $\epsilon < \tilde{\omega}(R|Q)$ for each $Q \in \mathbf{b}$.

Proof The proof is based on Theorem 1.27 and on an appropriate adaptation of a covering result due to de Possel. Details are omitted. □

2 Notation

The sets A, B overlap if $A \cap B \neq \emptyset$. We let $B \setminus A \stackrel{\text{def}}{=} \{x : x \in B, x \notin A\}$ and $\complement A \stackrel{\text{def}}{=} X \setminus A$. The notation $A \subset B$ (for sets A, B , with $A, B \subset X$) means that, for all $x \in X$, $x \in A \Rightarrow x \in B$.

The identity function $\mathbf{I}_X : X \rightarrow X$ is defined by $\mathbf{I}_X(x) \stackrel{\text{def}}{=} x$ for all $x \in X$.

The extended real line $\mathbb{R} \equiv [-\infty, +\infty]$ is defined in the familiar way [4, IV.13]. It is a compact topological space which contains \mathbb{R} as an open subset.

2.1 Sets, Collections, and Families

Since *filters* are elements of $\mathcal{P}_\bullet(\mathcal{P}_\bullet(A))$, in order to avoid confusion between the different levels in the hierarchy of powersets, we find it useful to reserve the term set (of points) to a generic element of $\mathcal{P}(A)$, and call collection (of sets) a generic element of $\mathcal{P}(\mathcal{P}(A))$; an element of $\mathcal{P}(\mathcal{P}(\mathcal{P}(A)))$ is called a family (of collections). We only deal with sets A for which $x, r \in A \Rightarrow x \notin r$.

2.1.1 Direct Image and Inverse Image Notation

We also find it useful, for the sake of clarity, to adopt the following notation from [22, p. 154], and write, if $f \in \text{hom}_{\text{Set}}(A, Z)$, $B \in \mathcal{P}(A)$, and $C \in \mathcal{P}(Z)$,

$$f_*(B) \stackrel{\text{def}}{=} \{z \in Z : \exists b \in B, z = f(b)\} \quad \text{and} \quad f^*(C) \stackrel{\text{def}}{=} \{a \in A : f(a) \in C\}.$$

In particular, $f_* : \mathcal{P}(A) \rightarrow \mathcal{P}(Z)$ and, by the same token, $(f_*)_* : \mathcal{P}(\mathcal{P}(A)) \rightarrow \mathcal{P}(\mathcal{P}(Z))$. The restriction of $f_* : \mathcal{P}(A) \rightarrow \mathcal{P}(Z)$ to $\mathcal{P}_\bullet(A)$ will also be denoted by f_* (with a slight abuse of language). Hence

$$f_* : \mathcal{P}_\bullet(A) \rightarrow \mathcal{P}_\bullet(Z). \tag{2.1}$$

2.2 Measure-Theoretic Notation

A measure space (X, \mathcal{M}, ω) is a nonempty set X endowed with a σ -algebra $\mathcal{M} \subset \mathcal{P}(X)$ of subsets and a set-function (called a measure) $\omega : \mathcal{M} \rightarrow [0, +\infty]$ which is countably additive and whose value at \emptyset is zero [29, p. 217]. The measure ω is said to be finite if $\omega(Q) \in [0, +\infty)$ for all $Q \in \mathcal{M}$. A probability space is a measure space (X, \mathcal{M}, ω) with $\omega(X) = 1$.

2.2.1 Null Sets and Derived Notions

A null set in a measure space (X, \mathcal{M}, ω) is a set $Q \in \mathcal{M}$ such that $\omega(Q) = 0$. The measure space (X, \mathcal{M}, ω) is complete if each subset of a null set is also a null set.

In a complete probability space (X, \mathcal{M}, ω) , the σ -ideal of null subsets is the collection

$$\mathcal{N} \stackrel{\text{def}}{=} \{R : R \in \mathcal{M}, \omega(R) = 0\}. \tag{2.2}$$

The collection \mathcal{N} is called a σ -ideal because it has the following properties: (i) it contains the empty set; (ii) if $Q \in \mathcal{N}$ and $R \subset Q$ then $R \in \mathcal{N}$; (iii) it is closed under countable unions [14, p. 16].

It is useful to introduce the binary relations “ \subset_ω ” and “ $\stackrel{\omega}{\approx}$ ” between subsets of a measure space, which are obtained from the inclusion relations “ \subset ” and “ $=$ ” by replacing the empty set with *null sets*. If $Q, R \subset X$, we say that Q is **a.e. contained** in R , and write $Q \subset_\omega R$ if $Q \setminus R \in \mathcal{N}$: This means that almost all of Q is a subset of R . We say that the sets Q, R are **almost everywhere equal**, and write $Q \stackrel{\omega}{\approx} R$ if $Q \subset_\omega R$ and $R \subset_\omega Q$. Observe that $\stackrel{\omega}{\approx}$ is an equivalence relation on \mathcal{M} and that $Q \stackrel{\omega}{\approx} R$ if and only if the symmetric difference $Q \Delta R \stackrel{\text{def}}{=} (Q \setminus R) \cup (R \setminus Q)$ is a null set. We say that R is **a.e. disjoint** from Q if $Q \cap R \stackrel{\omega}{\approx} \emptyset$, i.e., if $Q \cap R$ is a null set.

A set $Q \subset X$ has **full measure** if $\complement Q$ is a null set. A property holds a.e. (almost everywhere) if it holds on a set of full measure. A set $Q \subset R$ has full measure in R if $Q \cup \complement R$ has full measure.

In a complete probability space (X, \mathcal{M}, ω) , the collection of measurable sets of full measure is defined as follows:

$$\mathcal{M}_\omega^F \stackrel{\text{def}}{=} \{F : F \in \mathcal{M}, \omega(\mathbb{C}F) = 0\}. \tag{2.3}$$

The collection \mathcal{M}_ω^F is a *filter on X*. Observe that if $Q, R \in \mathcal{M}$, then $Q \stackrel{\omega}{=} R$ if and only if there exists $F \in \mathcal{M}_\omega^F$ such that $F \cap Q = F \cap R$.

3 Functional Convergence Classes

The goal of this section is to provide some of the proofs of results concerning the abstract notion of *functional convergence class*, introduced in Sect. 1.2 and show why a priori it is preferable to rephrase the work of R. de Possel in terms of *filters* rather than in terms of the choice of collections of sequences given in (1.12), as in the original approach by R. de Possel. We will also show that an approach based on the notion of filters appears to be preferable also with respect to a variant of (1.12) where instead of sequences one uses *Moore–Smith sequences*. Indeed, the lack of a uniqueness (in the representation of a given *functional convergence class* in terms of *convergence along a Moore–Smith sequence*) gives rise to ambiguities in the notion of *exceptional set*.

3.1 Functional Convergence Classes

We now show that the notion of limiting value along a filter on A yields a functional convergence class on A .

Definition 3.1 If A is a nonempty set and $Z \in \mathcal{F}(A)$, define $c_A(Z)$ as in (1.27).

Theorem 3.2 *If $Z \in \mathcal{F}(A)$ then $c_A(Z)$ is a functional convergence class, and hence (1.27) defines a map*

$$c_A : \mathcal{F}(A) \rightarrow \text{FCC}(A). \tag{3.1}$$

Proof If $\varphi \in \text{hom}_{\text{set}}(A, \mathbb{R})$ is identically equal to $y \in \mathbb{R}$, then $\varphi^*(U) \equiv A$ for each $U \in \mathbb{N}_{\mathbb{R}}(y)$, hence $\lim_Z \varphi = y$, i.e., $(y, \varphi) \in c_A(Z)$. If $y \in \mathbb{R}$, define $\varphi \in \text{hom}_{\text{set}}(A, \mathbb{R})$ by $\varphi(x) \stackrel{\text{def}}{=} y + 1$ for each $x \in A$. Observe that if $U \stackrel{\text{def}}{=} (y - \frac{1}{2}, y + \frac{1}{2})$ then $U \in \mathbb{N}_{\mathbb{R}}(y)$ and $(\varphi)^*(U) = \emptyset$, thus $\lim_Z \varphi = y$ does *not* hold, hence $(y, \varphi) \notin c_A(Z)$. We have proved that $c_A(Z)$ is a functional convergence relation.

If $(y, \varphi) \in c_A(Z)$, i.e., $\lim_Z \varphi = y$, and $r \in \mathbb{R}$, let $\beta \stackrel{\text{def}}{=} r + \varphi$, and $U \in \mathbb{N}_{\mathbb{R}}(r + y)$. Define $U - r \stackrel{\text{def}}{=} \{x - r : x \in U\}$. Then $U - r \in \mathbb{N}_{\mathbb{R}}(y)$. Observe that $\beta^*(U) = \varphi^*(U - r)$, since $\beta(x) = r + \varphi(x) \in U$ if and only if $\varphi(x) \in U - r$. Then $\lim_Z \varphi = y$ implies that $\varphi^*(U - r) \in Z$, and since $\beta^*(U) = \varphi^*(U - r)$, it follows that $\beta^*(U) \in Z$. Since $U \in \mathbb{N}_{\mathbb{R}}(r + y)$ is arbitrary, it follows that $\lim_Z \beta = r + y$, i.e., $c_A(Z)$ is translation invariant.

Let $\beta \in \text{hom}_{\text{Set}}(A, \mathbb{R})$ and assume that, for each $U \in N_{\mathbb{R}}(y)$, there exists $V \in N_{\mathbb{R}}(y)$ and $\varphi \in \text{hom}_{\text{Set}}(A, \mathbb{R})$ such that $(y, \varphi) \in c_A(Z)$ and $\varphi^*(V) \subset \beta^*(U)$. Observe that $\varphi^*(V) \in Z$, since $\text{lim}_Z \varphi = y$, and hence $\beta^*(U) \in Z$. Thus we have proved that $\beta^*(U) \in Z$ for each $U \in N_{\mathbb{R}}(y)$, and this means that $\text{lim}_Z \beta = y$, i.e., $(y, \beta) \in c_A(Z)$. Hence $c_A(Z)$ is local.

Assume that $y \in \mathbb{R}$, $\text{lim}_Z \varphi = y$, $\text{lim}_Z \beta = y$, and $\gamma \in \text{hom}_{\text{Set}}(A, \mathbb{R})$. Suppose that γ has the property that, for some $U \in N_{\mathbb{R}}(y)$, $\gamma(x) \in \{\varphi(x), \beta(x)\}$ for each $x \in \varphi^*(U) \cap \beta^*(U)$. Let $V \in N_{\mathbb{R}}(y)$. Then

$$\gamma^*(V) \supset \gamma^*(V \cap U) \supset \varphi^*(V \cap U) \cap \beta^*(V \cap U)$$

and since $\varphi^*(V \cap U)$ and $\beta^*(V \cap U)$ both belong to Z , and Z is a filter, it follows that $\gamma^*(V) \in Z$. Since $V \in N_{\mathbb{R}}(y)$ is arbitrary, it follows that $\text{lim}_Z \gamma = y$. Hence $c_A(Z)$ is hereditary. □

In the following section, we will show that the map c_A in (3.1) is one-to-one and onto.

3.2 A Representation Theorem for Functional Convergence Classes

Definition 3.3 If A is a nonempty set and $\mathcal{F} \in \text{FCC}(A)$, then define by

$$s_A(\mathcal{F}) \stackrel{\text{def}}{=} \{b : b \subset A, \exists U \in N_{\mathbb{R}}(0), \exists (0, \varphi) \in \mathcal{F} \text{ such that } b = \varphi^*(U)\}. \quad (3.2)$$

Lemma 3.4 If $\mathcal{F} \in \text{FCC}(A)$ then $s_A(\mathcal{F})$ is a filter on A , and (3.2) defines a function

$$s_A : \text{FCC}(A) \rightarrow \mathcal{F}(A). \quad (3.3)$$

Proof It suffices to show that $s_A(\mathcal{F})$ is a filter. Let $\mathcal{F}(0) \stackrel{\text{def}}{=} \{(0, \varphi) \in \mathcal{F}\}$. Observe that $\mathcal{F}(0)$ is not empty, since it contains at least the constant function identically equal to 0. Observe that $s_A(\mathcal{F}) = \{\varphi^*(U) : U \in N_{\mathbb{R}}(0), \varphi \in \mathcal{F}(0)\}$.

Firstly, observe that $s_A(\mathcal{F})$ is not empty, since it contains A , because $\mathcal{F}(0)$ contains the constant function identically equal to 0.

Secondly, we show that $\emptyset \notin s_A(\mathcal{F})$. We proceed by contradiction and assume that there exists $V \in N_{\mathbb{R}}(0)$ and $\varphi \in \mathcal{F}(0)$ such that $(\varphi)^*(V) = \emptyset$. Let $\beta \in \text{hom}_{\text{Set}}(A, \mathbb{R})$ and observe that (1.20) holds for $y = 0$. Since \mathcal{F} is local, it follows that $\beta \in \mathcal{F}(0)$. Hence we have proved that $\text{hom}_{\text{Set}}(A, \mathbb{R}) = \mathcal{F}(0)$. Since \mathcal{F} is translation invariant, it follows that $\mathcal{F} = \mathbb{R} \times \text{hom}_{\text{Set}}(A, \mathbb{R})$, a contradiction.

We now show that

$$\text{if } b \in s_A(\mathcal{F}) \text{ and } c \supseteq b \text{ then } c \in s_A(\mathcal{F}). \quad (3.4)$$

Indeed, if $\mathfrak{b} \in s_A(\mathcal{F})$, there exists $V \in \mathbb{N}_{\mathbb{R}}(0)$ and $\varphi \in \mathcal{F}(0)$ and $\mathfrak{b} = \varphi^*(V)$. Observe that, under these hypotheses, $V \subsetneq \mathbb{R}$. Choose $z \in \mathbb{R} \setminus V$. Define $\beta \in \text{hom}_{\text{set}}(A, \mathbb{R})$ as follows: If $x \in c$ then $\beta(x) \stackrel{\text{def}}{=} 0$; if $x \in A \setminus c$ then $\beta(x) \stackrel{\text{def}}{=} z$. Then $\beta^*(U)$ is either equal to c or it is equal to A . In either case, $\beta^*(U)$ contains $\mathfrak{b} = \varphi^*(V)$. Since \mathcal{F} is local, it follows that $(0, \beta) \in \mathcal{F}$. Observe that $\beta^*(V) = c$. Hence $c \in s_A(\mathcal{F})$, and the proof of (3.4) is complete.

Now, assume that $U \in \mathbb{N}_{\mathbb{R}}(0)$. We claim that

$$\text{if } \varphi, \beta \in \mathcal{F}(0) \text{ then } \varphi^*(U) \cap \beta^*(U) \in s_A(\mathcal{F}). \tag{3.5}$$

Indeed, if $U = \mathbb{R}$ then $\varphi^*(U) = \beta^*(U) = A$, hence $\varphi^*(U) \cap \beta^*(U) = A$ and we know already that $A \in s_A(\mathcal{F})$. If $U \subsetneq \mathbb{R}$, let $z \in \mathbb{R} \setminus U$ and define $\gamma \in \text{hom}_{\text{set}}(A, \mathbb{R})$ as follows: If $x \in \varphi^*(U) \cap \beta^*(U)$ then $\gamma(x) \stackrel{\text{def}}{=} \beta(x)$; if $x \in A \setminus (\varphi^*(U) \cap \beta^*(U))$ then $\gamma(x) \stackrel{\text{def}}{=} z$. Observe that $\gamma^*(U) = \varphi^*(U) \cap \beta^*(U)$. Moreover, if $x \in \varphi^*(U) \cap \beta^*(U)$ then $\gamma(x) \in \{\varphi(x), \beta(x)\}$, hence $\gamma \in \mathcal{F}(0)$, since \mathcal{F} is hereditary. It follows that $\varphi^*(U) \cap \beta^*(U) \in s_A(\mathcal{F})$.

Finally, we prove that

$$\text{if } \mathfrak{b}, c \in s_A(\mathcal{F}) \text{ then } \mathfrak{b} \cap c \in s_A(\mathcal{F}). \tag{3.6}$$

Indeed, if $\mathfrak{b}, c \in s_A(\mathcal{F})$ then there exists $U, V \in \mathbb{N}_{\mathbb{R}}(0)$ and $\varphi, \beta \in \mathcal{F}(0)$ such that $\mathfrak{b} = \varphi^*(U)$ and $c = \beta^*(V)$. Then

$$\mathfrak{b} \cap c = \varphi^*(U) \cap \beta^*(V) \supset \varphi^*(U \cap V) \cap \beta^*(U \cap V) \quad \text{and} \quad U \cap V \in \mathbb{N}_{\mathbb{R}}(0).$$

Hence (3.6) follows from (3.4) and (3.5). The proof that $s_A(\mathcal{F})$ is a filter is complete. □

Lemma 3.5 *The map (3.3) is a left inverse of (3.1).*

Proof We have to show that if $Z \in \mathcal{F}(A)$ then

$$Z = s_A(c_A(Z)). \tag{3.7}$$

If $\mathfrak{b} \in Z$ define $\varphi \in \text{hom}_{\text{set}}(A, \mathbb{R})$ as follows: if $x \in \mathfrak{b}$ then $\varphi(x) \stackrel{\text{def}}{=} 0$; if $x \in A \setminus \mathfrak{b}$ then $\varphi(x) \stackrel{\text{def}}{=} 1$. Observe that $\lim_Z \varphi = 0$. Indeed, if $U \in \mathbb{N}_{\mathbb{R}}(0)$ then $\varphi^*(U)$ is either \mathfrak{b} or A , and hence it belongs to Z . It follows that $(0, \varphi) \in c_A(Z)$. Now observe that $\mathfrak{b} = \varphi^*(-1/2, 1/2)$, thus $\mathfrak{b} \in s_A(c_A(Z))$. Hence we have proved that $Z \subset s_A(c_A(Z))$. Now assume that $\mathfrak{b} \in s_A(c_A(Z))$. Then there exists φ and U , where $(0, \varphi) \in c_A(Z)$ and $U \in \mathbb{N}_{\mathbb{R}}(0)$, such that $\mathfrak{b} = \varphi^*(U)$. The fact that $(0, \varphi) \in c_A(Z)$ implies that $\lim_Z \varphi = 0$, hence it implies that $\varphi^*(U) \in Z$, and thus $\mathfrak{b} \in Z$. Hence we have proved that $Z \supset s_A(c_A(Z))$, and the proof is complete. □

Lemma 3.6 *The map (3.3) is a right inverse of (3.1).*

Proof We have to show that if $\mathcal{F} \in \text{FCC}(\mathbb{A})$ then

$$\mathcal{F} = c_{\mathbb{A}}(s_{\mathbb{A}}(\mathcal{F})).$$

We claim that

$$(0, \varphi) \in \mathcal{F} \Rightarrow (0, \varphi) \in c_{\mathbb{A}}(s_{\mathbb{A}}(\mathcal{F})). \tag{3.8}$$

Indeed, if $(0, \varphi) \in \mathcal{F}$ then, for each $U \in N_{\mathbb{R}}(0)$, it follows that $\varphi^*(U) \in s_{\mathbb{A}}(\mathcal{F})$, hence $\lim_{s_{\mathbb{A}}(\mathcal{F})} \varphi = 0$ and thus $(0, \varphi) \in c_{\mathbb{A}}(s_{\mathbb{A}}(\mathcal{F}))$, hence (3.8) holds. Now, if $(y, \varphi) \in \mathcal{F}$ then $(0, \varphi - y) \in \mathcal{F}$, since \mathcal{F} is translation invariant, hence (3.8) implies that $(0, \varphi - y) \in c_{\mathbb{A}}(s_{\mathbb{A}}(\mathcal{F}))$, and since $c_{\mathbb{A}}(s_{\mathbb{A}}(\mathcal{F}))$ is translation invariant, it follows that $(y, \varphi) \in c_{\mathbb{A}}(s_{\mathbb{A}}(\mathcal{F}))$. Hence we have proved that $\mathcal{F} \subset c_{\mathbb{A}}(s_{\mathbb{A}}(\mathcal{F}))$.

Assume that $(y, \beta) \in c_{\mathbb{A}}(s_{\mathbb{A}}(\mathcal{F}))$. Then $\lim_{s_{\mathbb{A}}(\mathcal{F})} \beta = y$. Hence $\beta^*(U) \in s_{\mathbb{A}}(\mathcal{F})$ for each $U \in N_{\mathbb{R}}(y)$. This means that for each $U \in N_{\mathbb{R}}(y)$ there exists $W \in N_{\mathbb{R}}(0)$ and $\gamma \in \text{hom}_{\text{Set}}(\mathbb{A}, \mathbb{R})$ such that $(0, \gamma) \in \mathcal{F}$ and $\gamma^*(W) = \beta^*(U)$. Since \mathcal{F} is translation invariant, it follows that for each $U \in N_{\mathbb{R}}(y)$ there exists $V \in N_{\mathbb{R}}(y)$ and $\varphi \in \text{hom}_{\text{Set}}(\mathbb{A}, \mathbb{R})$ such that $(y, \varphi) \in \mathcal{F}$ and $\varphi^*(V) = \beta^*(U)$. Since \mathcal{F} is local, it follows that $(y, \beta) \in \mathcal{F}$. Hence we have proved that $c_{\mathbb{A}}(s_{\mathbb{A}}(\mathcal{F})) \subset \mathcal{F}$, and the proof is complete. \square

Theorem 3.7 *If $\mathcal{F} \in \text{FCC}(\mathbb{A})$ then there exists a unique $Z \in \mathcal{F}(\mathbb{A})$ such that $c_{\mathbb{A}}(Z) = \mathcal{F}$.*

Proof It suffices to apply Lemmas 3.5 and 3.6. \square

3.3 Moore–Smith Sequences

In 1915 and 1922 Eliakim Hastings Moore and Herman Lyle Smith attempted to subsume different limiting processes under the same notion [23, 24]. They were motivated by the following heuristic principle:

The existence of analogies between central features of various theories implies the existence of a more fundamental general theory embracing the special theories as particular instances and unifying them as to those central features. [23, p. 628]

We now present a list of examples which Moore and Smith had in mind, or which one should keep in mind in order to gain a better appreciation of their contribution. In these examples, marked with their initials, φ denotes a function $\mathbb{A} \rightarrow \mathbb{R}$.

(Example MS 1) $\mathbb{A} = \mathbb{N}$, hence φ is a sequence of real numbers, and $\lim_{n \rightarrow +\infty} \varphi(n) = y$ in the usual sense.

(Example MS 2) $\mathbb{A} = (-\infty, a) \cup (a, +\infty)$, with $a \in \mathbb{R}$, and $\lim_{x \rightarrow a} \varphi(x) = y$ in the usual sense

(Example MS 3) \mathbb{A} is the collection of tagged partitions of the interval $[0, 1]$, φ encodes the Riemann sums of a given function $f : [0, 1] \rightarrow \mathbb{R}$, and the limiting

process to which φ is subject yields as a limiting value the Riemann integral of f , i.e., $\lim \varphi = \int_0^1 f(x) dx$.

In their work, they created the notion of *Moore–Smith sequence* (see below), and, in so doing, they introduced the notion of a *direction*. As is customary, if R is a binary relation on a set S , i.e., a subset of $S \times S$, we write jRk instead of $(j, k) \in R$.

Definition 3.8 A preorder R on a nonempty set S is a reflexive and transitive binary relation on S , i.e., a subset of $S \times S$ with the following properties:

- (R) jRj for each $j \in S$ (reflexivity);
- (T) if jRk and kRl then jRl (transitivity).

A preordered set $A \equiv (A_{\text{Set}}, R_A)$ is a set A_{Set} endowed with a preorder R_A .

Definition 3.9 A partial order R on a nonempty set S is a preorder R on S which also satisfies the following condition:

- (A) if jRk and kRj then $j = k$ (antisymmetry).

A poset A is a set A_{Set} endowed with a partial order R_A .

Example 3.10 $\mathcal{P}(A)$ is a poset under set inclusion. Every subset of a poset is a poset under the restriction of the binary relation.

Definition 3.11 If A is a preordered set and $x \in A$, the tail in A from x is the set

$$\text{tail}_A(x) \stackrel{\text{def}}{=} \{r \in A : x R_A r\}. \tag{3.9}$$

A subset $T \subset A$ is called a *tail in A* if $T = \text{tail}_A(x)$ for some $x \in A$.

Definition 3.12 A subset $T \subset A$ is called final in A if it contains some tail, and the collection of all final sets in A is

$$\text{Fin}[A] \stackrel{\text{def}}{=} \{\mathbf{b} \in \mathcal{P}_\bullet(A) : \exists x \in A, \text{tail}_A(x) \subset \mathbf{b}\}. \tag{3.10}$$

We may write $\text{Fin}[R]$ instead of $\text{Fin}[A]$ in case we need to emphasize the role of the direction R .

The notion of *tail*, and the associated notion of *final set*, display their full power only if some other assumptions are made on the preorder.

Definition 3.13 A direction on a set S is a preorder R on S such that, for each $j, k \in S$, there exists an element $l \in S$ such that jRl and kRl . We define

$$\text{dir}(S) \stackrel{\text{def}}{=} \{R \in \mathcal{P}_\bullet(S \times S) : R \text{ is a direction on } S\}. \tag{3.11}$$

A directed set $A = (A_{\text{Set}}, R_A)$ is a set A_{Set} endowed with a direction R_A on A_{Set} .

We will see that *A is a directed set if and only if $\text{Fin}[A]$ is a filter on A.*

Example 3.14 \mathbb{N} is a directed set under the natural order: $j \leq k$ if $k - j \geq 0$.

The following result shows that reverse inclusion in a filter is a direction.

Example 3.15 If $Z \in \mathcal{F}(A)$, then reverse inclusion between sets (\supset) is a direction on Z . In particular, if Θ is a topology on A and $x \in A$, then $(N_\Theta(x), \supset)$ is a directed set.

Directed sets serve as domains of definition of *Moore–Smith sequences*. It is useful to emphasize the role of the codomain, as in the following definition.

Definition 3.16 If Y is a nonempty set, we define

$$\mathcal{S}() Y \stackrel{\text{def}}{=} \{ \omega : \exists \text{ a directed set } A, \omega \in \text{hom}_{\text{Set}}(A, Y) \} \tag{3.12}$$

The elements of $\mathcal{S}(Y)$ are called *Y-valued Moore–Smith sequences*. The directed set which appears in (3.12) is called (with slight abuse of language) the *direction of* ω .

Observe that

$$Y \hookrightarrow \text{hom}_{\text{Set}}(\mathbb{N}, Y) \quad \text{and} \quad \text{hom}_{\text{Set}}(\mathbb{N}, Y) \subset \mathcal{S}(Y) \tag{3.13}$$

i.e., each element of Y may be seen as a constant sequence, and each sequence is a Moore–Smith sequence.

Lemma 3.17 *The map $Y \mapsto \mathcal{S}(Y)$ is the object function of a functor $\mathcal{S} : \text{Set} \rightarrow \text{Set}$. The mapping function of \mathcal{S} maps $f \in \text{hom}_{\text{Set}}(Y, Y')$, where Y, Y' are two sets, to the function $f_\circ : \mathcal{S}(Y) \rightarrow \mathcal{S}(Y')$ which maps $\omega \in \mathcal{S}(Y)$ to $f \circ \omega \in \mathcal{S}(Y')$, where $f \circ \omega$ is the composition of functions.*

Proof The proof follows at once from the fact that the composition of functions is associative whenever defined, and $1_Y \circ \omega = \omega$. For background, see [22, p. 501]. \square

Observe that a direction is not necessarily a partial order, since antisymmetry may fail. An *antisymmetric direction* on a set A is a direction R on A for which if jRk and kRj then $j = k$.

3.4 Limiting Values of Moore–Smith Sequences

Definition 3.18 If ω is a Y -valued Moore–Smith sequence, Θ is a topology on Y , A is the direction of ω , and $y \in Y$, we say that y is the *limiting value of* ω *along* A , and write

$$\lim \omega = y \tag{3.14}$$

if, for each $O \in N_\Theta(y)$, $\omega^*(O)$ is final in A .

Example 3.19 On \mathbb{R} the preorder \leq [resp. the preorder \geq] yield the familiar notions $\lim_{r \rightarrow +\infty} \omega(r)$ [resp. $\lim_{r \rightarrow -\infty} \omega(r)$] for a Y -valued Moore–Smith sequence $\omega : \mathbb{R} \rightarrow Y$.

If we need to emphasize more explicitly the preorder R or the direction A , we write

$$\lim_R \mathscr{w} = z \quad \text{or} \quad \lim_A \mathscr{w} = z$$

instead of (3.14).

Definition 3.20 If $\mathscr{w} \in \mathcal{S}(\mathbb{R})$ and A is the direction of \mathscr{w} , we say that $\lim_A \mathscr{w} = +\infty$ if for each $r \in \mathbb{R}$ the set $\{x \in A : \mathscr{w}(x) > r\}$ is final in A . We say that $\lim_A \mathscr{w} = -\infty$ if $\lim_A(-\mathscr{w}) = +\infty$

The following elementary remark is useful in topological spaces where points are not necessarily separated. We will see that the set $\mathcal{F}(A)$ is endowed with a topology of this kind. Indeed, we will see that $\mathcal{F}(A)$ is compact but not Hausdorff, while $\mathcal{U}(A)$ is compact and Hausdorff.

Lemma 3.21 *If $\mathbf{z}, \mathbf{w} \in Y$ and Θ is a topology on Y , then the following conditions are equivalent:*

- (1) $\mathbf{z} \in \overline{\{\mathbf{w}\}}$,
- (2) $\mathbf{z} = \lim \mathbf{w}$.

Remark 3.22 Of course the statement is interesting only if $\mathbf{z} \neq \mathbf{w}$. Observe that $\overline{\{\mathbf{w}\}}$ is the closure in the given topology, and that (2) rests on the fact that, according to (3.13), we may identify \mathbf{w} with the constant sequence \mathscr{w} identically equal to \mathbf{w} , and indeed (2) says that \mathbf{z} is the limiting value of this sequence.

Proof Define $\mathscr{w} : \mathbb{N} \rightarrow A$ by $\mathscr{w}(k) \stackrel{\text{def}}{=} \mathbf{w}$ for each w . Then $\mathscr{w}^*(O)$ is equal to \mathbb{N} for each $O \in N_\Theta(\mathbf{z})$, since $\mathbf{z} \in \overline{\{\mathbf{w}\}}$, hence $\mathbf{z} = \lim \mathscr{w}$, and (2) follows from the identification of \mathbf{w} with \mathscr{w} in (3.13). □

Lemma 3.21 is a special case of the following, more general, result, due to Garrett Birkhoff [3]. Observe that if $W \subset Y$ then each W -valued Moore–Smith sequence may be seen as a Y -valued Moore–Smith sequence:

$$\mathcal{S}(W) \hookrightarrow \mathcal{S}(Y).$$

Lemma 3.23 ([3]) *If (Y, Θ) is a topological space, $W \subset Y$, and $z \in Y$ then the following conditions are equivalent.*

- (1) $z \in \overline{W}$,
- (2) there exists $\mathscr{w} \in \mathcal{S}(W)$ such that $z = \lim \mathscr{w}$.

Proof If (1) holds, then $\mathbf{b} \cap W \neq \emptyset$ for each $\mathbf{b} \in N_\Theta(z)$, hence there exists a function $\mathscr{w} : N_\Theta(z) \rightarrow W$ such that $\mathscr{w}(\mathbf{b}) \in \mathbf{b} \cap W$ for each $\mathbf{b} \in N_\Theta(z)$, and \mathscr{w} is a generalized sequence, by Example 3.15. Let $O \in N_\Theta(z)$. If $U \in N_\Theta(z)$ and $O \supset U$ then $\mathscr{w}(U) \in U \subset O$ hence $\mathscr{w}(U) \in O$. Hence $\text{tail}_{N_\Theta(z)}(O) \subset \mathscr{w}^*(O)$. Thus $z = \lim \mathscr{w}$. If (2) holds then for each $O \in N_\Theta(z)$ there exists $x \in A$ such that $\text{tail}_A(x) \subset \mathscr{w}^*(O)$, thus $O \cap W$ contains $\mathscr{w}(r)$ for any $r \in \text{tail}_A(x)$. Hence $O \cap W$ is not empty and (1) holds. □

Remark on notation In order to facilitate the distinction between the setting of filters and the setting of Moore–Smith sequences, and also to gain a better appreciation of the connection between the two viewpoints, we use *bold Sans Serif* font to denote limiting notions pertaining to filters, such as **lim**, **cluster**, **liminf**, **limsup**, and *Type-writer* font to denote notions pertaining to Moore–Smith sequences, such as `lim` and `ClusterSet`. Indeed, it seems to us that if we used the same notation for the different notions then the connection between the two viewpoints would be obscured by the uniform notation.

3.5 The Functional Convergence Class Associated to a Direction

The following result says that convergence along a direction, described in Definition 3.18, is a limiting process that yields a functional convergence class, just as the limiting process of convergence along a filter does. However, we will see that the limiting process of convergence along a filter on A , described in Definition 1.12, has wider scope and higher synthetic power than the limiting process of convergence along a direction on A , described in Definition 3.18.

Theorem 3.24 *If $R \in \text{dir}(A)$ then*

$$\mathcal{F}_R \stackrel{\text{def}}{=} \left\{ (y, \varphi) \in \mathbb{R} \times \text{hom}_{\text{Set}}(A, \mathbb{R}) : \underset{R}{\text{lim}} \varphi = y \right\} \tag{3.15}$$

is a functional convergence class on A .

Proof The proof will be given in Sect. 3.6. □

3.6 A Comparison of the Two Notions

In 1938, Herman Lyle Smith considered the following notion of limiting value, due to Arnaud Denjoy [10, p. 165], [32], [13, p. 158]. We say that φ has *approximate limiting value* equal to y at x_0 if the following condition holds.

(Example MS 4) $\varphi : \mathbb{R} \rightarrow \mathbb{R}$ is measurable, $x_0 \in \mathbb{R}$, $y \in \mathbb{R}$, and for each $\epsilon > 0$ the set

$$\{x \in \mathbb{R} : |\varphi(x) - y| < \epsilon\}$$

has density equal to 1 at x_0 .

H. L. Smith observed that the limiting notion in (Example MS 4) may be readily subsumed under Definition 1.12 but that it cannot be covered by Definition 3.18 “without a somewhat artificial transformation.”

Observe that the collection of final sets in a directed set is a filter. For example, the filter generated by the natural order on \mathbb{N} is the Fréchet filter (see Example 1.9). Indeed, we now show that every directed set A yields a filtered set $A_{\text{FSet}} \stackrel{\text{def}}{=} (A_{\text{Set}}, \text{Fin}[A])$, whose underlying set is the underlying set of A and whose filter is the one generated

by the given direction on A . In other words, we define a map

$$\text{dir}(A) \rightarrow \mathcal{F}(A). \tag{3.16}$$

Lemma 3.25 *If A is a directed set, then the collection $\text{Fin}[A]$ of final sets in A is a filter on A , called the filter generated by (the tails of) R .*

Proof If $b_1, b_2 \in \text{Fin}[A]$ then there exist $x_1, x_2 \in A$ with $\text{tail}_A(x_1) \subset b_1$ and $\text{tail}_A(x_2) \subset b_2$, and there exists a majorant x of x_1, x_2 , and therefore $\text{tail}_A(x) \subset \text{tail}_A(x_1) \cap \text{tail}_A(x_2) \subset b_1 \cap b_2$. Hence $b_1 \cap b_2 \in \text{Fin}[A]$. \square

Lemma 3.25 enables us to subsume Definition 3.18 under Definition 1.12.

Lemma 3.26 *If ω is a Y -valued Moore–Smith sequence, Θ is a topology on Y , A is the direction of ω , and $y \in Y$, then the following conditions are equivalent*

(Definition 3.18) $\lim_A \omega = y$,

(Definition 1.12) $\lim_{\text{Fin}[A]} \omega = y$.

Proof Definition 3.18 says precisely that $\omega : (A, \text{Fin}[A]) \rightarrow (Y, N_\Theta(y))$ is a filter-homomorphism. \square

Proof of Theorem 3.24 Lemma 3.26 says that

$$\begin{aligned} & \left\{ (y, \varphi) \in \mathbb{R} \times \text{hom}_{\text{Set}}(A, \mathbb{R}) : \lim_R \varphi = y \right\} \\ &= \left\{ (y, \varphi) \in \mathbb{R} \times \text{hom}_{\text{Set}}(A, \mathbb{R}) : \lim_{\text{Fin}[A]} \varphi = y \right\} \end{aligned} \tag{3.17}$$

and we know from Theorem 3.2 that the right-hand side of (3.17) is a functional convergence class, since $\text{Fin}[A]$ is a filter on A . \square

Hence (3.15) and Theorem 3.24 yield a map

$$\text{dir}(A) \rightarrow \text{FCC}(A). \tag{3.18}$$

Moreover, the following result also follows immediately from Theorem 3.24.

Theorem 3.27 *If A is a nonempty set, then the following diagram is commutative*

$$\begin{array}{ccc} \text{dir } A & \longrightarrow & \mathcal{F}(A) \\ & \searrow & \downarrow c_A \\ & & \text{FCC}(A) \end{array} \tag{3.19}$$

where the map on the top is the one given in (3.16) and the diagonal map is the one given in (3.18).

Proof The result follows immediately from Lemma 3.26. □

Recall that Theorem 3.7 says that c_A in (3.19) is 1–1 and onto, and this means that every functional convergence class on A is associated to a unique filter. One may wonder whether the diagonal map in (3.19) is also onto, i.e., *whether every functional convergence class is associated to a direction on A* . As far as we know, the following result is new.

Theorem 3.28 *If A is equal to the unit disc in \mathbb{C} , then the diagonal map in (3.19) is not onto. Indeed, the functional convergence class associated to nontangential convergence is not associated to any direction.*

Proof We now show that Theorem 3.28 may be reduced to Theorem 3.29, to be stated momentarily. Recall that if $\mathbb{D} \stackrel{\text{def}}{=} \{z : z \in \mathbb{C}, |z| < 1\}$ is the unit disc in \mathbb{C} , then there exists a filter $S \in \mathcal{F}(\mathbb{D})$, called the *nontangential filter on \mathbb{D} ending at 1* (see [11, 12, 33], for background), such that the following result holds.

(Example MS 5) For each $\varphi : \mathbb{D} \rightarrow \mathbb{R}$ and each $z \in [-\infty, +\infty]$, $\lim_S \varphi = z$ if and only if $\lim_{T \ni z \rightarrow x} \varphi(z) = z$ for each open Euclidean triangle T contained in \mathbb{D} and having 1 as a vertex.

A precise definition of the nontangential filter S will be given in Sect. 5.

Theorem 3.28 follows at once from the following result.

Theorem 3.29 *The nontangential filter S on \mathbb{D} is not equal to the filter of tails of any direction on \mathbb{D} .*

The proof of Theorem 3.29 will be given in Sect. 5. □

Remark 3.30 We do not know whether an intrinsic characterization of the image of the map (3.16) is known, i.e., whether it is possible to give an intrinsic characterization of those filters which are generated by a direction.

Remark 3.31 Lemma 3.25 shows that every directed set A yields a filtered set $A_{\text{FSet}} \stackrel{\text{def}}{=} (A_{\text{Set}}, \text{Fin}[A])$, whose underlying set is the underlying set of A and whose filter is the filter of tails of the given direction on A . We will look at DSet as a full subcategory of FSet , i.e., we will declare that DSet -homomorphisms from A to A' , where A and A' are directed sets, are precisely the FSet -homomorphisms from A_{FSet} to A'_{FSet} . However, we will not base the notion of *Moore–Smith subsequence* on this identification, since it would lead to “irregularities” [1, p. 285] and make the subject somewhat “contentious,” as Saitulaa Naranong puts it in *Translating between Nets and Filters* (2010) (unpublished). We will return to this theme in Sect. 12.

Directed sets form a proper subclass of the objects of the category FSet of filtered sets, since

(Lemma 3.26) the relevant data in a directed set is the filter of tails of the given direction, and

(Theorem 3.29) The map (3.18) is not necessarily onto.

In his work, R. de Possel used *sequences* of measurable sets. One may be tempted to employ instead *Moore–Smith sequences*, and we will do so in Sect. 3.7, but we will

see that filters appear to be more flexible and direct. This conclusion may appear to be counterintuitive, since convergence phenomena are based on an idea of movement, and Moore–Smith sequences appear to be especially suited to represent them, because a “dynamic” is encoded in the directed set which acts as their basis, while filters are seemingly “static” objects, in the sense that there is no apparent “sense of direction” in them. In Sect. 9, we will show that this impression is erroneous, since the collection of all filters on a given nonempty set is endowed with a natural topology, which is especially suited to be used in the study of convergence phenomena. Hence, the advantage of filters is that there is no need to rest on the additional structure of a directed set, since a “sense of direction” is encoded in their intrinsic structure.

3.7 The Functional Convergence Class Associated to a Family of Moore–Smith Sequences

We now introduce another method for constructing functional convergence classes.

Definition 3.32 If A is a nonempty set and a nonempty set $V \subset \mathcal{S}(A)$ is given, then define

$$\mathcal{F}_V \stackrel{\text{def}}{=} \{(y, \varphi) \in \mathbb{R} \times \text{hom}_{\text{Set}}(A, \mathbb{R}) : \forall \omega \in V, \lim \varphi \circ \omega = y\} \quad (3.20)$$

Theorem 3.33 If A is a nonempty set and a nonempty set $V \subset \mathcal{S}(A)$ is given, then \mathcal{F}_V , defined in (3.20), is a functional convergence class.

Proof The proof will be given in Sect. 7. □

Theorem 3.34 If $Z \in \mathcal{F}(A)$ then there exists $V \subset \mathcal{S}(A)$ such that, for each topological space (Y, Θ) , every $y \in Y$, and each function $\varphi : A \rightarrow Y$, the following conditions are equivalent:

- (1) $\lim_Z \varphi = y$,
- (2) for each $\iota \in V$, $\lim \varphi \circ \iota = y$.

Proof Define

$$S \stackrel{\text{def}}{=} \{\iota : Z \rightarrow A, \iota(\mathbf{b}) \in \mathbf{b} \text{ for each } \mathbf{b} \in Z : \cdot\}$$

Observe that Z is a directed set, by Example 3.15, and hence $S \subset \mathcal{S}(A)$. Let (Y, Θ) be a topological space, $\varphi : A \rightarrow Y$, and $y \in Y$, and assume that (1) holds. If $U \in N_{\Theta}(y)$ then there exists $\mathbf{b} \equiv \mathbf{b}_U \in Z$ such that $\mathbf{b} = \varphi^*(U)$. Let $\iota \in S$ and consider $\varphi \circ \iota : Z \rightarrow A$, where Z is seen as a directed set, as in Example 3.15. If $\mathbf{d} \in Z$ and $\mathbf{b} \supset \mathbf{d}$, then $(\varphi \circ \iota)(\mathbf{d}) = \varphi(\iota(\mathbf{d}))$, $\iota(\mathbf{d}) \in \mathbf{d}$, $\mathbf{d} \subset \mathbf{b}$, and $\mathbf{b} = \varphi^*(U)$ imply that $(\varphi \circ \iota)(\mathbf{d}) \in U$. Since $U \in N_{\Theta}(y)$ is arbitrary, it follows that $\lim \varphi \circ \iota = y$, and since $\iota \in S$ is arbitrary, it follows that (2) holds. If (1) does not hold, then there exists $U \in N_{\Theta}(y)$ such that $\varphi^*(U) \notin Z$. Hence for each $\mathbf{b} \in Z$ it is not true that $\mathbf{b} \subset \varphi^*(U)$

(for otherwise it would follow that $\varphi^*(U) \in Z$, since Z is a filter). Hence for each $b \in Z$ there exists $x_b \in b$ such that $x_b \notin \varphi^*(U)$, i.e., $\varphi(x_b) \notin U$. Define

$$\omega : Z \rightarrow A$$

by letting $\omega(b) \stackrel{\text{def}}{=} x_b$. Then $\omega \in S$ but it is not true that $\lim f \circ \omega = y$, hence (2) does not hold. □

Theorem 3.35 *If A is a nonempty set, then every functional convergence class on A is equal to \mathcal{F}_V , defined in (3.20), for some nonempty $V \subset \mathcal{S}(A)$.*

Proof This result follows at once from Theorems 3.7 and 3.34. □

We have thus seen that a functional convergence class on A may be represented in terms of a unique filter, or in terms of a family V , as in Theorem 3.33. The advantage of the representation in terms of filters is precisely given by uniqueness. Indeed, the lack of uniqueness would cause some difficulties in the determination of the exceptional set for a.e. convergence. Hence the approach based on the notion of filter has higher synthetic power and flexibility.

Theorem 3.34 shows that the functional convergence class $c_A(Z)$ of a given filter Z on A may be described as \mathcal{F}_V , in terms of a set V of A -valued Moore–Smith sequences. One may wonder whether it is possible to choose as V a set of A -valued sequences, and whether it is possible to choose as V as set consisting of just one Moore–Smith sequence. We will see that the answer to the first question is in the negative, and that the answer to the second question is in the positive.

Theorem 3.36 *There exists a nonempty set A and a functional convergence class \mathcal{F} on A such that \mathcal{F} cannot be represented in the form \mathcal{F}_V where V is a collection of A -valued sequences.*

Proof Let $A = \mathbb{N}$ and let $Z \in \mathcal{F}(\mathbb{N})$ be an ultrafilter on \mathbb{N} which contains the Fréchet filter. □

Theorem 3.37 *For every nonempty set A and each functional convergence class \mathcal{F} on A there exists an A -valued Moore–Smith sequence q such that $\mathcal{F} = \mathcal{F}_q$.*

Proof The proof will be given in Sect. 8. □

4 Preliminary Results on Filters

The goal of this section is to give a self-contained presentation of the basic results on filters.

4.1 Basic Lattice-Theoretic Properties of $\mathcal{F}(A)$

A preliminary examination of some lattice-theoretic properties of $\mathcal{F}(A)$ will be useful, as we will see, in order to gain a better understanding of the topological implications

of the notion of filter. Recall that if \mathcal{C} is a family of filters, i.e., if $\mathcal{C} \subset \mathcal{F}(A)$, then

$$\bigcap \mathcal{C} \stackrel{\text{def}}{=} \{b \in \mathcal{P}_\bullet(A) : b \in Z \text{ for each } Z \in \mathcal{C}\}$$

Lemma 4.1 (Cartan [8]) *The intersection $\bigcap \mathcal{C}$ of any nonempty family \mathcal{C} of filters on a set is not empty and is a filter.*

Proof If $\mathcal{C} \subset \mathcal{F}(A)$ then $A \in \bigcap \mathcal{C}$, hence $\bigcap \mathcal{C} \neq \emptyset$. If $b_1, b_2 \in \bigcap \mathcal{C}$ then $b_1, b_2 \in Z$ for each $Z \in \mathcal{C}$, hence $b_1 \cap b_2 \in Z$ for each $Z \in \mathcal{C}$, hence $b_1 \cap b_2 \in \bigcap \mathcal{C}$. If $b \in \bigcap \mathcal{C}$ and $b \subset d$, then $b \in Z$ hence $d \in Z$ for each $Z \in \mathcal{C}$, thus $d \in \bigcap \mathcal{C}$. \square

Observe that $\mathcal{P}(X)$ is a poset, hence $\mathcal{F}(A)$ is a poset under set inclusion (Example 3.10).

Definition 4.2 If x, y are elements of a poset (X, R) , then an element $l \in X$ is called a *lower bound for x and y in X* if lRx and lRy . An element $l \in X$ of a poset X is called a *meet of x and y* , or *greatest lower bound (g.l.b.)* of x and y , if (i) l is a lower bound of x and y , and (ii) if b is any other lower bound of x and y , then bRl . If it exists, a meet of x and y in a poset X is denoted by $x \wedge y$.

Observe that antisymmetry of R implies that, in a poset, a meet of x and y , if it exists, is unique.

The notion of greatest lower bound of a subset S of a poset X is defined in a natural way, to wit: If it exists, it is an element $l \in X$ such that (i) l is a lower bound of S (i.e., lRa for each $a \in S$), and (ii) if b is a lower bound of S , then bRl ; If it exists, it is unique. If it exists, the greatest lower bound of a subset S is denoted by $\bigwedge_{s \in S} s$.

Proposition 4.3 (Cartan [8]) *The infimum (greatest lower bound) $\bigwedge_{Z \in \mathcal{C}} Z$ of any nonempty family \mathcal{C} of filters on A exists in $\mathcal{F}(A)$. It is the intersection of all the filters in the family.*

Proof The statement follows at once from Lemma 4.1. \square

Definition 4.4 If x, y are elements of a poset (X, R) , an element $l \in X$ is called a *upper bound for x and y in X* if xRl and yRl . An element $l \in X$ of a poset X is called a *join of x and y* , or *least upper bound (l.u.b.)* of x and y , if (i) l is an upper bound of x and y , and (ii) if u is any other upper bound of x and y , then lRu . If it exists, a join of x and y in a poset X is denoted by $x \vee y$.

Antisymmetry implies that, in a poset, a join of x and y , if it exists, is unique. In Sect. 9.2 we will see that the existence of the join of two filters is more delicate.

4.2 The Operator A^\uparrow

In order to present a basic technique for the construction of filters and exhibit more examples of filters, we introduce an operator A^\uparrow associated to every nonempty set. This operator is actually implicit in the definition of the notion of filter, so it is not surprising that it serves as a useful tool to construct new ones.

The basic building block for the operator A^\uparrow is contained in the following observation, which shows that $\mathcal{F}(A)$ contains a copy of $\mathcal{P}_\bullet(A)$. Indeed, consider the following diagram

$$\begin{array}{ccc}
 & \mathcal{P}_\bullet(\mathcal{P}_\bullet(A)) & \\
 A_\bullet \nearrow & \uparrow A^\uparrow & \\
 \mathcal{P}_\bullet(A) & \xrightarrow{\iota} & \mathcal{P}_\bullet(\mathcal{P}_\bullet(A))
 \end{array} \tag{4.1}$$

where the function $\iota : \mathcal{P}_\bullet(A) \rightarrow \mathcal{P}_\bullet(\mathcal{P}_\bullet(A))$ is defined by $\iota(b) \stackrel{\text{def}}{=} \{b\}$, for each $b \in \mathcal{P}_\bullet(A)$, and the functions A_\bullet and A^\uparrow will be defined momentarily.

Lemma 4.5 *If $b \in \mathcal{P}_\bullet(A)$ then the collection*

$$A_b \stackrel{\text{def}}{=} \{c \in \mathcal{P}_\bullet(A) : b \subset c\} \tag{4.2}$$

is a filter which contains b as an element: it is the smallest filter on A which contains b as an element, and is called the principal filter generated by b on A .

Proof (F 0) $b \neq \emptyset \Rightarrow \emptyset \notin A_b$. **(F1.a)** $b \subset A \Rightarrow A \in A_b$. **(F1.b)** $b_1, b_2 \in A_b \Rightarrow b \subset b_1$ and $b \subset b_2$, hence $b \subset b_1 \cap b_2$, thus $b_1 \cap b_2 \in A_b$. **(F2)** If $c \in A_b$ and $c \subset d$ then $b \subset c \subset d$, hence $b \subset d$, i.e., $d \in A_b$. Let \mathcal{C} be the family of filters on A which contains b as an element. If $Z \in \mathcal{C}$ and $c \in A_b$ then $c \in Z$, since $b \in Z$ and Z is a filter. Hence $A_b \subset Z$. The conclusion follows from the fact that $A_b \in \mathcal{C}$. \square

Definition 4.6 Define $A_\bullet : \mathcal{P}_\bullet(A) \rightarrow \mathcal{P}_\bullet(\mathcal{P}_\bullet(A))$ by $A_\bullet(b) \stackrel{\text{def}}{=} A_b$, for each $b \in \mathcal{P}_\bullet(A)$.

The map A^\uparrow is designed to make the diagram (4.1) commutative (i.e., to extend A_\bullet to $\mathcal{P}_\bullet(\mathcal{P}_\bullet(A))$) and to commute with the union of collections.

Definition 4.7 A map

$$\varphi : \mathcal{P}_\bullet(\mathcal{P}_\bullet(A)) \rightarrow \mathcal{P}_\bullet(\mathcal{P}_\bullet(A))$$

commutes with the union of collections if

$$\varphi\left(\bigcup_{\alpha \in I} Z_\alpha\right) = \bigcup_{\alpha \in I} \varphi(Z_\alpha) \tag{4.3}$$

for each indexed family of collections $\{Z_\alpha\}_{\alpha \in I}$, where $Z_\alpha \in \mathcal{P}_\bullet(\mathcal{P}_\bullet(A))$ and I is a nonempty set of indexes.

Lemma 4.8 *In diagram (4.1) there exists a unique map A^\uparrow (dotted arrow) that makes the diagram commute, and which commutes with the union of collections.*

Proof We define the map as follows:

$$A^\uparrow[W] \stackrel{\text{def}}{=} \{c \in \mathcal{P}_\bullet(A) : c \supset b \text{ for some } b \in W\}. \tag{4.4}$$

Observe that if $W = \{b\}$ where $b \in \mathcal{P}_\bullet(A)$ then $A^\uparrow[W] = A_b$, hence (4.1) commutes. We now show that A^\uparrow commutes with the union of collections. Indeed, the statement that $b \in A^\uparrow[\bigcup_{\alpha \in I} Z_\alpha]$ means that there exists $\alpha \in I$ and $c \in Z_\alpha$ such that $b \supset c$, and this means precisely that $b \in \bigcup_{\alpha \in I} A^\uparrow[Z_\alpha]$. In order to show uniqueness, it suffices to observe that $W = \bigcup_{b \in W} \{b\} = \bigcup_{b \in W} i(b)$ for each $W \in \mathcal{P}_\bullet(\mathcal{P}_\bullet(A))$. \square

Lemma 4.9 *If $W \in \mathcal{P}_\bullet(\mathcal{P}_\bullet(A))$ then*

$$A \subset A^\uparrow[W]. \tag{4.5}$$

Proof If $b \in W$ then $b \subset b$, hence $b \in A^\uparrow[W]$. \square

Lemma 4.10 *If $W \in \mathcal{P}_\bullet(\mathcal{P}_\bullet(A))$ then*

$$A^\uparrow[A^\uparrow[W]] = A^\uparrow[W]. \tag{4.6}$$

Proof If $b \in A^\uparrow[A^\uparrow[W]]$ then $b \supset c$ for some $c \in A^\uparrow[W]$, i.e., $c \supset d$ for some $d \in W$. Hence $b \supset d$, i.e., $b \in A^\uparrow[W]$. We have thus proved that $A^\uparrow[A^\uparrow[W]] \subset A^\uparrow[W]$. The conclusion follows from Lemma 4.9. \square

4.3 Bases and Subbases

Observe that $W \in \mathcal{P}_\bullet(\mathcal{P}_\bullet(A))$ satisfies **(F2)** in the axioms of a filter (Sect. 1.2.3) if and only if $A^\uparrow[W] = W$. Lemma 4.10 then says that $A^\uparrow[W]$ satisfies **(F2)**. Lemma 4.5 says that the image of A_\bullet in (4.1) is contained in $\mathcal{F}(A)$. The same result does not hold for the map A^\uparrow . Indeed, if $W \in \mathcal{P}_\bullet(\mathcal{P}_\bullet(A))$ then the collection $A^\uparrow[W]$, defined in (4.4), satisfies **(F0)** (since $A \in A^\uparrow[W]$) and **(F2)** (by Lemma 4.10) but not necessarily **(F1)** in the definition of filter. For example, if $W = \{b_1, b_2\}$ where $b_1, b_2 \in \mathcal{P}_\bullet(A)$ are disjoint, then $A^\uparrow[W]$ is not a filter, since a filter cannot contain disjoint sets.

Lemma 4.11 (Cartan [8]) *If $W \in \mathcal{P}_\bullet(\mathcal{P}_\bullet(A))$ then the following conditions are equivalent:*

- (1) $A^\uparrow[W]$ is a filter on A .
- (2) For each $b, c \in W$, there exists $d \in W$ such that $d \subset b \cap c$.

Proof If (1) holds and $b, c \in W$, then $b \cap c \in A^\uparrow[W]$, hence there exists $d \in W$ such that $b \cap c \in A_d$, i.e., $d \subset b \cap c$. If (2) holds and $b, c \in A^\uparrow[W]$, then there exist $b', c' \in W$ such that $b' \subset b$ and $c' \subset c$. Hence there exists $d \in W$ with $d \subset b' \cap c'$. Thus $d \subset b \cap c$, i.e., $b \cap c \in A^\uparrow[W]$. \square

Definition 4.12 If $W \in \mathcal{P}_\bullet(\mathcal{P}_\bullet(A))$ has one of the equivalent properties in Lemma 4.11, we then say that W is a *filter base on A* ; the filter $A^\uparrow[W]$ defined in (4.4) is the *filter generated by W on A* .

Example 4.13 The collection $W \stackrel{\text{def}}{=} \{(-x^2, 0) : x \in \mathbb{R}, x > 0\}$ is a filter base on \mathbb{R} .

Example 4.14 The collection $W \stackrel{\text{def}}{=} \{(-\infty, x^2,) \cup (x^2, +\infty) : x \in \mathbb{R}, x > 0\}$ is a filter base on \mathbb{R} .

Lemma 4.15 A preorder R on a set A is a direction on A if and only if the collection of tails in (A, R) is a filter base.

Proof If the collection of tails in (A, R) is a filter base on A then, given $x, r \in A$, there exists $p \in A$ such that $\text{tail}_A(p) \subset \text{tail}_A(x) \cap \text{tail}_A(r)$, hence p is a majorant of $\{x, r\}$. In Lemma 3.26 we proved the converse. \square

Lemma 4.16 If $Z \in \mathcal{F}(A)$ and $f \in \text{hom}_{\text{Set}}(A, Y)$, then $(f_*)_*(Z)$ is a filter base on Y .

Proof Recall that $(f_*)_* : \mathcal{P}(\mathcal{P}(A)) \rightarrow \mathcal{P}(\mathcal{P}(Y))$ and observe that $(f_*)_*(Z) = \{f_*(b) : b \in Z\} \subset \mathcal{P}_*(Y)$. If $b_1, b_2 \in Z$ then $b_1 \cap b_2 \in Z$ (since Z is a filter) and $f_*(b_1 \cap b_2) \subset f_*(b_1) \cap f_*(b_2)$, hence (2) in Lemma 4.11 holds. \square

4.3.1 Generating Bases for a Filter

Lemma 4.17 If $Z \in \mathcal{F}(A)$, $W \subset Z$, and the following condition holds:

$$Z \subset A^\uparrow[W] \tag{4.7}$$

then W is a filter base on A and $A^\uparrow[W] = Z$.

Proof $W \subset Z \Rightarrow A^\uparrow[W] \subset A^\uparrow[Z]$. Since $Z \in \mathcal{F}(A)$, $A^\uparrow[Z] = Z$, hence $A^\uparrow[W] \subset Z$. On the other hand, (4.7) and Lemma 4.10 imply that $A^\uparrow[Z] \subset A^\uparrow[A^\uparrow[W]] = A^\uparrow[W]$, hence $Z \subset A^\uparrow[W]$. \square

Definition 4.18 If $Z \in \mathcal{F}(A)$, $W \subset Z$, and (4.7) holds, then we say that W is *generating basis* for Z .

Example 4.19 The collection $W \stackrel{\text{def}}{=} \{b \in \mathcal{P}_*(\mathbb{N}) : \exists n \in \mathbb{N} \text{ such that } b = \{k \in \mathbb{N} : k \geq n\}\}$ is a generating basis for the Fréchet filter $f\mathbb{N}$ on \mathbb{N} , introduced in Example 1.9. Indeed, $f\mathbb{N} = \mathbb{N}^\uparrow[W]$.

Observe that (4.7) says that for each $b \in Z$ there exists $c \in W$ such that $c \subset b$.

Corollary 4.20 If W and Y in $\mathcal{P}_*(\mathcal{P}_*(A))$ are filter bases on A , then the following conditions are equivalent:

- (1) $A^\uparrow[W] = A^\uparrow[Y]$,
- (2) $W \subset A^\uparrow[Y]$ and $Y \subset A^\uparrow[W]$.

If any of these equivalent conditions holds, we say that W and Y are equivalent.

4.3.2 Filter Subbases

Observe that if $W \in \mathcal{P}_\bullet(\mathcal{P}_\bullet(A))$ then the collection

$$W^\cap \stackrel{\text{def}}{=} \{Q \in \mathcal{P}(A) : \exists C \subset W, C \text{ is finite and nonempty}, Q = \cap C\} \quad (4.8)$$

satisfies Condition (2) in Lemma 4.11 but it is not necessarily true that $W^\cap \in \mathcal{P}_\bullet(\mathcal{P}_\bullet(A))$, since it may happen that $\emptyset \in W^\cap$. However, we have the following result, stated in terms of (4.8).

Lemma 4.21 (Cartan [8]) *If $W \in \mathcal{P}_\bullet(\mathcal{P}_\bullet(A))$ then a necessary and sufficient condition for the existence of a filter on A which contains W is that $\emptyset \notin W^\cap$. If $\emptyset \notin W^\cap$, then W^\cap is a filter base on A , and the filter $A^\uparrow[W^\cap]$ is said to be generated by the subbase W .*

Proof If $Y \in \mathcal{F}(A)$ with $W \subset Y$ and $\{b_1, \dots, b_n\} \subset W, n \in \mathbb{N}$, then $\{b_1, \dots, b_n\} \subset Y$, hence $\bigcap_{j=1}^n b_j \in Y$ and thus $\bigcap_{j=1}^n b_j \neq \emptyset$. If $\emptyset \notin W^\cap$ then $W^\cap \in \mathcal{P}_\bullet(\mathcal{P}_\bullet(A))$. Condition (2) in Lemma 4.11 holds for W^\cap by its very construction, and $A^\uparrow[W^\cap]$ is a filter which contains W . □

Definition 4.22 If $W \in \mathcal{P}_\bullet(\mathcal{P}_\bullet(A))$ and $\emptyset \notin W^\cap$, then we then say that W is a *filter subbase on A* , and $A^\uparrow[W^\cap]$ is the *filter generated by the subbase W on A* : It is the broadest filter which contains W .

4.4 Ultrafilters and Compactness

If $Z \in \mathcal{F}(A)$, then $Z \subset \mathcal{P}_\bullet(A)$, and, in particular, if $b \in Z$, then $b \subset A$. Thus

$$\mathcal{F}(A) \subset \mathcal{P}_\bullet(\mathcal{P}_\bullet(A)). \quad (4.9)$$

Hence $\mathcal{F}(A)$ inherits from $\mathcal{P}_\bullet(\mathcal{P}_\bullet(A))$ the partial order given by inclusion. The notion of *ultrafilter*, due to H. Cartan, introduced in Definition 1.5, is useful in several areas: topology, functional analysis, mathematical logic, among many others.

Observe that a filter on A is an *ultrafilter* if it is a maximal element of $\mathcal{F}(A)$ under inclusion.

Lemma 4.23 *If $b \in \mathcal{P}_\bullet(A)$ then the principal filter A_b is an ultrafilter if and only if b is a singleton.*

Proof If $b = \{x\}, x \in A, Z \in \mathcal{F}(A), A_b \subset Z$, and $c \in Z$, then $b \cap c \neq \emptyset$, thus $x \in c$, hence $c \in A_b$. If b is not a singleton, let $x \in b$. Then $A_b \subsetneq A_{\{x\}}$ since $\{x\} \in A_{\{x\}} \setminus A_b$, hence A_b is not an ultrafilter. □

Lemma 4.24 *The collection $\mathcal{F}(A)$ is inductive with respect to the partial order induced by $\mathcal{P}_\bullet(\mathcal{P}_\bullet(A))$.*

Proof If $L \subset \mathcal{F}(A)$ is linearly ordered and $W \stackrel{\text{def}}{=} \{b : b \in \mathcal{P}_\bullet(A), \exists Z \in L, b \in Z\}$ then W^\cap in (4.8) does not contain the empty set, and the filter generated by the subbase W is an upper bound of L . □

Theorem 4.25 *If $Z \in \mathcal{F}(A)$ then there exists $W \in \mathcal{U}(A)$ such that $Z \subset W$.*

Proof Apply Zorn’s lemma and Lemma 4.24. □

Lemma 4.26 *If $A \neq \emptyset$ then $\mathcal{U}(A) = \{Z \in \mathcal{F}(A) : \forall b \in \mathcal{P}(A) \text{ either } b \in Z \text{ or } \complement b \in Z\}$.*

Proof If $Z \in \mathcal{U}(A)$, $b \in \mathcal{P}(A)$, and $b \notin Z$, then $Z \subsetneq Z \cup \{b\}$, and $Z \cup \{b\}$ is not a filter subbase on A , i.e., there exists $c \in Z$ with $c \cap b = \emptyset$. Hence $c \subset \complement b$, thus $\complement b \in Z$. If $Z \in \mathcal{F}(A) \setminus \mathcal{U}(A)$, then there exists $b \in \mathcal{P}_*(A) \setminus Z$ such that $Z \cup \{b\}$ is a filter subbase; hence $b \cap c \neq \emptyset$ for each $c \in Z$, thus $\complement b \notin Z$. □

Corollary 4.27 *If $A \neq \emptyset$ then $\mathcal{U}(A) = \{Z \in \mathcal{F}(A) : Z = \text{wloc}(Z)\}$.*

Lemma 4.28 *If $Z \in \mathcal{U}(b)$, $b \in Z$, and $c \subset b$, then either $c \in Z$ or $b \setminus c \in Z$.*

Proof If $c \notin Z$ then $Z \cup \{c\}$ is not a filter subbase, hence there exists $d \in Z$ with $d \cap c = \emptyset$. Hence $b \cap d \subset b \setminus c$. Thus $b \setminus c \in Z$, since $b \cap d \in Z$. □

Observe that, if $T \in \mathcal{P}(\mathcal{P}(A))$ is an open cover of $K \subset A$, then for each $x \in K$ there exists $O \in T$ with $x \in O$, and $K \subset O \cup \complement O$.

Lemma 4.29 *If $T \in \mathcal{P}(\mathcal{P}(A))$ is an open cover of $K \subset A$, then the collection*

$$W_K^T \stackrel{\text{def}}{=} \left\{ b \in \mathcal{P}(b) : \exists \text{ finite } T_0 \subset T \text{ such that } K \subset \bigcup T_0 \cup b \right\} \quad (4.10)$$

is a filter if and only if T has no finite subcover of K .

Proof Observe that $\emptyset \in W_K^T$ if and only if T has a finite subcover of K , hence it suffices to observe that (i) $A \in W_K^T$; (ii) $b, c \in W_K^T \Rightarrow b \cap c \in W_K^T$; (iii) $b \in W_K^T$ and $b \subset c \Rightarrow c \in W_K^T$. □

The following characterization of compactness is useful.

Lemma 4.30 (Cartan [8]) *Assume that (A, Θ) is a topological space and that $K \subset A$. Then the following conditions are equivalent:*

- K is compact.
- For each $Z \in \mathcal{U}(A)$, if Z is localized in K , then there exists $x \in K$ such that $N_\Theta(x) \subset Z$.

Proof If K is not compact, then there exists $T \subset \Theta$ which is an open cover of K with no finite subcover. Then W_K^T in (4.10) is a filter. Observe that $K \in W_K^T$. Theorem 4.25 yields $Z \in \mathcal{U}(A)$ with $W_K^T \subset Z$. Since T is an open cover of K , for each $x \in K$ there exists $O \in T$ with $x \in O$. We claim that $O \notin Z$. Indeed, $K \subset O \cup \complement O$ yields $\complement O \in W_K^T$, hence $\complement O \in Z$, thus $O \notin Z$.

If K is compact, $Z \in \mathcal{U}(A)$, and $K \in Z$, define $\Theta_Z \subset \Theta$ by $\Theta_Z \stackrel{\text{def}}{=} \{b \in \Theta : \complement b \in Z\}$. We claim that Θ_Z does not cover K , and hence there exists $x \in K$

with $x \notin \bigcup \Theta_Z$. If $U \in \Theta$ and $x \in U$ then $U \notin \Theta_Z$, and thus $\bigcup U \notin Z$, hence $U \in Z$, by Lemma 4.26. Hence $N_\Theta(x) \subset Z$.

We now prove the claim. If Θ_Z covers K , then a finite subcover of Θ_Z covers K , and since Θ_Z is closed under finite unions, K is contained in one of the sets in Θ_Z , hence $\bigcup K \in Z$, which is impossible since $K \in Z$. \square

4.5 Functorial Properties of Direct Images and Application to Limiting Values

Recall from Lemma 4.16 that if $Z \in \mathcal{F}(A)$ and $f \in \text{hom}_{\text{Set}}(A, Y)$, then $(f_*)_*(Z)$ is a filter base on Y .

Definition 4.31 If $Z \in \mathcal{F}(A)$ and $f \in \text{hom}_{\text{Set}}(A, Y)$, then the filter generated by $(f_*)_*(Z)$ on Y is denoted by $f_\diamond(Z)$ and is called *the image of Z by f* . Hence

$$f_\diamond(Z) \stackrel{\text{def}}{=} Y^\uparrow[(f_*)_*(Z)] = \{c \in \mathcal{P}_\bullet(Y) : \exists b \in Z, f_*(b) \subset c\} \in \mathcal{F}(Y). \tag{4.11}$$

Lemma 4.32 If $Z \in \mathcal{F}(A)$, and $f \in \text{hom}_{\text{Set}}(A, Y)$, then

$$f_\diamond(Z) = \{c \in \mathcal{P}_\bullet(Y) : f^*(c) \in Z\}.$$

Proof If $c \in f_\diamond(Z)$ then there exists $b \in Z$ with $f_*(b) \subset c$, hence $b \subset f^*(f_*(b)) \subset f^*(c)$, thus $f^*(c) \in Z$. If $c \in \mathcal{P}_\bullet(Y)$ then $f_*(f^*(c)) \subset c$, and if $f^*(c) \in Z$ then $c \in f_\diamond(Z)$. \square

Proposition 4.33 Assume that A and Y are filtered spaces, and $f \in \text{hom}_{\text{Set}}(A, Y)$. Then f is a filter-homomorphism if and only if

$$Z_Y \subset f_\diamond(Z_A).$$

Proof f is a filter-homomorphism iff $b \in Z_Y \Rightarrow f^*(b) \in Z_A$, and Lemma 4.32 says that this is the same as asking that $b \in Z_Y \Rightarrow b \in f_\diamond(Z_A)$, i.e., that $Z_Y \subset f_\diamond(Z_A)$. \square

Corollary 4.34 If (A, Z) is a filtered set, (Y, Θ) is a topological space, $f : A \rightarrow Y$ is a function, and $y \in Y$, then the following conditions are equivalent:

- (1) $\lim_Z f = y$,
- (2) $N_\Theta(y) \subset f_\diamond(Z)$.

Proof The result follows at once from Proposition 4.33 and Definition 1.12. \square

Corollary 4.35 If $Z \in \mathcal{U}(A)$ and $f \in \text{hom}_{\text{Set}}(A, Y)$, then $f_\diamond(Z) \in \mathcal{U}(Y)$.

Proof Since $Z \in \mathcal{U}(A)$, Lemma 4.26 implies that if $c \in \mathcal{P}_\bullet(Y)$ then either $f^*(c) \in Z$ or $\complement f^*(c) \in Z$, and thus, by Lemma 4.32, either $c \in f_\circ(Z)$ or $c \notin f_\circ(Z)$. Hence $f_\circ(Z) \in \mathcal{U}(Y)$ by Lemma 4.26. \square

Given a function $f : A \rightarrow Y$ we have thus defined the map

$$f_\circ : \mathcal{F}(A) \rightarrow \mathcal{F}(Y). \tag{4.12}$$

Observe that if $Z_1, Z_2 \in \mathcal{F}(A)$ and $Z_1 \subset Z_2$ then $f_\circ(Z_1) \subset f_\circ(Z_2)$. Hence we have almost completely proved the following result.

Lemma 4.36 *The assignment $A \mapsto \mathcal{F}(A)$ is the object function of a functor from the category of sets to the category of posets. The associated arrow function assigns to each function $f : A \rightarrow Y$ the order-preserving function $f_\circ : \mathcal{F}(A) \rightarrow \mathcal{F}(Y)$.*

Proof If $Z \in \mathcal{F}(A)$ then $c \in g_\circ(f_\circ(Z)) \Leftrightarrow g^*(c) \in f_\circ(Z) \Leftrightarrow (g \circ f)^*(c) = f^*(g^*(c)) \in Z$ for each $c \in \mathcal{P}_\bullet(A'')$, by Lemma 4.32 hence $g_\circ(f_\circ(Z)) = (g \circ f)_\circ(Z)$. \square

4.6 Extension of Filters from a Subset and Restriction to a Subset

If $\Omega \subsetneq A$ and $\iota : \Omega \rightarrow A$ is the standard injection, defined by $\iota(x) \stackrel{\text{def}}{=} x$, then the associated map

$$\iota_\circ : \mathcal{F}(\Omega) \rightarrow \mathcal{F}(A) \tag{4.13}$$

is injective, as we will see in Lemma 4.38, but this does not mean that if $Z \in \mathcal{F}(\Omega)$ then $Z \in \mathcal{F}(A)$. The following result clarifies this point.

Lemma 4.37 *If $\Omega \subsetneq A$ and $Z \in \mathcal{F}(\Omega)$ then $Z \notin \mathcal{F}(A)$.*

Proof Observe that Z only contains subsets of Ω , and $Z \in \mathcal{F}(A) \Rightarrow A \in Z$, which is impossible. \square

A precise description of the map (4.13) will now be given.

Lemma 4.38 *If $\Omega \subsetneq A$ and $Z \in \mathcal{F}(\Omega)$ then Z is a filter base on A ,*

$$A^\uparrow[Z] = \iota_\circ(Z) = \{b \in \mathcal{P}_\bullet(A) : \exists c \in Z, \exists d \in \mathcal{P}(A \setminus \Omega), b = c \cup d\} \tag{4.14}$$

and

$$Z \subset \iota_\circ(Z). \tag{4.15}$$

Proof The fact that Z is a filter base on A follows at once from $Z \in \mathcal{F}(\Omega)$. If $b \in A^\uparrow[Z]$ and $b \in A_d$ for some $d \in Z$, then $d \subset \Omega$, $d \subset b$, hence $b \cap \Omega \in Z$. Thus $b = [b \cap \Omega] \cup [b \cap (A \setminus \Omega)]$ with $b \cap \Omega \in Z$ since $d \subset b \cap \Omega \subset \Omega$ and $d \in Z$. If $b = c \cup d$, $c \in Z$, and $d \in \mathcal{P}(A \setminus \Omega)$, then $b \in A_c$ thus $b \in A^\uparrow[Z]$. The fact that ι_\circ is injective follows at once from (4.14). Finally, (4.15) follows at once from (4.14). \square

Definition 4.39 If $\Omega \subsetneq A$ and Z is a filter on Ω then the filter in (4.14) is a filter on A called the *extension of Z from Ω to A* .

Proposition 4.40 If $W \in \mathcal{F}(A)$ and $\Omega \subset A$, then the following conditions are equivalent:

- (1) W is weakly localized in Ω
- (2) For each $d \in W$, $\Omega \cap d \neq \emptyset$.
- (3) There exists a filter $\tilde{W} \supset W$ which is localized in Ω .
- (4) The following collection is a filter on Ω

$$Z \stackrel{\text{def}}{=} \{\Omega \cap b : b \in W\}. \tag{4.16}$$

Proof Let $Y \stackrel{\text{def}}{=} \{b\} \cup W$. Since W is a filter, then $\emptyset \notin Y^n$ means that $b \cap d \neq \emptyset$ for each $d \in W$. The equivalence between (2) and (3) then follows at once from Lemma 4.21. We now show that (1) and (2) are equivalent. If (2) does not hold then there exists $d \in W$ such that $b \cap d = \emptyset$, and this means that $d \subset \complement b$, hence $\complement b \in W$, i.e., (1) does not hold. If (1) does not hold then $\complement b \in W$, hence $b \cap \complement b = \emptyset$, hence (2) does not hold. Observe that (4) implies (2) at once, since no set in a filter can be empty. We now show that (2) implies (4). If $b_1 \in W$ and $b_2 \in W$ then $(\Omega \cap b_1) \cap (\Omega \cap b_2) = \Omega \cap (b_1 \cap b_2) \in Z$. Moreover, if $b \in W$ and $\Omega \cap b \subset d \subset \Omega$ then $b \cup d \supset b$, hence $b \cup d \in W$, and since $d = \Omega \cap (b \cup d)$, it follows that $d \in Z$. □

Definition 4.41 If $\Omega \subsetneq A$, and W is a filter on A which is weakly localized in Ω , then the filter in (4.16) is a filter on Ω called the *restriction of W from A to Ω* .

Theorem 4.42 If $\Omega \subsetneq A$ and $W \in \mathcal{F}(A)$ then the following conditions are equivalent:

- (1) There exists $Z \in \mathcal{F}(\Omega)$ such that $\iota_\circ(Z) = W$.
- (2) W is localized in Ω .

Proof Assume that (1) holds, and observe that $\Omega = \Omega \cup \emptyset$ and $\Omega \in Z$. Hence (4.14) implies that $\Omega \in W$. Assume that (2) holds. Then W is weakly localized in Ω , and Proposition 4.40 implies that the collection in (4.16) is a filter on Ω . We claim that $\iota_\circ(Z) = W$. Let $d \in \iota_\circ(Z)$. Then there exists $b \in W$ and $c \in \mathcal{P}(A \setminus \Omega)$ such that $d = (\Omega \cap b) \cup c$. Since $\Omega \in W$, it follows that $\Omega \cap b \in W$ and hence $d \in W$. Hence we have proved that $\iota_\circ(Z) \subset W$. Now let $d \in W$. Observe that $d = (\Omega \cap d) \cup (d \setminus \Omega)$. Let $c \stackrel{\text{def}}{=} \Omega \cap d$. Then $c \in Z$ and $d = c \cup (d \setminus \Omega)$ with $c \in Z$ and $d \setminus \Omega \in \mathcal{P}(A \setminus \Omega)$. Hence (4.14) implies that $d \in \iota_\circ(Z)$. Hence we have proved that $\iota_\circ(Z) \supset W$, and the proof is concluded. □

4.7 Separable Filters

Definition 4.43 If there exists a countable generating basis for a filter $Z \in \mathcal{F}(Y)$, we say that Z is *separable*.

In other words, Z is separable if there exists a countable subcollection $W \subset Z$ such that $Z \subset A^\uparrow[W]$.

Lemma 4.44 *If $Z \in \mathcal{F}(A)$, $B \subset Z$ and $C \subset Z$ are generating bases for Z , and C is countable, then there exists a countable subcollection $G \subset B$ such that G is a generating basis for Z .*

Proof Corollary 4.20 implies that $C \subset A^\uparrow[B]$, hence there is a map $\beta : C \rightarrow B$ such that, for each $c \in C$, $c \supset \beta(c)$. Define $G \stackrel{\text{def}}{=} \beta_*(C)$. Then G is a countable subcollection of B . Let $b \in Z$. Since C is a generating basis for Z , there exists $c \in C$ such that $b \supset c$. Since $c \supset \beta(c)$, it follows that $b \supset \beta(c)$. Since $\beta(c) \in G$ and $b \in Z$ is arbitrary, we have proved that $Z \subset A^\uparrow[G]$. Hence G is a generating basis for Z . \square

5 Proof of Theorem 3.29

If we specialize (3.11) to \mathbb{D} we obtain the following:

$$\text{dir}(\mathbb{D}) = \{R : R \text{ is a direction on } \mathbb{D}\}.$$

The goal of this section is to prove Theorem 3.29, a result which deals with the collection $\text{dir}(\mathbb{D})$ of all directions on \mathbb{D} . In Lemma 3.25 we have defined a function $R \mapsto \text{Fin}[R]$

$$\text{Fin} : \text{dir}(\mathbb{D}) \rightarrow \mathcal{F}(\mathbb{D}) \tag{5.1}$$

which maps every direction R on \mathbb{D} to the filter of tails of R , denoted by $\text{Fin}[R]$. Recall that there exists $S \in \mathcal{F}(\mathbb{D})$, called the *nontangential filter on \mathbb{D} ending at 1*, which has the following property

- (*) For each $w : \mathbb{D} \rightarrow \mathbb{R}$ and each $z \in \bar{\mathbb{R}}$, $\mathbf{lim}_S w = z$ if and only if, for each open Euclidean triangle T contained in \mathbb{D} and having 1 as a vertex, $\lim_{T \ni z \rightarrow x} w(z) = z$.

See [11, 12, 33], for background. It is convenient to replace the open Euclidean triangles which appear in (*) with the more symmetrical *nontangential approach regions in \mathbb{D} at 1*, as follows. For $\varrho > 0$, let

$$D[\varrho] \stackrel{\text{def}}{=} \{z \in \mathbb{C} : |z - 1| < \varrho\}$$

be the open disc in \mathbb{C} of center 1 and radius 1.

Definition 5.1 If $\alpha > 1$ define

$$\Gamma_\alpha \stackrel{\text{def}}{=} \left\{ z \in \mathbb{D} : \frac{|z - 1|}{1 - |z|} \leq \alpha \right\} \cap D[1]. \tag{5.2}$$

Remark If we used strict inequality in (5.2) (instead of the nonstrict inequality which appears inside the curly brackets) and if we were to omit the intersection with $D[1]$, then we would obtain *the same filter*, and hence the same notion of convergence, but

the proof would become a bit more involved. Indeed, observe that Γ_α contains the following set, which will be useful in the proof:

$$\partial\Gamma_\alpha \stackrel{\text{def}}{=} \left\{ z \in \mathbb{D} : \frac{|z - 1|}{1 - |z|} = \alpha \right\} \cap D[1]. \tag{5.3}$$

The nontangential filter S may now be defined as follows. Choose, once and for all, a bijective function

$$\alpha : \mathbb{N} \rightarrow (1, +\infty) \cap \mathbb{Q} \tag{5.4}$$

and let $\mathbb{Q}_+ \stackrel{\text{def}}{=} (0, +\infty) \cap \mathbb{Q}$. The set $\text{hom}_{\text{Set}}(\mathbb{N}, \mathbb{Q}_+)$ parametrizes a filter base on \mathbb{D} as follows: For $\mathbf{r} \in \text{hom}_{\text{Set}}(\mathbb{N}, \mathbb{Q}_+)$, let

$$Q(\mathbf{r}) \stackrel{\text{def}}{=} \bigcup_{n \in \mathbb{N}} \Gamma_{\alpha(n)} \cap D[\mathbf{r}(n)]. \tag{5.5}$$

Observe that $Q(\mathbf{r}) \subset \mathbb{D}$. Now define

$$B \stackrel{\text{def}}{=} \{Q(\mathbf{r}) : \mathbf{r} \in \text{hom}_{\text{Set}}(\mathbb{N}, \mathbb{Q}_+)\}. \tag{5.6}$$

Lemma 5.2 *The collection B is a filter base on \mathbb{D} .*

Proof If $\mathbf{r}, \mathbf{s} \in \text{hom}_{\text{Set}}(\mathbb{N}, \mathbb{Q}_+)$, define $\mathbf{p} \in \text{hom}_{\text{Set}}(\mathbb{N}, \mathbb{Q}_+)$ by setting $\mathbf{p}(n) \stackrel{\text{def}}{=} \mathbf{r}(n) \wedge \mathbf{s}(n)$. Observe that $Q(\mathbf{p}) \subset Q(\mathbf{r}) \cap Q(\mathbf{s})$. Lemma 4.11 implies that the collection B is a filter base on \mathbb{D} . □

Definition 5.3 *The nontangential filter on \mathbb{D} ending at 1 is the filter generated by B on \mathbb{D} , i.e., $S \stackrel{\text{def}}{=} \mathbb{D}\uparrow[B]$.*

Our goal is to prove the following statement.

- (♠) There exists no direction R on \mathbb{D} such that the filter of tails of R is equal to the nontangential filter S .

Indeed, we will prove that S does not belong to the image of the map (5.1). In other words, we will prove that the following set is empty:

$$\text{Fin}^*(S) \stackrel{\text{def}}{=} \{R \in \text{dir}(\mathbb{D}) : \text{Fin}[R] = S\}.$$

The following useful criterion follows at once from Lemma 3.26.

Lemma 5.4 *If $R \in \text{Fin}^*(S)$, $\omega : \mathbb{D} \rightarrow [-\infty, +\infty]$, and $z \in [-\infty, +\infty]$, then the following conditions are equivalent.*

- (1) $\lim_S \omega = z$,
- (2) $\lim_R \omega = z$.

The nontangential filter is related to the nontangential approach regions described in (5.2) as follows.

(**) For each $\omega : \mathbb{D} \rightarrow \mathbb{R}$ and each $z \in [-\infty, +\infty]$, $\lim_S \omega = z$ if and only if $\lim_{\Gamma_j \ni z \rightarrow x} \omega(z) = z$ for each $j \geq 1$.

Remark The fact that (**) holds implies that the choice made in (5.4) does not change the resulting filter. See [11].

If R is a direction on \mathbb{D} and $x \in \mathbb{D}$, the R -tail in \mathbb{D} from $x \in \mathbb{D}$ is defined just as in (3.9), with an emphasis on the direction rather than on the directed set:

$$\text{tail}_R(x) \stackrel{\text{def}}{=} \{z \in \mathbb{D} : xRz\}.$$

We will also need the following notion.

Definition 5.5 If $Q \in \mathcal{P}_\bullet(\mathbb{D})$, we write $Q \rightarrow 1$ if 1 belongs to the topological closure of Q in \mathbb{R}^2 .

Lemma 5.6 If $Q \rightarrow 1$ then there exists $f : Q \rightarrow \mathbb{R}$ such that $\lim_{Q \ni x \rightarrow 1} f(x)$ does not exist.

Proof Since $Q \rightarrow 1$, it is possible to define a sequence $\{r_j > 0\}_{j \geq 0}$ in such a way that $2 = r_0 > r_1 > \dots > r_j > r_{j+1}$ for each $j \geq 0$, $\lim_{j \rightarrow +\infty} r_j = 0$, and $Q_j \stackrel{\text{def}}{=} Q \cap (D[r_j] \setminus D[r_{j+1}]) \neq \emptyset$ for each j . The function $f : Q \rightarrow \mathbb{R}$ defined by setting $f(x) = (-1)^j$ if $x \in Q_j$ has the required property. \square

Lemma 5.7 If $R \in \text{Fin}^*(S)$, $x \in \mathbb{D}$, $\alpha > 1$, $Q \subset \Gamma_\alpha$, and $Q \rightarrow 1$, then $Q \cap \text{tail}_R(x) \neq \emptyset$.

Proof Assume that $R \in \text{dir}(\mathbb{D})$, $x \in \mathbb{D}$, $\alpha > 1$, $Q \subset \Gamma_\alpha$, $Q \rightarrow 1$, and $Q \cap \text{tail}_R(x) = \emptyset$. Define $\omega : \mathbb{D} \rightarrow \mathbb{R}$ as a function that vanishes identically on $\mathbb{D} \setminus Q$ and which on Q is equal to the function described in Lemma 5.6. Then $\lim_S \omega$ does not exist, by (**), but $\lim_R \omega$ exists. Indeed, $\lim_R \omega = 0$, since for each $\epsilon > 0$ the values of ω on the R -tail from x all lie in $(-\epsilon, \epsilon)$. Lemma 5.4 then implies that $R \notin \text{Fin}^*(S)$. \square

Lemma 5.8 If $R \in \text{Fin}^*(S)$, then $\text{Fin}[R]$ is separable.

Proof Let $q_n \stackrel{\text{def}}{=} 1 - \frac{1}{n}$, for each $n \in \mathbb{N}$ with $n \geq 1$ and let $Q \stackrel{\text{def}}{=} \{q_n : n \in \mathbb{N}, n \geq 1\}$. Then $Q \rightarrow 1$ and $Q \subset \Gamma_\alpha$ for each $\alpha > 1$. Let $C \stackrel{\text{def}}{=} \{b \in \mathcal{P}_\bullet(\mathbb{D}) : b = \text{tail}_R(q_n) \text{ for some } n \in \mathbb{N}\}$. Observe that C is countable and $C \subset \text{Fin}[R]$. Lemma 5.7 implies that for each $x \in \mathbb{D}$ there exists $n \in \mathbb{N}$ such that $q_n \in \text{tail}_R(x)$, i.e., $\text{tail}_R(x) \supset \text{tail}_R(q_n)$, and this means that $\text{Fin}[R] \subset \mathbb{D}^\uparrow[C]$. Hence C is a countable generating set for $\text{Fin}[R]$. \square

Lemma 5.9 If $G \subset B$ and G is countable, then $S \not\subset \mathbb{D}^\uparrow[G]$.

Proof Let $r_1, r_2, \dots, r_k, \dots$ be a sequence of elements of $\text{hom}_{\text{Set}}(\mathbb{N}, \mathbb{Q}_+)$ such that $G = \{Q(r_k) : k \in \mathbb{N}\}$. We claim that there exists $s \in \text{hom}_{\text{Set}}(\mathbb{N}, \mathbb{Q}_+)$ such that

$$\text{for each } k \in \mathbb{N}, \quad Q(r_k) \setminus Q(s) \neq \emptyset. \tag{5.7}$$

Hence $Q(s) \not\supseteq Q(r_k)$ for each $k \in \mathbb{N}$, and since $Q(s) \in S$, this means that $S \not\subseteq \mathbb{D}^\uparrow[G]$. We will construct $s \in \text{hom}_{\text{Set}}(\mathbb{N}, \mathbb{Q}_+)$ and a sequence $z_1, z_2, \dots, z_k, \dots$ of points in \mathbb{D} in such a way that, for each $k \in \mathbb{N}$,

$$z_k \in Q(r_k) \tag{5.8}$$

and

$$z_k \notin Q(s). \tag{5.9}$$

Since $Q(s) = \bigcup_{n \in \mathbb{N}} \Gamma_{\alpha(n)} \cap D[s(n)]$, in order to ensure that (5.9) holds it is necessary that, for each $n \in \mathbb{N}$,

$$z_k \notin \Gamma_{\alpha(n)} \cap D[s(n)]. \tag{5.10}$$

Recall that $\alpha : \mathbb{N} \rightarrow (0, +\infty) \cap \mathbb{Q}$ is an enumeration of the positive rationals larger than 1 chosen in (5.4) once and for all. For $k = 1, 2, \dots$, define an increasing sequence $\{n_k\}$ of positive integers with the following property: $\alpha(n_1) = 2$, $\alpha(n_2) > 2\alpha(n_1)$, and $\alpha(n_{k+1}) > 2\alpha(n_k)$ for each $k \geq 1$. Then define

$$I_1 \stackrel{\text{def}}{=} \{n \in \mathbb{N} : 1 < \alpha(n) < \alpha(n_1)\}$$

and, for each integer $j \geq 2$, define

$$I_j \stackrel{\text{def}}{=} \{n \in \mathbb{N} : \alpha(n_{j-1}) \leq \alpha(n) < \alpha(n_j)\}.$$

Then $\mathbb{N} = \bigcup_{j=1}^{+\infty} I_j$. Define $s \in \text{hom}_{\text{Set}}(\mathbb{N}, \mathbb{Q}_+)$ in such a way that

$$\begin{aligned} &\text{the restriction of } s \text{ to } I_j \text{ is constant and equal to } c_j \text{ and the sequence } \{c_j\} \\ &\text{is decreasing} \end{aligned} \tag{5.11}$$

The values c_j will be specified momentarily. Define

$$Q_1 \stackrel{\text{def}}{=} r_1(n_1) \wedge 1$$

and, for each $k \geq 2$,

$$Q_k \stackrel{\text{def}}{=} r_k(n_k) \wedge Q_{k-1}. \tag{5.12}$$

Choose

$$z_1 \in \partial\Gamma_{\alpha(n_1)} \cap D[\varrho_1] \quad \text{and then define} \quad c_2 \stackrel{\text{def}}{=} |1 - z_1|/2 \tag{5.13}$$

and, for each $k \geq 1$,

$$z_k \in \partial\Gamma_{\alpha(n_k)} \cap D[\varrho_k] \quad \text{and then define} \quad c_{k+1} \stackrel{\text{def}}{=} \frac{|1 - z_k|}{2} \wedge c_k. \tag{5.14}$$

Define $c_1 = |1 - z_1|$. Observe that (5.12) implies that, for each $k \in \mathbb{N}$,

$$z_k \in \partial\Gamma_{\alpha(n_k)} \cap D[\varrho_k] \subset \Gamma_{\alpha(n_k)} \cap D[r_k(n_k)] \subset Q(r_k).$$

Hence (5.8) holds for each $k \geq 1$.

In order to show that (5.10) holds for $k = 1$ and each $n \geq 1$, observe that if $n \in I_1$ then $\alpha(n) < \alpha(n_1)$, hence (5.13) implies that $z_1 \notin \Gamma_{\alpha(n)}$, hence (5.10) holds for these values of n . If $n \in I_2 \cup I_3 \cup \dots$ then (5.11) and (5.13) imply that $s(n) \leq c_2 < |1 - z_1|$, thus $z_1 \notin D[s(n)]$, hence (5.10) holds also for these values of n .

Now we show that (5.10) holds if $k = 2$ for all $n \in \mathbb{N}$. If $n \in I_1 \cup I_2$ then $\alpha(n) < \alpha(n_2)$, and hence (5.14) with $k = 2$ implies (5.10) for these values of n . If $n \in I_3 \cup I_4 \cup \dots$ then (5.11) implies that $s(n) \leq c_3$, and since (5.14) implies that $c_3 < |1 - z_2|$, it follows that $s(n) < |1 - z_2|$, hence $z_2 \notin D[s(n)]$, and (5.10) holds also for these values of n .

The proof of (5.10) for a generic value of k is similar, and is achieved by first showing that it holds if $n \in I_1 \cup I_2 \cup \dots \cup I_k$, and then by showing that it holds for $n \in I_k \cup I_{k+1} \cup \dots$. Indeed, in the first case, observe that $\alpha(n) < \alpha(n_k)$. Thus (5.14) implies that $z_k \notin \Gamma_{\alpha(n)}$, hence (5.10) holds. In the second case, (5.11) and (5.14) imply that $s(n) \leq c_{k+1} < |1 - z_k|$ hence $z_k \notin D[s(n)]$, and (5.10) holds also for these values of n .

□

Proposition 5.10 *The nontangential filter on \mathbb{D} ending at 1 is not separable.*

Proof Recall that the collection B , defined in (5.6), is a generating basis for S . Let us assume that S is separable. Then Lemma 4.44 implies that there exists a countable subcollection $G \subset B$ which is a generating basis for S , but this is impossible by Lemma 5.9. □

Proof of Theorem 3.29 Assume that the set $\text{Fin}^*(S)$ is not empty, and let $R \in \text{Fin}^*(S)$. Then Lemma 5.8 implies that $\text{Fin}[R]$ is separable. Now $R \in \text{Fin}^*(S)$ means that $\text{Fin}[R] = S$, hence it follows that S is separable, in contradiction with Proposition 5.10.

6 Applications to Set-Valued Moore–Smith Sequences

The goal of this section is to apply the results presented so far to Moore–Smith sequences of nonempty subsets of a given topological space. It seems to us that the

topic has an interest of its own, even though its application to the main task of this paper appears to be limited, both because of a lack of a topology, and for the reasons illustrated in Sect. 3.

Since Moore–Smith sequences of points are a special case of Moore–Smith sequences of nonempty subsets of the given topological space, we find it useful to begin with the former case.

6.1 Functorial Properties of the Filter of Tails

The convergence properties of a Moore–Smith sequence are entirely determined by the associated *filter of tails*, which is encoded in the operator

$$\begin{array}{c} \mathcal{S}(Y) \\ \downarrow t_Y \\ \mathcal{F}(Y) \end{array} \tag{6.1}$$

In Lemma 6.5 we will see that the map $Y \mapsto t_Y : \mathcal{S}(Y) \rightarrow \mathcal{F}(Y)$ a natural transformation between two functors. Recall that, if A is a directed set, then $\text{Fin}[A]$ is the filter of tails of A , described in Lemma 3.26.

Definition 6.1 If ω is a Y -valued Moore–Smith sequence and A is the direction of ω , then the *filter of tails of ω* is the filter on Y defined by

$$t_Y[\omega] \stackrel{\text{def}}{=} \omega_\circ(\text{Fin}[A]). \tag{6.2}$$

It follows that a filter base of $t_Y[\omega]$ is $\{\omega_\circ(\text{tail}_A(x)) : x \in A_{\text{Set}}\}$, i.e., the collection

$$\{\{\omega(r) : xRr\} : x \in A\}.$$

The following result says that the convergence properties of a Moore–Smith sequence are entirely determined by the associated filter of tails.

Theorem 6.2 *If $\omega \in \mathcal{S}(Y)$ is a Y -valued Moore–Smith sequence, Θ is a topology on Y , and $y \in Y$, the following conditions are equivalent*

- $\lim \omega = y$,
- $t_Y[\omega] \supset N_\Theta(y)$.

Proof It suffices to apply Lemma 3.26 and Corollary 4.34. □

In the following result, due to Bruns and Schmidt [5, p. 171], we show that the map (6.1) is onto, i.e., that for each $Z \in \mathcal{F}(Y)$ there exists $\omega \in \mathcal{S}(Y)$ such that $t_Y[\omega] = Z$.

Lemma 6.3 *If Y is a nonempty set, then every filter Z on Y is the filter of tails of a Y -valued Moore–Smith sequence ω .*

Proof Given a filter Z on Y , define

$$A \stackrel{\text{def}}{=} \{(\mathbf{b}, x) : \mathbf{b} \in Z, x \in \mathbf{b}\}, \tag{6.3}$$

consider the direction R on A defined by

$$(\mathbf{b}_1, x_1)R(\mathbf{b}_2, x_2) \text{ if and only if } \mathbf{b}_1 \supset \mathbf{b}_2,$$

and define

$$\omega : A \rightarrow Y$$

by $\omega(\mathbf{b}, x) \stackrel{\text{def}}{=} x$ for each $(\mathbf{b}, x) \in A$. If $x \in A$, i.e., $x \equiv (\mathbf{b}, x)$, for some $\mathbf{b} \in Z$ and some $x \in \mathbf{b}$, then

$$\{\omega(r) : xRr\} = \{\omega(\mathbf{b}', x') : (\mathbf{b}, x)R(\mathbf{b}', x')\} = \{x' : (\mathbf{b}, x)R(\mathbf{b}', x')\} = \mathbf{b}$$

hence $\text{t}_Y[\omega] = Z$. □

Lemma 6.3 may be strengthened so as to yield the following result, due to Bruns and Schmidt [5].

Lemma 6.4 *If Y is a nonempty set, then every filter Z on Y is the filter of tails of a Y -valued Moore–Smith sequence ω such that the direction of ω is antisymmetric.*

Proof Instead of (6.3), define

$$A \stackrel{\text{def}}{=} \{(\mathbf{b}, n, x) : \mathbf{b} \in Z, n \in \mathbb{N}, x \in \mathbf{b}\},$$

endowed with the lexicographic partial order R defined by $(\mathbf{b}_1, n_1, x_1)R(\mathbf{b}_2, n_2, x_2)$ if and only if

$$\mathbf{b}_1 \supsetneq \mathbf{b}_2 \text{ or } \mathbf{b}_1 = \mathbf{b}_2, \quad n_1 < n_2 \text{ or } \mathbf{b}_1 = \mathbf{b}_2, \quad n_1 = n_2, \quad x_1 = x_2.$$

Observe that R is an antisymmetric direction. Define the Moore–Smith sequence ω on A by $\omega(\mathbf{b}, n, x) \stackrel{\text{def}}{=} x$ for each $(\mathbf{b}, n, x) \in A$. Then $\text{t}_Y[\omega] = Z$. □

We now show that the function which associates to each nonempty set A the map in (6.1) is a natural transformation between the functor in Lemma 3.17 and the one in Lemma 4.36 (see [21] for background on categorical language).

Lemma 6.5 *For each pair of nonempty sets Y and X and every $f : Y \rightarrow X$, the diagram (6.4) is commutative.*

$$\begin{array}{ccc}
 \mathcal{S}(Y) & \xrightarrow{f_\circ} & \mathcal{S}(X) \\
 \downarrow \tau_Y & & \downarrow \tau_X \\
 \mathcal{F}(Y) & \xrightarrow{f_\circ} & \mathcal{F}(X)
 \end{array} \tag{6.4}$$

Proof If $w \in \mathcal{S}(Y)$ and $d \in \tau_X[f_\circ(w)]$, then there exists $x \in A_{\text{Set}}$ such that $d \supset (f_\circ(w))_*(\text{tail}_A(x))$, and $(f_\circ(w))_*(\text{tail}_A(x)) = (f \circ w)_*(\text{tail}_A(x)) = (f_* \circ w_*)(\text{tail}_A(x)) = f_*(w_*(\text{tail}_A(x)))$. It follows that $w_*(\text{tail}_A(x)) \in \tau_Y[w]$ and $d \supset f_*(w_*(\text{tail}_A(x)))$, and this means that $d \in f_\circ(\tau_Y[w])$. We have thus proved that $f_\circ(\tau_Y[w]) \supset \tau_X[f_\circ(w)]$. In order to prove that $f_\circ(\tau_Y[w]) \subset \tau_X[f_\circ(w)]$, it suffices to follow these steps backwards. \square

6.2 Set-Valued Moore–Smith Sequences

We will examine not only Y -valued Moore–Smith sequences (where Y is a given topological space) but also $\mathcal{P}_\bullet(Y)$ -valued Moore–Smith sequences, and show that the latter category of Moore–Smith sequences enjoys properties that are more streamlined with respect to the Y -valued Moore–Smith sequences. We now show that the second class of Moore–Smith sequences includes the first one.

Definition 6.6 The injective function

$$\mathcal{S}(Y) \hookrightarrow \mathcal{S}(\mathcal{P}_\bullet(Y)) \tag{6.5}$$

maps $w : A \rightarrow Y$ to the function $A \rightarrow \mathcal{P}_\bullet(Y)$ (still denoted by w) which maps $k \in A$ to $\{w(k)\} \in \mathcal{P}_\bullet(Y)$.

Observe that the injective map (6.5) is obtained by composition of $w : A \rightarrow Y$ with the natural injection $\iota_Y : Y \rightarrow \mathcal{P}_\bullet(Y)$ given by $\iota_Y(x) \stackrel{\text{def}}{=} \{x\}$. Hence we will think of $\mathcal{S}(Y)$ as a subset of $\mathcal{S}(\mathcal{P}_\bullet(Y))$, i.e., we will identify $w : A \rightarrow Y$ with $\iota_Y \circ w$.

Lemma 6.7 *The assignment $Y \mapsto \mathcal{S}(\mathcal{P}_\bullet(Y))$ is the object function of a functor from the category of sets to the category of sets. The associated arrow function assigns to each function $f : Y \rightarrow X$ the function $f_\circ : \mathcal{S}(\mathcal{P}_\bullet(Y)) \rightarrow \mathcal{S}(\mathcal{P}_\bullet(X))$ which maps $w \in \mathcal{S}(\mathcal{P}_\bullet(Y))$ to $f_* \circ w \in \mathcal{S}(\mathcal{P}_\bullet(X))$.*

Proof The proof follows at once from the fact that the composition of functions is associative. \square

The function $f_\circ : \mathcal{S}(\mathcal{P}_\bullet(Y)) \rightarrow \mathcal{S}(\mathcal{P}_\bullet(X))$, restricted to $\mathcal{S}(Y)$, recaptures the function described in Lemma 3.17. For this reason, it is denoted by the same symbol. Recall that in Sect. 6.1 the map

$$\tau_Y : \mathcal{S}(Y) \rightarrow \mathcal{F}(Y) \tag{6.6}$$

has been defined, which associates to each $\omega \in \mathcal{S}(Y)$ the filter $\tau_Y[\omega] \in \mathcal{F}(Y)$, called the filter of tails of ω , and recall the natural injection (6.5)

$$\mathcal{S}(Y) \hookrightarrow \mathcal{S}(\mathcal{P}_\bullet(Y)).$$

In Lemma 6.9 we show that the dotted arrow in the following diagram may be defined so as to make it commutative:

$$\begin{array}{ccc} \mathcal{S}(Y) & \hookrightarrow & \mathcal{S}(\mathcal{P}_\bullet(Y)) \\ & \searrow \tau_Y & \downarrow \tau_Y \\ & & \mathcal{F}(Y) \end{array} \tag{6.7}$$

Definition 6.8 If ω is a $\mathcal{P}_\bullet(Y)$ -valued Moore–Smith sequence, then a *tail* of ω is a subset of Y of the form

$$\text{Tail}_j[\omega] \stackrel{\text{def}}{=} \{x \in Y : x \in \omega(k) \text{ for some } k \in A_{\text{Set}} \text{ with } jRk\}, \tag{6.8}$$

where A is the direction of ω and $j \in A_{\text{Set}}$. The collection

$$\tau_Y[\omega] \stackrel{\text{def}}{=} \{Q \in \mathcal{P}_\bullet(Y) : Q \text{ is a superset of some tail of } \omega\} \tag{6.9}$$

is called the *filter on Y generated by the tails of ω* . This terminology is justified by the following result.

Lemma 6.9 *If ω is a $\mathcal{P}_\bullet(Y)$ -valued Moore–Smith sequence, then the collection $\tau_Y[\omega]$ defined in (6.9) is a filter on X , and the map $\omega \in \mathcal{S}(\mathcal{P}_\bullet(Y)) \mapsto \tau_Y[\omega] \in \mathcal{F}(Y)$ makes the diagram (6.7) commutative.*

Proof The first statement follows from the fact that the collection of tails, defined in (6.8), forms a filter base. Indeed, given $j_1, j_2 \in A_{\text{Set}}$, there exists $j_3 \in A_{\text{Set}}$ such that j_1Rj_3 and j_2Rj_3 , and then it follows that $\text{Tail}_{j_3}[\omega] \subset \text{Tail}_{j_1}[\omega] \cap \text{Tail}_{j_2}[\omega]$. The second statement follows at once from the identification of $\omega \in \mathcal{S}(Y)$ with the element of $\mathcal{S}(\mathcal{P}_\bullet(Y))$ described in Definition (6.6). □

Hence, for every nonempty set Y , we have defined a map

$$\tau_Y : \mathcal{S}(\mathcal{P}_\bullet(Y)) \rightarrow \mathcal{F}(Y). \tag{6.10}$$

Consider the following diagram:

$$\begin{array}{ccc} \mathcal{S}(\mathcal{P}_\bullet(Y)) & \xrightarrow{f_\circ} & \mathcal{S}(\mathcal{P}_\bullet(X)) \\ \tau_Y \downarrow & & \tau_X \downarrow \\ \mathcal{F}(Y) & \xrightarrow{f_\circ} & \mathcal{F}(X) \end{array} \tag{6.11}$$

Lemma 6.10 *For each nonempty sets Y and X and every $f : Y \rightarrow X$, (6.11) is commutative.*

Proof It suffices to prove that $f_\circ(T_Y[\mathcal{w}]) = T_X[f_\circ(\mathcal{w})]$ for each $\mathcal{w} \in \mathcal{S}(\mathcal{P}_\bullet(Y))$. Let $\mathfrak{b} \in f_\circ(T_Y[\mathcal{w}])$. Then there exists $Q \in \mathcal{P}_\bullet(Y)$ such that $Q \in T_Y[\mathcal{w}]$ and $f_*(Q) \subset \mathfrak{b}$. Hence there exists $j \in A_{\text{Set}}$, where A is the direction of \mathcal{w} , such that $\text{Tail}_j[\mathcal{w}] \subset Q$. We claim that $\text{Tail}_j[f_\circ(\mathcal{w})] \subset \mathfrak{b}$, and hence $\mathfrak{b} \in T_X[f_\circ(\mathcal{w})]$. In order to prove the claim, observe that if $x \in \text{Tail}_j[f_\circ(\mathcal{w})]$ then $x \in (f_\circ(\mathcal{w}))(k) = f_*[\mathcal{w}(k)]$ for some $k \in A_{\text{Set}}$ with jRk . Hence there exists $y \in \mathcal{w}(k)$ such that $f(y) = x$. Thus $y \in \text{Tail}_j[\mathcal{w}]$ (since jRk) and $y \in Q$ (since $\text{Tail}_j[\mathcal{w}] \subset Q$), hence $x = f(y) \in \mathfrak{b}$ (since $f_*(Q) \subset \mathfrak{b}$).

If $\mathfrak{b} \in T_X[f_\circ(\mathcal{w})]$ then there exists $j \in A_{\text{Set}}$ such that $\text{Tail}_j[f_\circ(\mathcal{w})] \subset \mathfrak{b}$. We claim that $f_*(\text{Tail}_j[\mathcal{w}]) \subset \mathfrak{b}$, and hence $\mathfrak{b} \in f_\circ(T_Y[\mathcal{w}])$. In order to prove the claim, let $y \in \text{Tail}_j[\mathcal{w}]$ and $x = f(y)$. Then $y \in \mathcal{w}(k)$ for some $k \in A_{\text{Set}}$ with jRk . Then $x = f(y) \in f_*(\mathcal{w}(k)) = (f_\circ(\mathcal{w}))(k) \subset \text{Tail}_j[f_\circ(\mathcal{w})] \subset \mathfrak{b}$. □

Observe that Lemma 6.10 says that the assignment $Y \mapsto T_Y : \mathcal{S}(\mathcal{P}_\bullet(Y)) \rightarrow \mathcal{F}(Y)$ is a natural transformation from the functor $A \mapsto \mathcal{S}(\mathcal{P}_\bullet(A))$, $f \mapsto f_\circ$ to the functor $Y \mapsto \mathcal{F}(Y)$, $f \mapsto f_\circ$.

Definition 6.11 If $Z \in \mathcal{F}(Y)$, $\mathcal{w} \in \mathcal{S}(\mathcal{P}_\bullet(Y))$, and $T_Y[\mathcal{w}] = Z$ then we say that Z is represented by \mathcal{w} .

We now show that every filter on Y is the filter generated by the tails of a generalized sequence of nonempty subsets of Y .

Definition 6.12 From Example 3.15 we obtain a map

$$\mathcal{F}(Y) \rightarrow \mathcal{S}(\mathcal{P}_\bullet(Y)) \tag{6.12}$$

as follows: If $Z \in \mathcal{F}(Y)$, then the natural injection

$$s_Z : Z \rightarrow \mathcal{P}_\bullet(Y) \tag{6.13}$$

defined, for each $\mathfrak{b} \in Z$, by $s_Z(\mathfrak{b}) \stackrel{\text{def}}{=} \mathfrak{b}$, is a $\mathcal{P}_\bullet(Y)$ -valued Moore–Smith sequence. The proof of the following result is independent of Lemma 6.3.

Lemma 6.13 *If $Z \in \mathcal{F}(Y)$ then $T_Y[s_Z] = Z$, hence the map $T_Y : \mathcal{S}(\mathcal{P}_\bullet(Y)) \rightarrow \mathcal{F}(Y)$ is onto.*

Proof If $Z \in \mathcal{F}(Y)$ consider $s_Z : Z \rightarrow \mathcal{P}_\bullet(Y)$ described in Definition 6.12, where (Z, \supset) is directed by reverse set inclusion. Then s_Z is a $\mathcal{P}_\bullet(Y)$ -valued Moore–Smith sequence. Observe that if $\mathfrak{c} \in Z$ then

$$\text{Tail}_\mathfrak{c}[s_Z] = \mathfrak{c}$$

hence $T_Y[s_Z] = Z$. □

Lemma 6.13 says that a filter Z is represented by the generalized sequence $s_Z : Z \rightarrow \mathcal{P}_\bullet(Y)$. The following result follows at once from Lemmas 6.10 and 6.13.

Corollary 6.14 *If $f : Y \rightarrow X$ is a function and $Z \in \mathcal{F}(Y)$ then*

$$f_\circ(Z) = T_Y[f_\circ(s_Z)].$$

7 Proof of Theorem 3.33

Assume that $V = \{\omega_\alpha\}_{\alpha \in I}$, where I is a set of indices and $\omega_\alpha : D_\alpha \rightarrow A$, where D_α is a directed set. Consider the filter

$$Z \stackrel{\text{def}}{=} \bigwedge_{\alpha \in I} (\omega_\alpha)_\circ(\text{Fin}[D_\alpha]).$$

Now observe that \mathcal{F}_V , defined in (3.20), is equal to $c_A(Z)$, and apply Theorem 3.2. □

8 Proof of Theorem 3.37

Let \mathcal{F} be a functional convergence class on A . Theorem 3.7 implies that there exists a filter Z on A such that $\mathcal{F} = c_A(Z)$. Lemma 6.3 implies that there exists a Moore–Smith sequence $\omega : D \rightarrow A$, where D is a directed set, such that $Z = t_Y[\omega]$. Recall that $t_Y[\omega] = \omega_\circ(\text{Fin}[D])$. Let $\varphi \in \text{hom}_{\text{Set}}(A, \mathbb{R})$ and $y \in \mathbb{R}$. Then $(y, \varphi) \in \mathcal{F}$ if and only if $\lim_Z \varphi = y$ (since $\mathcal{F} = c_A(Z)$). Corollary 4.34 implies that $\lim_Z \varphi = y$ if and only if $N_{\mathbb{R}}(y) \subset \varphi_\circ(Z)$. Since $Z = t_Y[\omega] = \omega_\circ(\text{Fin}[D])$, it follows that $N_{\mathbb{R}}(y) \subset \varphi_\circ(Z)$ if and only if $N_{\mathbb{R}}(y) \subset \varphi_\circ(\omega_\circ(\text{Fin}[D]))$. Lemma 4.36 implies that $\varphi_\circ(\omega_\circ(\text{Fin}[D])) = (\varphi \circ \omega)_\circ(\text{Fin}[D])$. Hence $(y, \varphi) \in \mathcal{F}$ if and only if $N_{\mathbb{R}}(y) \subset (\varphi \circ \omega)_\circ(\text{Fin}[D])$. Theorem 6.2 implies that $N_{\mathbb{R}}(y) \subset (\varphi \circ \omega)_\circ(\text{Fin}[D])$ if and only if $\lim \varphi \circ \omega = y$. Hence $(y, \varphi) \in \mathcal{F}$ if and only if $\lim \varphi \circ \omega = y$. □

9 A Natural Topology on the Collection of Filters

The goal of this section is to show that the collection $\mathcal{F}(A)$ of all filters on a given set A is naturally endowed with a topology. This result, among many others, indicates that filters are intrinsically associated to the notion of convergence.

9.1 Topological Preliminaries

Observe that, if Θ is a topology on a nonempty set X , then (1.16) defines a function

$$N_\Theta : X \rightarrow \mathcal{F}(X) \tag{9.1}$$

called the *family of (neighborhood) filters associated to* Θ . Observe that the map $\Theta \mapsto N_\Theta$ is injective, i.e., Θ may be recaptured from N_Θ . Indeed, $Q \in \Theta$ if and only if for each $x \in Q$ there exists $U \in N_\Theta(x)$ such that $x \in U \subset Q$.

Definition 9.1 A function $N : X \rightarrow \mathcal{F}(X)$ is called a *family of filters on X based on X*.

We now list some properties that a map $\varphi : \mathcal{P}(X) \rightarrow \mathcal{P}(X)$ may have.

Definition 9.2 A map $\varphi : \mathcal{P}(X) \rightarrow \mathcal{P}(X)$ may have one or more of the following properties.

- (pas) (φ preserves the ambient space) $\varphi(X) = X$.
- (pfi) (φ preserves finite intersections) $\varphi(Q \cap R) = \varphi(Q) \cap \varphi(R)$ for all $Q, R \in \mathcal{P}(X)$.
- (c) (φ is a contraction) $\varphi(Q) \subset Q$ for each $Q \in \mathcal{P}(X)$.
- (idem) (φ is idempotent) $\varphi(\varphi(Q)) = \varphi(Q)$ for each $Q \in \mathcal{P}(X)$.
- (mi) (φ is monotone increasing) $Q \subset R \implies \varphi(Q) \subset \varphi(R)$ for all $Q, R \in \mathcal{P}(X)$.
- (d) (φ is deflating) $\varphi(\varphi(Q)) \subset \varphi(Q)$ for each $Q \in \mathcal{P}(X)$.
- (i) (φ is inflating) $\varphi(Q) \subset \varphi(\varphi(Q))$ for each $Q \in \mathcal{P}(X)$.
- (pfu) (φ preserves finite unions) $\varphi(Q \cup R) = \varphi(Q) \cup \varphi(R)$ for all $Q, R \in \mathcal{P}(X)$.

A map $\varphi : \mathcal{P}(X) \rightarrow \mathcal{P}(X)$ is called *regular* if it preserves the ambient space and finite intersections, and is an idempotent contraction. Observe that (pas) and (pfi) say that φ is a homomorphism of the multiplicative semigroup of $\mathcal{P}(X)$ as a Boolean algebra (see Sect. 9.3).

Observe that

$$(pfi) \implies (mi); \quad (c) \ \& \ (pfi) \implies (d); \quad (c) \ \& \ (mi) \ \& \ (i) \implies (idem). \quad (9.2)$$

Indeed, $Q \subset R \implies \varphi(Q) = \varphi(Q \cap R) \stackrel{(pfi)}{=} \varphi(Q) \cap \varphi(R) \subset \varphi(R)$, while $(\varphi(Q) \subset Q) \stackrel{(c)}{\implies} \varphi(\varphi(Q)) \subset \varphi(Q)$.

Lemma 9.3 *If Θ is a topology on X, then the associated topological interior operator $\mathcal{I}_\Theta : \mathcal{P}(X) \rightarrow \mathcal{P}(X)$, defined by $\mathcal{I}_\Theta(Q) \stackrel{\text{def}}{=} \{x : x \in Q, \exists U \in \Theta, x \in U \subset Q\}$, is a regular map. The map $\Theta \mapsto \mathcal{I}_\Theta$ is injective since $Q \in \Theta$ if and only if $\mathcal{I}_\Theta(Q) = Q$.*

Proof We omit the proof, which follows immediately from the notion of topology. \square

Proposition 9.4 ([19]) *Every regular map $\mathcal{I} : \mathcal{P}(X) \rightarrow \mathcal{P}(X)$ is the topological interior operator associated to a (unique) topology.*

Proof Define $\Theta_{\mathcal{I}} \stackrel{\text{def}}{=} \{Q \in \mathcal{P}(X) : Q = \mathcal{I}(Q)\}$. Then $\Theta_{\mathcal{I}}$ is a topology on X and $\mathcal{I} = \mathcal{I}_{\Theta_{\mathcal{I}}}$. \square

To every map $N : X \rightarrow \mathcal{F}(X)$, we associate the map

$$\mathring{N} : \mathcal{P}(X) \rightarrow \mathcal{P}(X)$$

defined by $\mathring{N}(Q) \stackrel{\text{def}}{=} \{x \in X : Q \in N(x)\}$. We may write N° instead of \mathring{N} for typographical reasons (for example, we do it in the proof of Theorem 9.7). Observe that the map $N \mapsto \mathring{N}$ is injective, i.e., N may be recaptured from \mathring{N} . Indeed

$$N(x) = \{Q \in \mathcal{P}(X) : x \in \mathring{N}(Q)\}.$$

Observe that

$$\text{if } \mathring{N} = \mathcal{I}_\Theta \text{ for some topology } \Theta \text{ then } N = N_\Theta \tag{9.3}$$

and that, if Θ is a topology on X , then

$$\mathcal{I}_\Theta = (N_\Theta)^\circ. \tag{9.4}$$

Corollary 9.5 *For each map $N : X \rightarrow \mathcal{P}(X)$ the following conditions are equivalent.*

- (t) $N : X \rightarrow \mathcal{P}(X)$ is the family of filters associated to a topology
- (r) $\mathring{N} : \mathcal{P}(X) \rightarrow \mathcal{P}(X)$ is a regular map.

Proof **t** \Rightarrow **r** follows from (9.4) and Lemma 9.3; **r** \Rightarrow **t** follows from (9.3) and Proposition 9.4. □

Lemma 9.6 *For each map $N : X \rightarrow \mathcal{F}(X)$, \mathring{N} preserves the ambient space and finite intersections.*

Proof The result follows at once from the properties of filters. □

Theorem 9.7 ([8]) *For each map $N : X \rightarrow \mathcal{F}(X)$, the following conditions are equivalent:*

- (t) N is the family of neighborhood filters associated to some topology on X .
- (r) $\mathring{N} : \mathcal{P}(X) \rightarrow \mathcal{P}(X)$ is an inflating contraction.

Proof If $N = N_\Theta$ for a topology N , then (9.4) implies that $\mathcal{I}_\Theta = (N_\Theta)^\circ = \mathring{N}$, hence Lemma 9.3 yields the result. If $\mathring{N} : \mathcal{P}(X) \rightarrow \mathcal{P}(X)$ is an inflating contraction, then it is a regular map by (9.2) and Lemma 9.6. Proposition 9.4 then implies that \mathring{N} is the topological interior operator of some topology, say Θ . Hence (9.3) implies that $N = N_\Theta$. □

We now wish to express Condition (r) in Theorem 9.7 directly in terms of N .

Proposition 9.8 *For each map $N : X \rightarrow \mathcal{F}(X)$, the following conditions are equivalent:*

- (t) N is the family of neighborhood filters associated to some topology on X .
- (r) \mathring{N} is an inflating contraction
- (r') $x \in X, Q \in N(x) \Rightarrow x \in Q$ and $\exists R \in N(x)$ such that $y \in R \Rightarrow Q \in N(y)$.

Observe that the set R is necessarily contained in Q .

Proof In Theorem 9.7 we proved that **(t)** and **(r)** are equivalent, hence it suffices to show that **(r)** and **(r')** are equivalent. Assume that **(r)** holds. Then \mathring{N} is regular [by Lemma 9.6 and (9.2)]. Hence if $x \in X$ and $Q \in N(x)$ then $x \in \mathring{N}(Q) \stackrel{(c)}{\subset} Q$, hence $x \in Q$; moreover $x \in \mathring{N}(Q) \stackrel{(\text{idem})}{=} \mathring{N}(\mathring{N}(Q)) \Rightarrow x \in \mathring{N}(\mathring{N}(Q)) \Rightarrow \mathring{N}(Q) \in N(x)$ and if $y \in \mathring{N}(Q)$ then $Q \in N(y)$, hence $R \stackrel{\text{def}}{=} \mathring{N}(Q)$ has the property in **(r')**. Assume that **(r')** holds. Then $Q \subset X$ & $x \in \mathring{N}(Q) \Rightarrow Q \in N(x) \stackrel{(r')}{\Rightarrow} x \in Q$, hence $\mathring{N}(Q) \subset Q$, i.e., \mathring{N} is a contraction. If $x \in \mathring{N}(Q)$ then $Q \in N(x)$ and thus by **(r')** there exists $R \in N(x)$ with $y \in R \Rightarrow Q \in N(y)$, i.e., $y \in R \Rightarrow y \in \mathring{N}(Q)$, i.e., $R \subset \mathring{N}(Q)$, and since $R \in N(x)$ and $N(x)$ is a filter on X it follows that $\mathring{N}(Q) \in N(x)$, i.e., $x \in \mathring{N}(\mathring{N}(Q))$. Hence $x \in \mathring{N}(Q) \Rightarrow x \in \mathring{N}(\mathring{N}(Q))$, i.e., \mathring{N} is inflating. \square

Hence in order to describe a topology on $\mathcal{F}(A)$, it suffices to describe a map $N : \mathcal{F}(A) \rightarrow \mathcal{F}(\mathcal{F}(A))$ such that $\mathring{N} : \mathcal{P}(\mathcal{F}(A)) \rightarrow \mathcal{P}(\mathcal{F}(A))$ is an inflating contraction. We first need some more preliminary work.

9.2 Further Lattice-Theoretic Properties of $\mathcal{F}(A)$

We now go back to a question that was left open in Sect. 4.1, to wit: the existence in $\mathcal{F}(A)$, seen as a poset, of the l.u.b. of two given filters $Z_1, Z_2 \in \mathcal{F}(A)$. Recall from Sect. 4.1 that the l.u.b. of $Z_1, Z_2 \in \mathcal{F}(A)$ (called the *join* of Z_1 and Z_2), if it exists, is denoted $Z_1 \vee Z_2$ and has the following two properties: (i) $Z_1 \subset Z_1 \vee Z_2$ and $Z_2 \subset Z_1 \vee Z_2$, and (ii) if $W \in \mathcal{F}(A)$, $Z_1 \subset W$ and $Z_2 \subset W$, then $Z_1 \vee Z_2 \subset W$. We now show that the obstruction to the existence of the join of two filter lies in the existence of a filter which contains both. The following result follows at once from Lemma 4.21. However, it is instructive to provide a direct proof.

Lemma 9.9 *If $b, c \in \mathcal{P}_\bullet(A)$ and $b \cap c = \emptyset$ then there is no filter on A which contains both A_b and A_c .*

Proof If $Z \in \mathcal{F}(A)$, $A_b \subset Z$, and $A_c \subset Z$, then $b, c \in Z$ and $b \cap c = \emptyset$, which is impossible. \square

These lattice-theoretic issues are actually useful in order to gain a better understanding of the topological implications of the notion of filter, as we will see.

Definition 9.10 If $Z, W \in \mathcal{F}(A)$ and $Z \vee W$ exists, we write

$$Z \bowtie W. \tag{9.5}$$

We read “ $Z \bowtie W$ ” as “ Z and W intertwine.” If $b \in \mathcal{P}_\bullet(A)$ and $A_b \bowtie Z$ [where A_b is the principal filter generated by b over A , defined in (4.2)] then we write $b \bowtie Z$.

Observe that $Z \bowtie W$ if and only if, for each $b \in Z$, $b \bowtie W$.

Definition 9.11 If $Z, W \in \mathcal{F}(A)$ and $Z \vee W$ does not exist, we write

$$Z \triangleleft \triangleright W. \tag{9.6}$$

We read “ $Z \triangleleft \triangleright W$ ” as “ Z and W are eventually disjoint.”

See [11] for the motivation behind this terminology. In order to clarify this terminology and its meaning, observe that (4.2) defines an injective map

$$\epsilon_A : \mathcal{P}_\bullet(A) \hookrightarrow \mathcal{F}(A). \tag{9.7}$$

Hence $\mathcal{F}(A)$ contains a copy of $\mathcal{P}_\bullet(A)$.

If A is a nonempty set and if $f : A \rightarrow Y$ is a function, then we have the following diagram, where ϵ_A and ϵ_Y are given in (9.7), f_* is given in (2.1), and f_\diamond in (4.12)

$$\begin{array}{ccc} \mathcal{F}(A) & \xrightarrow{f_\diamond} & \mathcal{F}(Y) \\ \uparrow \epsilon_A & & \uparrow \epsilon_Y \\ \mathcal{P}_\bullet(A) & \xrightarrow{f_*} & \mathcal{P}_\bullet(Y) \end{array} \tag{9.8}$$

The following result says that the map $A \mapsto \epsilon_A$ is a natural transformation from the functor

$$A \mapsto \mathcal{P}_\bullet(A), \quad f \mapsto f_*$$

to the functor

$$A \mapsto \mathcal{F}(A), \quad f \mapsto f_\diamond.$$

Lemma 9.12 For each nonempty set A and Y and every $f : A \rightarrow Y$, the diagram (9.8) is commutative.

Proof If $c \in f_\diamond(A_b)$ where $b \in \mathcal{P}_\bullet(A)$, then there exists $d \in A_b$ and $f_*(d) \subset c$. Thus $b \subset d$, hence $f_*(b) \subset f_*(d)$, so $f_*(b) \subset c$, i.e., $c \in A_{f_*(b)}$. Hence $f_\diamond(A_b) \subset A_{f_*(b)}$. If $c \in A_{f_*(b)}$ then $f_*(b) \subset c$. Since $b \in A_b$, it follows that $c \in f_\diamond(A_b)$. Hence $f_\diamond(A_b) = A_{f_*(b)}$. \square

Consider also the natural injection

$$\iota_A : A \rightarrow \mathcal{P}_\bullet(A), \tag{9.9}$$

given by $\iota_A(x) \stackrel{\text{def}}{=} \{x\}$. Lemma 4.23 says that the composition of (9.9) with (9.7) yields the injection

$$A \hookrightarrow \mathcal{F}(A) \tag{9.10}$$

which maps $x \in A$ to the principal ultrafilter generated by x over A .

Lemma 9.13 *The injective map (9.7) is order reversing. That is, if $b_1, b_2 \in \mathcal{P}_\bullet(A)$ then*

$$A_{b_1} \wedge A_{b_2} = A_{b_1 \cup b_2}. \tag{9.11}$$

Proof The fact that if $b \subset c$ then $A_b \supset A_c$ follows at once from transitivity of inclusion. Observe that $b_1 \cup b_2 \subset c$ if and only if $b_1 \subset c$ and $b_2 \subset c$, hence (9.11) follows at once. \square

Lemma 9.14 *If $b_1, b_2 \in \mathcal{P}_\bullet(A)$ then the following conditions are equivalent:*

- (1) $A_{b_1} \bowtie A_{b_2}$,
- (2) b_1 and b_2 overlap (as sets).

If any of these conditions hold, then

$$A_{b_1} \vee A_{b_2} = A_{b_1 \cap b_2}.$$

Proof It suffices to apply Lemma 4.21 \square

The following result also follows from Lemma 4.21.

Lemma 9.15 *If $Z_1, Z_2 \in \mathcal{F}(A)$ then the following conditions are equivalent:*

- (1) $Z_1 \bowtie Z_2$,
- (2) $b_1 \cap b_2 \neq \emptyset$ for each $b_1 \in Z_1$ and each $b_2 \in Z_2$.

Proof If (1) holds then $Z_1 \vee Z_2$ is a filter which contains both Z_1 and Z_2 , hence if $b_1 \in Z_1$ and $b_2 \in Z_2$ then both b_1 and b_2 belong to $Z_1 \vee Z_2$ and therefore their intersection cannot be empty. If (2) holds, then $Z_1 \cup Z_2$ is a filter subbase, and Lemma 4.21 implies that there exists a filter Z which contains $Z_1 \cup Z_2$. \square

Lemma 9.15 says that b and Z intertwine if and only if b and c overlap for each $c \in Z$. This result implies at once the following one.

Corollary 9.16 *The filters $Z_1, Z_2 \in \mathcal{F}(A)$ are eventually disjoint if and only if there exist sets $b_1 \in Z_1$ and $b_2 \in Z_2$ such that $b_1 \cap b_2 = \emptyset$.*

9.3 Boolean Algebras

In this section, we prove some useful results which highlight the connection between filters (ultrafilters) and the algebraic structure of a *Boolean algebra*.

Definition 9.17 A *Boolean algebra* is a ring R with unity where $a^2 = a$ for each $a \in R$. A function $f : R_1 \rightarrow R_2$ between Boolean algebras R_1 and R_2 is called a *Boolean algebra homomorphism* if $f(a+b) = f(a) + f(b)$ and $f(b \cdot c) = f(b) \cdot f(c)$ for all $b, c \in R_1$.

The collection of Boolean algebra homomorphisms from a Boolean algebra R_1 to a Boolean algebra R_2 is denoted by $\text{hom}_{\text{BA}}(R_1, R_2)$. The collection of nonzero elements of $\text{hom}_{\text{BA}}(R, \mathbb{Z}_2)$ [resp. $\text{hom}_{\text{Set}}(R, \mathbb{Z}_2)$] is denoted by $\text{hom}_{\text{BA}}^*(R, \mathbb{Z}_2)$ [resp. $\text{hom}_{\text{Set}}^*(R, \mathbb{Z}_2)$].

Lemma 9.18 *Every Boolean algebra R is commutative, and $a+a = 0$ holds identically for each $a \in R$.*

Proof See [15]. □

9.3.1 Examples of Boolean Algebras

The simplest example of a Boolean algebra is $\{0, 1\} = \mathbb{Z}_2$, endowed with the usual ring operations of $\mathbb{Z}_2 \equiv \mathbb{Z}/2$. In order to avoid ambiguities, the sum of $a, b \in \mathbb{Z}_2$ is denoted by $a +_2 b$.

A large class of Boolean algebras may be constructed as follows. If S is a set then $\text{hom}_{\text{Set}}(S, \mathbb{Z}_2)$ inherits the algebraic structure from \mathbb{Z}_2 by the familiar procedure of having the operations performed “pointwise.” See [22] for this general technique. Indeed, if $f, g \in \text{hom}_{\text{Set}}(S, \mathbb{Z}_2)$, we define $f + g$ and $f \cdot g$ as elements of $\text{hom}_{\text{Set}}(S, \mathbb{Z}_2)$ defined by $(f +_2 g)(s) \stackrel{\text{def}}{=} f(s) +_2 g(s)$ and $(f \cdot g)(s) \stackrel{\text{def}}{=} f(s) \cdot g(s)$, $s \in S$. Hence $\text{hom}_{\text{Set}}(S, \mathbb{Z}_2)$ inherits from \mathbb{Z}_2 a Boolean algebra structure.

Since a natural identification of $\mathcal{P}(A)$ with $\text{hom}_{\text{Set}}(A, \mathbb{Z}_2)$ is established by the map

$$Q \in \mathcal{P}(A) \mapsto \mathbb{1}_Q \in \text{hom}_{\text{Set}}(A, \mathbb{Z}_2)$$

it follows that $\mathcal{P}(A)$ inherits the Boolean algebra structure from $\text{hom}_{\text{Set}}(A, \mathbb{Z}_2)$. Observe that, under this identification, the symmetric difference of two elements b_1, b_2 of $\mathcal{P}(A)$ corresponds to the sum $\mathbb{1}_{b_1} +_2 \mathbb{1}_{b_2}$ in $\text{hom}_{\text{Set}}(A, \mathbb{Z}_2)$, and the intersection of b_1 and b_2 corresponds to the product $\mathbb{1}_{b_1} \cdot \mathbb{1}_{b_2}$.

9.3.2 Filters, Ultrafilters, and Boolean Algebras

Lemma 9.19 *If A is not empty, $\sigma \in \text{hom}_{\text{Set}}^*(\mathcal{P}(A), \mathbb{Z}_2)$, and $Z_\sigma \stackrel{\text{def}}{=} \{b \in \mathcal{P}(A) : \sigma(b) = 1\}$ then*

- (1) Z_σ is a filter on A if and only if $\sigma(b \cap c) = \sigma(b)\sigma(c)$ and $\sigma(\emptyset) = 0$ for all $b, c \in \mathcal{P}(A)$.
- (2) Z_σ is an ultrafilter on A if and only if $\sigma \in \text{hom}_{\text{BA}}^*(\mathcal{P}(A), \mathbb{Z}_2)$.

Proof (1) (\Rightarrow) If Z_σ is a filter then $\sigma(\emptyset) = 0$ (since a filter does not contain the empty set). Moreover, if $b \cap c \notin Z_\sigma$ then at least one of the sets b, c does not belong to Z_σ , hence $\sigma(b \cap c) = \sigma(b)\sigma(c)$.

(1) (\Leftarrow) If $b, c \in Z_\sigma$ then $\sigma(b \cap c) = 1$, hence $b \cap c \in Z_\sigma$. The empty set does not belong to Z_σ , since $\sigma(\emptyset) = 0$. If $b \subset c$ and $b \in Z_\sigma$ then $\sigma(b) = \sigma(b \cap c) = \sigma(b)\sigma(c)$, hence $1 = 1 \cdot \sigma(c) = \sigma(c)$, i.e., $c \in Z_\sigma$.

(2) (\Rightarrow) Observe that Lemma 4.28 says that if $\sigma(e) = 1$ and $d \subset e$, then $1 = \sigma(d) +_2 \sigma(e \setminus d)$ (where $+_2$ denotes sum in \mathbb{Z}_2), hence if $\sigma(b \triangle c) = 1$ then $(\sigma(b \setminus c), \sigma(c \setminus b))$ is equal to $(1, 0)$ or $(0, 1)$, and by symmetry it suffices to treat the first case. Hence $\sigma(b) = 1$ (since $b \setminus c \subset b$) and $\sigma(c) = 0$ (since a filter cannot contain disjoint sets) and thus $\sigma(b \triangle c) = \sigma(b) +_2 \sigma(c)$. If $\sigma(b \triangle c) = 0$ and $\sigma(b) = 1$

then $(\sigma(\mathbf{b} \setminus \mathbf{c}), \sigma(\mathbf{b} \cap \mathbf{c}))$ equals $(1, 0)$ or $(0, 1)$. The first case is impossible, since $\sigma(\mathbf{b} \setminus \mathbf{c}) = 1 \Rightarrow \sigma(\mathbf{b} \Delta \mathbf{c}) = 1$. If instead $(\sigma(\mathbf{b} \setminus \mathbf{c}), \sigma(\mathbf{b} \cap \mathbf{c})) = (0, 1)$, then $\sigma(\mathbf{c}) = 1$ (since $\mathbf{b} \cap \mathbf{c} \subset \mathbf{c}$), and thus $\sigma(\mathbf{b} \Delta \mathbf{c}) = \sigma(\mathbf{b}) +_2 \sigma(\mathbf{c})$. The case where $\sigma(\mathbf{b} \Delta \mathbf{c}) = 0$, $\sigma(\mathbf{b}) = 0$, and $\sigma(\mathbf{c}) = 1$ is treated by symmetry. If $\sigma(\mathbf{b} \Delta \mathbf{c}) = 0$, $\sigma(\mathbf{b}) = 0$, and $\sigma(\mathbf{c}) = 0$ then the conclusion is immediate. Hence $\sigma(\mathbf{b} \Delta \mathbf{c}) = \sigma(\mathbf{b}) +_2 \sigma(\mathbf{c})$ holds for all \mathbf{b}, \mathbf{c} .

(2) (\Leftarrow) We know from (1) that Z_σ is a filter. Let $\mathbf{b} \subset A$, assume that $\mathbf{b} \notin Z_\sigma$, and observe that $A = \mathbf{b} \Delta \mathbb{C}\mathbf{b}$. The hypotheses imply that $1 = \sigma(\mathbf{b}) +_2 \sigma(\mathbb{C}\mathbf{b})$, hence $\sigma(\mathbb{C}\mathbf{b}) = 1$, i.e., $\mathbb{C}\mathbf{b} \in Z_\sigma$. Hence Z_σ is an ultrafilter by Lemma 4.26. \square

9.4 The Natural Topology on $\mathcal{F}(A)$

We are now ready to apply Theorem 9.7 and define a map

$$N : \mathcal{F}(A) \rightarrow \mathcal{F}(\mathcal{F}(A))$$

which satisfies the compatibility condition described in (r) in Theorem 9.7.

Definition 9.20 If $\mathbf{b} \in \mathcal{P}(A)$ and $Q \subset \mathcal{F}(A)$ define

$$\mathbf{F}_\mathbf{b}(A) \stackrel{\text{def}}{=} \{Z : Z \in \mathcal{F}(A), \mathbf{b} \in Z\} \subset \mathcal{F}(A)$$

and

$$T_A(Q) \stackrel{\text{def}}{=} \{\mathbf{b} \in \mathcal{P}_\bullet(A) : \mathbf{F}_\mathbf{b}(A) \subset Q\} \subset \mathcal{P}_\bullet(A).$$

Lemma 9.21 If $Z \in \mathcal{F}(A)$ then

$$Z_\circ \stackrel{\text{def}}{=} \{\mathbf{F}_\mathbf{b}(A) : \mathbf{b} \in Z\}$$

is a filter base on $\mathcal{F}(A)$.

Proof If $\mathbf{b}_1, \mathbf{b}_2 \in Z$ let $\mathbf{b}_3 \stackrel{\text{def}}{=} \mathbf{b}_1 \cap \mathbf{b}_2$. Then $\mathbf{b}_3 \in Z$. Observe that $\mathbf{F}_{\mathbf{b}_3}(A) = \mathbf{F}_{\mathbf{b}_1}(A) \cap \mathbf{F}_{\mathbf{b}_2}(A)$. \square

Definition 9.22 If $Z \in \mathcal{F}(A)$, let $N(Z)$ be the filter on $\mathcal{F}(A)$ generated by the filter base Z_\circ , i.e.,

$$N(Z) \stackrel{\text{def}}{=} \langle Z_\circ \rangle_{\mathcal{F}(A)}. \tag{9.12}$$

Theorem 9.23 The map N defined above satisfies the regularity conditions in Theorem 9.7.

Proof If $Z \in \mathcal{F}(A)$ and $Q \in N(Z)$ then $\exists \mathbf{b} \in Z$ such that $\mathbf{F}_\mathbf{b}(A) \subset Q$. Observe that $\mathbf{b} \in Z$ implies that $Z \in \mathbf{F}_\mathbf{b}(A)$. Hence $Z \in Q$. Now let $R \stackrel{\text{def}}{=} \mathbf{F}_\mathbf{b}(A)$ and observe that if $Y \in R$ then $\mathbf{b} \in Y$, hence $\mathbf{F}_\mathbf{b}(A) \in Y_\circ$, and from $\mathbf{F}_\mathbf{b}(A) \subset Q$ it follows that $Q \in N(Y)$. Hence (r') in Proposition 9.8 is satisfied. \square

Definition 9.24 If A is a nonempty set, then the topology on $\mathcal{F}(A)$ associated to the map N defined above is called the *natural topology on $\mathcal{F}(A)$* .

Lemma 9.25 If $Q \subset \mathcal{F}(A)$ and $N : \mathcal{F}(A) \rightarrow \mathcal{F}(\mathcal{F}(A))$ is the map defined in (9.12) then

$$\mathring{N}(Q) = \{Z \in \mathcal{F}(A) : Z \cap T_A(Q) \neq \emptyset\}.$$

Proof $Z \in \mathring{N}(Q) \Leftrightarrow Q \in N(Z) \Leftrightarrow \exists b \in Z$ with $F_b(A) \subset Q \Leftrightarrow \exists b \in Z$ with $b \in T_A(Q)$. □

Corollary 9.26 A set $Q \subset \mathcal{F}(A)$ is open in the natural topology if and only if
 if $Z \in Q$ then there exists $b \in \mathcal{P}_\bullet(A)$ such that $Z \in F_b(A) \subset Q$.

Proof It suffices to apply Lemmas 9.3 and 9.25. □

The following examples are meant to illustrate these ideas.

Example 9.27 The only open set in the natural topology in $\mathcal{F}(A)$ which contains $\{A\}$ is $\mathcal{F}(A)$.

Indeed, if $\{A\} \in F_b(A)$ then $b \in \{A\}$, hence $b = A$, thus $F_b(A) = \mathcal{F}(A)$.

Example 9.28 The set $Q \stackrel{\text{def}}{=} \{Z \in \mathcal{F}(\mathbb{R}) : \exists (\alpha, \beta) \subset (0, 1) \text{ such that } \mathbb{R}_{(\alpha, \beta)} \subset Z\}$ is open in $\mathcal{F}(\mathbb{R})$ and is not equal to $\mathcal{F}(\mathbb{R})$.

Indeed, if $Z \in Q$, then there exists $(\alpha, \beta) \subset (0, 1)$ such that $\mathbb{R}_{(\alpha, \beta)} \subset Z$. In particular, $(\alpha, \beta) \in Z$. If $W \in F_{(\alpha, \beta)}(\mathbb{R})$ then $(\alpha, \beta) \in W$ hence $\mathbb{R}_{(\alpha, \beta)} \subset W$ and thus $W \in Q$. Thus $F_{(\alpha, \beta)}(\mathbb{R}) \subset Q$ and $(\alpha, \beta) \in Z \cap T_{\mathbb{R}}(Q)$, i.e., $Z \in \mathring{N}(Q)$. We have proved that $Q \subset \mathring{N}(Q)$, hence Q is open. Observe that $\mathbb{R}_{(2,3)} \notin Q$, since a filter cannot contain disjoint sets, hence $Q \neq \mathcal{F}(\mathbb{R})$.

Example 9.29 For each $x \in A$, the set $U \stackrel{\text{def}}{=} \{A_{\{x\}}\}$ is open in $\mathcal{F}(A)$.

Indeed, if $\{x\} \in Z$ and $Z \in \mathcal{F}(A)$, then $A_{\{x\}} \subset Z$ and thus $A_{\{x\}} = Z$, since $A_{\{x\}}$ is an ultrafilter. Hence $F_{\{x\}}(A) \subset U$, i.e., $\{x\} \in T_A(U)$. Since $\{x\} \in A_{\{x\}}$ it follows that $A_{\{x\}} \cap T_A(U) \neq \emptyset$, i.e., $A_{\{x\}} \in \mathring{N}(U)$.

Example 9.30 The set $Q \stackrel{\text{def}}{=} \{\mathbb{R}_{\{1,2\}}\}$ is not open in $\mathcal{F}(\mathbb{R})$.

Indeed, Theorem 4.25 implies that for each $b \subset \mathbb{R}$ with $\{1, 2\} \subset b$, there exists an ultrafilter $Z \in \mathcal{F}(\mathbb{R})$ with $Z \supset \mathbb{R}_b$. Hence $Z \notin Q$, since \mathbb{R}_b is not an ultrafilter, and this means that $F_b(\mathbb{R}) \not\subset Q$, i.e., $\mathbb{R}_{\{1,2\}} \cap T_{\mathbb{R}}(Q) = \emptyset$. Hence $\mathbb{R}_{\{1,2\}} \notin \mathring{N}(Q)$.

9.5 Basic Properties of the Natural Topology on $\mathcal{F}(A)$

Lemma 9.31 The assignment $A \mapsto \mathcal{F}(A)$ is the object function of a functor from the category of sets to the category of topological spaces, where $\mathcal{F}(A)$ is endowed with the natural topology. The associated arrow function assigns to each function $f : A \rightarrow Y$ the continuous function $f_\circ : \mathcal{F}(A) \rightarrow \mathcal{F}(Y)$.

Proof It suffices to prove that $f_\diamond : \mathcal{F}(A) \rightarrow \mathcal{F}(Y)$ is continuous with respect to the natural topologies of $\mathcal{F}(A)$ and $\mathcal{F}(Y)$, since the other statements have been proved in Lemma 4.36. Let $Z \in \mathcal{F}(A)$, $W \stackrel{\text{def}}{=} f_\diamond(Z)$, and let $Q \subset \mathcal{F}(Y)$ be a neighborhood of W in the natural topology of $\mathcal{F}(Y)$. Then there exists $\mathbf{b} \in W$ such that $\mathbf{F}_\mathbf{b}(Y) \subset Q$. Since $W \stackrel{\text{def}}{=} f_\diamond(Z)$, $\mathbf{b} \in W$ implies that there exists $\mathbf{c} \in Z$ such that $f_*(\mathbf{c}) \subset \mathbf{b}$. Observe that $\mathbf{F}_\mathbf{c}(A)$ is a neighborhood of Z in the natural topology of $\mathcal{F}(A)$. If $V \in \mathbf{F}_\mathbf{c}(A)$ then $\mathbf{c} \in V$, and since $f_*(\mathbf{c}) \subset \mathbf{b}$, it follows that $\mathbf{b} \in f_\diamond(V)$, i.e., $f_\diamond(V) \in \mathbf{F}_\mathbf{b}(Y)$, and thus $f_\diamond(V) \in Q$. Hence we have proved that $V \in \mathbf{F}_\mathbf{c}(A) \Rightarrow f_\diamond(V) \in Q$. \square

Proposition 9.32 *If (A, Θ) is a topological space and $\mathcal{F}(A)$ is endowed with the natural topology, then the function $N_\Theta : A \rightarrow \mathcal{F}(A)$ is continuous.*

Proof Let $x \in A$ and let $U \in N_{\mathcal{F}(A)}(N_\Theta(x))$. Then there exists $\mathbf{b} \in N_\Theta(x)$ such that $\mathbf{F}_\mathbf{b}(A) \subset U$. Since $\mathbf{b} \in N_\Theta(x)$, there exists an open set $\mathbf{c} \in \Theta$ such that $x \in \mathbf{c} \subset \mathbf{b}$. Let $z \in \mathbf{c}$. Since $\mathbf{c} \in \Theta$ and $\mathbf{c} \subset \mathbf{b}$, then $\mathbf{b} \in N_\Theta(z)$, hence $N_\Theta(z) \in \mathbf{F}_\mathbf{b}(A)$, thus $N_\Theta(z) \in U$. Hence we have proved that if $z \in \mathbf{c}$ then $N_\Theta(z) \in U$, i.e., the function N_Θ is continuous at x . Since x is arbitrary, the proof of continuity of N_Θ is complete. \square

Observe that if (A, Θ) is Hausdorff then $N_\Theta : A \rightarrow \mathcal{F}(A)$ is injective.

The following result will be better appreciated by keeping in mind Lemma 3.21.

Lemma 9.33 *If $Z, W \in \mathcal{F}(A)$ then the following conditions are equivalent:*

- (1) $Z \subset W$.
- (2) $Z \in \overline{\{W\}}$, where $\overline{\{W\}}$ is the closure in $\mathcal{F}(A)$.
- (3) $\lim W = Z$.

Proof If $Z \subset W$ and U is an open set in $\mathcal{F}(A)$ which contains Z , then there exists $\mathbf{b} \in \mathcal{P}(A)$ such that $Z \in \mathbf{F}_\mathbf{b}(A) \subset U$. Then $\mathbf{b} \in Z$, hence $\mathbf{b} \in W$, thus $W \in \mathbf{F}_\mathbf{b}(A)$. Therefore $W \in U$. These steps are reversible, hence the other implication follows. Hence (1) is equivalent to (2). Recall from Lemma 3.21 that the meaning of (3) is that if we denote by w the constant sequence $w : \mathbb{N} \rightarrow \mathcal{F}(A)$ which is identically equal to W then $\lim w = Z$ in the topology of $\mathcal{F}(A)$. Hence (2) and (3) are equivalent, by Lemma 3.23. \square

Lemma 9.34 *If $A \neq \emptyset$, then the following conditions are equivalent.*

- (1) A contains only one point.
- (2) $\mathcal{U}(A)$ is closed in $\mathcal{F}(A)$.
- (3) $\mathcal{F}(A)$ is Hausdorff.

Proof If (1) holds then $\mathcal{F}(A) = \mathcal{U}(A) = \{A\}$, hence (2) and (3) follow. If A contains more than one point, then $\{A\} \in \mathcal{F}(A) \setminus \mathcal{U}(A)$ and by Example 9.27 the only open set in $\mathcal{F}(A)$ which contains $\{A\}$ is $\mathcal{F}(A)$, which is not contained in $\mathcal{F}(A) \setminus \mathcal{U}(A)$. Hence (2) \Rightarrow (1). Lemma 9.33 implies that (3) \Rightarrow (1). \square

Proposition 9.35 *If $\Omega \subsetneq A$ then $\iota_\diamond : \mathcal{F}(\Omega) \rightarrow \mathcal{F}(A)$ is continuous.*

Proof Let $Z_0 \in \mathcal{F}(\Omega)$ and let $W_0 \stackrel{\text{def}}{=} \iota_\diamond(Z_0) \in \mathcal{F}(A)$. Let $U \in \mathcal{N}_{\mathcal{F}(A)}(W_0)$. Then $W_0 \in \mathbf{F}_b(A) \subset U$ for some $b \in W_0$. Hence $b = d \cup c$ for some $d \in Z_0$ and some $c \in \mathcal{P}(A \setminus \Omega)$. We claim that if $Z \in \mathbf{F}_d(\Omega)$ then $\iota_\diamond(Z) \in U$, and this will prove continuity at Z_0 , and since Z_0 is arbitrary, it will prove continuity. Let $Z \in \mathbf{F}_d(\Omega)$. Then $Z \in \mathcal{F}(\Omega)$ and $d \in Z$. Since $b = d \cup c$ and $d \in Z$, it follows that $b \in \iota_\diamond(Z)$ hence $\iota_\diamond(Z) \in \mathbf{F}_b(A)$, and since $\mathbf{F}_b(A) \subset U$, it follows that $\iota_\diamond(Z) \in U$. \square

9.6 Compactness Properties of the Natural Topology

Theorem 9.36 *If $A \neq \emptyset$ then*

- (1) $\mathcal{F}(A)$ is compact and, for each $d \in \mathcal{P}_\bullet(A)$, $\mathbf{F}_d(A)$ is compact in $\mathcal{F}(A)$.
- (2) $\mathcal{U}(A)$ is compact and Hausdorff.
- (3) $\mathcal{F}(A)$ has a basis of open compact sets. $\mathcal{U}(A)$ has a basis of closed and open compact sets.

Proof (1). Since $\mathcal{F}(A) = \mathbf{F}_A(A)$, it suffices to show that, for each $d \in \mathcal{P}_\bullet(A)$, $\mathbf{F}_d(A)$ is compact. Let $d \in \mathcal{P}_\bullet(A)$, $\mathcal{W} \in \mathcal{U}(\mathcal{F}(A))$ with $\mathbf{F}_d(A) \in \mathcal{W}$, and define

$$\mathcal{W}^* : \mathcal{P}(A) \rightarrow \mathbb{Z}_2 \tag{9.13}$$

by

$$\mathcal{W}^*(b) \stackrel{\text{def}}{=} \mathbb{1}_{\mathcal{W}}(\mathbf{F}_b(A)),$$

where $b \in \mathcal{P}(A)$. We claim that

$$\mathcal{W}^*(b_1 \cap b_2) = \mathcal{W}^*(b_1)\mathcal{W}^*(b_2), \quad \text{for all } b_1, b_2 \in \mathcal{P}(A) \tag{9.14}$$

and

$$\mathcal{W}^*(\emptyset) = 0. \tag{9.15}$$

Hence Lemma 9.19 implies that

$$Z_{\mathcal{W}} \stackrel{\text{def}}{=} \{b \in \mathcal{P}(A) : \mathcal{W}^*(b) = 1\} \tag{9.16}$$

is a filter on A . Now observe that $\mathbf{F}_d(A) \in \mathcal{W} \Rightarrow \mathcal{W}^*(d) = 1 \Rightarrow d \in Z_{\mathcal{W}} \Rightarrow Z_{\mathcal{W}} \in \mathbf{F}_d(A)$. Moreover,

$$\begin{aligned} \mathbf{F}_b(A) \in \mathcal{N}_{\mathcal{F}(A)}(Z_{\mathcal{W}}) &\Rightarrow Z_{\mathcal{W}} \in \mathbf{F}_b(A) \Rightarrow b \in Z_{\mathcal{W}} \Rightarrow \mathcal{W}^*(b) = 1 \\ &\Rightarrow \mathbf{F}_b(A) \in \mathcal{W}, \end{aligned} \tag{9.17}$$

i.e., $\mathcal{N}_{\mathcal{F}(A)}(Z_{\mathcal{W}}) \subset \mathcal{W}$. Lemma 4.30 implies that $\mathbf{F}_d(A)$ is compact.

We now prove the claim. Observe that $\mathcal{W}^*(\emptyset) = \mathbb{1}_{\mathcal{W}}(\mathbf{F}_{\emptyset}(A)) = \mathbb{1}_{\mathcal{W}}(\emptyset) = 0$, since a filter cannot contain the empty set. In order to prove (9.14), observe that

$$\mathbf{F}_{b_1}(A) \cap \mathbf{F}_{b_2}(A) = \mathbf{F}_{b_1 \cap b_2}(A). \tag{9.18}$$

Let $v = (\mathcal{W}^*(b_1), \mathcal{W}^*(b_2))$. If $v = (1, 1)$ then (9.14) is immediate, since $\mathbf{F}_{b_1 \cap b_2}(A) \in \mathcal{W}$ by (9.18). Observe that $\mathbf{F}_{b_1 \cap b_2}(A) \subset \mathbf{F}_{b_1}(A)$, hence $\mathbf{F}_{b_1 \cap b_2}(A) \in \mathcal{W} \Rightarrow \mathbf{F}_{b_1}(A) \in \mathcal{W}$. Thus $\mathcal{W}^*(b_1) = 0$ implies that $\mathbf{F}_{b_1 \cap b_2}(A) \notin \mathcal{W}$, and then both members of (9.14) are equal to 0. A similar result follows if $\mathcal{W}^*(b_2) = 0$.

(2). Let $\mathcal{W} \in \mathcal{U}(\mathcal{F}(A))$ with $\mathcal{U}(A) \in \mathcal{W}$. We claim that $\mathcal{W}^* \in \text{Boole}_*(\mathcal{P}(A), \mathbb{Z}_2)$. Lemma 9.19 then implies that $Z_{\mathcal{W}}$, defined in (9.16), belongs to $\mathcal{U}(A)$, and (9.17) says that $N_{\mathcal{F}(A)}(Z_{\mathcal{W}}) \subset \mathcal{W}$, and the proof is concluded by Lemma 4.30. In order to prove that

$$\mathcal{W}^*(b_1 \Delta b_2) = \mathcal{W}^*(b_1) +_2 \mathcal{W}^*(b_2) \tag{9.19}$$

let $v = (\mathcal{W}^*(b_1), \mathcal{W}^*(b_2))$. If $v = (1, 1)$ then $\mathbf{F}_{b_k}(A) \in \mathcal{W}$ (for $k = 1, 2$), hence $\mathbf{F}_{b_1}(A) \cap \mathbf{F}_{b_2}(A) \in \mathcal{W}$, thus $\mathbf{F}_{b_1 \cap b_2}(A) \in \mathcal{W}$, by (9.18), and, in particular, $b_1 \cap b_2 \neq \emptyset$. Since $\mathbf{F}_{b_1 \Delta b_2}(A) \cap \mathbf{F}_{b_1 \cap b_2}(A) = \emptyset$, it follows that $\mathbf{F}_{b_1 \Delta b_2}(A) \notin \mathcal{W}$, hence (9.19) holds.

If $v = (0, 1)$ then $\mathbf{F}_{b_1}(A) \notin \mathcal{W}$ and $\mathbf{F}_{b_2}(A) \in \mathcal{W}$, and, since \mathcal{W} is an ultrafilter on $\mathcal{F}(A)$, $\complement(\mathbf{F}_{b_1}(A)) \in \mathcal{W}$.

Let us assume that $\mathbf{F}_{b_2 \setminus b_1}(A) \notin \mathcal{W}$. Since \mathcal{W} is an ultrafilter on $\mathcal{F}(A)$, it follows that $\complement(\mathbf{F}_{b_2 \setminus b_1}(A)) \in \mathcal{W}$ and thus, since $\mathcal{U}(A) \in \mathcal{W}$,

$$\complement(\mathbf{F}_{b_1}(A)) \cap \mathbf{F}_{b_2}(A) \cap \complement(\mathbf{F}_{b_2 \setminus b_1}(A)) \cap \mathcal{U}(A) \in \mathcal{W}.$$

Hence there exists an ultrafilter Y on A such that

$$b_1 \notin Y, \quad b_2 \in Y, \quad b_2 \setminus b_1 \notin Y.$$

Since Y is an ultrafilter on A , Lemma 4.26 implies that

$$\complement b_1 \in Y, \quad b_2 \in Y, \quad \complement(b_2 \setminus b_1) \in Y,$$

thus $\emptyset = b_2 \cap \complement(b_2 \setminus b_1) \in Y$, which is impossible. It follows that $\mathbf{F}_{b_2 \setminus b_1}(A) \in \mathcal{W}$, and since $\mathbf{F}_{b_2 \setminus b_1}(A) \subset \mathbf{F}_{b_1 \Delta b_2}(A)$, it follows that $\mathbf{F}_{b_1 \Delta b_2}(A) \in \mathcal{W}$. Thus, if $v = (0, 1)$, both sides of (9.19) are equal to 1. Since the case $v = (1, 0)$ is symmetric, the proof is concluded if we show that (9.19) holds if $v = (0, 0)$. In this case, $\mathbf{F}_{b_1}(A) \notin \mathcal{W}$ and $\mathbf{F}_{b_2}(A) \notin \mathcal{W}$. Since \mathcal{W} is an ultrafilter on $\mathcal{F}(A)$, it follows that $\complement \mathbf{F}_{b_1}(A) \in \mathcal{W}$ and $\complement \mathbf{F}_{b_2}(A) \in \mathcal{W}$. Assume that $\mathbf{F}_{b_1 \Delta b_2}(A) \in \mathcal{W}$. Since $\mathbf{F}_{b_1 \Delta b_2}(A) \subset \mathbf{F}_{b_1 \cup b_2}(A)$, it follows that $\mathbf{F}_{b_1 \cup b_2}(A) \in \mathcal{W}$. Since $\mathcal{U}(A) \in \mathcal{W}$, it follows that

$$\complement(\mathbf{F}_{b_1}(A)) \cap \complement \mathbf{F}_{b_2}(A) \cap (\mathbf{F}_{b_1 \cup b_2}(A)) \cap \mathcal{U}(A) \in \mathcal{W}.$$

Hence there exists an ultrafilter Y on A such that

$$b_1 \notin Y, \quad b_2 \notin Y, \quad b_2 \cup b_1 \in Y,$$

and since Y is an ultrafilter on A , Lemma 4.26 implies that

$$\mathbb{C}b_1 \in Y, \quad \mathbb{C}b_2 \in Y, \quad (b_2 \cup b_1) \in Y.$$

Thus $\emptyset = \mathbb{C}b_1 \cap \mathbb{C}b_2 \cap (b_1 \cup b_2) \in Y$, which is impossible. Hence $\mathbf{F}_{b_1 \Delta b_2}(A) \notin \mathcal{W}$, and both sides of (9.19) are equal to 0. Hence $\mathcal{U}(A)$ is compact. In order to show that it is Hausdorff, let $Z_1, Z_2 \in \mathcal{U}(A)$, with $Z_1 \neq Z_2$. Then there exists $b_1 \in Z_1 \setminus Z_2$ and there exists $b_2 \in W_2$. We claim that $b_2 \setminus b_1 \in W$. Indeed, Lemma 4.28 and $b_2 \in Z_2$ imply that either $b_1 \cap b_2 \in Z_2$, or $b_2 \setminus b_1 \in Z_2$ but the first possibility is impossible since it implies that $b_1 \in Z_2$. Hence $Z_1 \in \mathbf{F}_{b_1}(A) \cap \mathcal{U}(A)$, $Z_2 \in \mathbf{F}_{b_2 \setminus b_1}(A) \cap \mathcal{U}(A)$, $\mathbf{F}_{b_1}(A) \cap \mathbf{F}_{b_2 \setminus b_1}(A) \cap \mathcal{U}(A) = \emptyset$.

(3). The sets $\mathbf{F}_b(A)$, for $b \in \mathcal{P}_\bullet(A)$, are open, compact, and are a basis for the topology of $\mathcal{F}(A)$. The sets $\mathbf{F}_b(A) \cap \mathcal{U}(A)$ are compact, and since $\mathcal{U}(A)$ is Hausdorff, are closed. Since they are also open in $\mathcal{U}(A)$, the proof is complete. \square

9.7 Other Properties of the Natural Topology

We now show that filters have a dual character. On the one hand, a filter W on A may be seen as a “static” object, i.e., as an element of $\mathcal{F}(A)$, which is endowed, as we have seen, with a natural topology. On the other hand, we may look at W in various other ways which bring to the forelight a certain dynamic character that is encoded in the intrinsic structure of a filter. Recall from Example 3.15 that if W is a filter on a nonempty set A , then (W, \supset) is a directed set, where \supset is reverse inclusion between sets.

The following commutative diagram displays the functions which appear in Proposition 9.37.

$$\begin{array}{ccccc}
 & & \mathcal{F}(A) & & \\
 & \delta_A \nearrow & \uparrow \epsilon_A & \nwarrow \llcorner W & \\
 A & \xrightarrow{\iota_A} & \mathcal{P}_\bullet(A) & \xleftarrow{s_W} & W
 \end{array} \tag{9.20}$$

Recall from Definition 6.12 that s_W (and hence $\llcorner W$) may be seen as generalized sequences, since W is directed by reverse set inclusion. Also recall that ϵ_A has been defined in (9.7), and ι_A in (9.9). The maps δ_A and $\llcorner W$ are defined by composition: $\delta_A = \epsilon_A \circ \iota_A$ and $\llcorner W = \epsilon_A \circ s_W$.

Proposition 9.37 *If $Z, W \in \mathcal{F}(A)$, then the following conditions are equivalent.*

- (1) $\lim_W \delta_A = Z$.
- (2) $\lim_{\iota_\bullet(W)} \epsilon_A = Z$.
- (3) $\lim \llcorner W = Z$.
- (4) $\lim W = Z$.
- (5) $Z \subset W$.
- (6) $Z \in \overline{\{W\}}$.

Proof In Lemmas 9.33 and 3.21, we have shown that (4), (5), and (6) are equivalent to each other. Observe that Corollary 4.34 says that (1) amounts to asking that

$$N_{\mathcal{F}(A)}(Z) \subset (\delta_A)_\circ(W) \tag{9.21}$$

and this means that $\forall b \in Z \exists d \in W$ such that $(\delta_A)_*(d) \subset \mathbf{F}_b(A)$. Observe that $(\delta_A)_*(d) \subset \mathbf{F}_b(A)$ means that $\forall x \in d, A_x \in \mathbf{F}_b(A)$, i.e., $b \in A_x$, i.e., $x \in b$. Hence $(\delta_A)_*(d) \subset \mathbf{F}_b(A)$ means that $d \subset b$. Thus (1) says that $\forall b \in Z, \exists d \in W$ such that $d \subset b$, and this condition is equivalent to (5). The diagram on the left side of (9.20) commutes, i.e., $\delta_A = \epsilon_A \circ \iota_A$, and thus the functoriality properties established in Lemma 4.36 imply that

$$(\delta_A)_\circ(W) = (\epsilon_A)_\circ((\iota_A)_\circ(W)).$$

Hence (1) and (2) are equivalent to each other. Observe that (3) amounts to saying that $\forall d \in Z \exists b \in W$ such that $c \in W$ and $c \subset b$ implies that $A_c \in \mathbf{F}_d(A)$. The condition $A_c \in \mathbf{F}_d(A)$ means that $d \in A_c$, i.e., $c \subset d$. Hence (3) says that $\forall d \in Z \exists b \in W$ such that $c \in W$ and $c \subset b$ implies that $c \subset d$, and this means that $\forall d \in Z \exists b \in W$ such that $b \subset d$, which is equivalent to (5). □

Proposition 9.38 *If (A, Z) is a filtered set, (Y, Θ) is a topological space, $\omega: A \rightarrow Y$ is a function, and $y \in Y$, then the following conditions are equivalent:*

- $\lim_Z \omega = y$,
- $\lim_{\omega_\circ}(Z) = N_\Theta(y)$.

Proof The result follows at once from Corollary 4.34 and Lemma 9.33. □

The meaning of Proposition 9.38 is that the limiting behavior of a function f along a filter Z is completely determined by the behavior of $f_\circ(Z)$. Lemma 9.33 enables us to reformulate Theorem 6.2 as follows.

Corollary 9.39 *If $\omega \in \mathcal{S}(Y)$ is a Y -valued Moore–Smith sequence, Θ is a topology on Y , and $y \in Y$, then the following conditions are equivalent:*

- $\lim \omega = y$,
- $\lim_{\mathbf{T}_Y[\omega]} = N_\Theta(y)$.

In all these results the same underlying idea emerges, to wit: It is useful to interpret everything in terms of filters and then exploit the natural topology on $\mathcal{F}(Y)$. For example, if Θ is a topology on Y , it is customary to say that y is a *point of convergence* for $W \in \mathcal{F}(Y)$ if $\lim W = N_\Theta(y)$ in the natural topology of Y . We will study other useful applications of this idea in the following sections.

10 Applications of the Natural Topology to Cluster Points of Filters

In this section, we apply the natural topology of $\mathcal{F}(A)$ to the study of the notion of cluster point of a filter.

Lemma 10.1 *If $Z_1, Z_2 \in \mathcal{F}(A)$, then the following conditions are equivalent:*

- (1) $Z_1 \bowtie Z_2$,
- (2) *There exists $W \in \mathcal{F}(A)$ such that $\lim W = Z_1$ and $\lim W = Z_2$.*

Proof The result follows at once from Lemma 9.33. □

Lemma 10.2 *The collection*

$$\mathcal{C}_A \stackrel{\text{def}}{=} \{(Z, W) \in \mathcal{F}(A) \times \mathcal{F}(A) : Z \bowtie W\} \tag{10.1}$$

is closed in the product topology of $\mathcal{F}(A) \times \mathcal{F}(A)$.

Proof If $(Z, W) \notin \mathcal{C}_A$, then there exist $b \in Z$ and $c \in W$ such that $b \cap c = \emptyset$, by Lemma 9.15. Observe that $Z \in \mathbf{F}_b(A)$, $W \in \mathbf{F}_c(A)$, and $\mathbf{F}_b(A)$ and $\mathbf{F}_c(A)$ are disjoint open neighborhoods of Z and W . Moreover, if $(Z', W') \in \mathbf{F}_b(A) \times \mathbf{F}_c(A)$ then $Z' \triangleleft W'$ hence $(Z', W') \notin \mathcal{C}_A$, hence \mathcal{C}_A is open in $\mathcal{F}(A) \times \mathcal{F}(A)$. □

Definition 10.3 If Θ is a topology on Y , the filter $W \in \mathcal{F}(Y)$ *clusters at* $x \in Y$ if $W \bowtie N_\Theta(x)$. The *cluster set of W on Y* is the following subset of Y :

$$\mathbf{Cluster}[W, \Theta] \stackrel{\text{def}}{=} \{x \in Y : W \bowtie N_\Theta(x)\}. \tag{10.2}$$

The following result says that the search for points of convergence of a filter should be restricted to the cluster set of the filter.

Lemma 10.4 *If a filter W converges to $N_\Theta(x)$ then it clusters at x .*

Proof If $N_\Theta(x) \subset W$ then $N_\Theta(x) \vee W = W$, hence $N_\Theta(x) \vee W$ exists. □

Lemma 10.5 *Let $W \in \mathcal{F}(Y)$ and let Θ be a topology on Y . Then $\mathbf{Cluster}[W, \Theta]$ is closed.*

Proof If $y \notin \mathbf{Cluster}[W, \Theta]$ then $O \cap b = \emptyset$ for some $O \in N_\Theta(y)$ and $b \in W$, and there exists an open set $O' \subset O$ such that $y \in O' \subset O$. Now observe that $O' \subset \mathbf{Cluster}[W, \Theta]$, hence $\mathcal{C}(\mathbf{Cluster}[W, \Theta])$ is open. □

10.1 Application to Compactness

We are now ready to obtain a more flexible version of Lemma 4.30.

Proposition 10.6 ([8]) *If A is endowed with a topology Θ and $K \subset A$, then the following conditions are equivalent:*

- (1) *K is compact.*
- (2) *For each ultrafilter on A which is localized in K there exists $x \in K$ such that $\lim W = N_\Theta(x)$.*

(3) For each filter Z on A which is localized in K , $K \cap \mathbf{Cluster}[Z, \Theta] \neq \emptyset$.

Proof It suffices to prove that (2) and (3) are equivalent, since in Lemma 4.30 we have proved that (1) and (2) are equivalent. Assume that (2) holds, and let $Z \in \mathcal{F}(A)$ with $K \in W$. Theorem 4.25 implies that there exists $W \in \mathcal{U}(A)$ such that $Z \subset W$. Hence (2) implies that there exists $x \in K$ such that $N_\Theta(x) \subset W$. It follows that $N_\Theta(x) \vee Z$ exists, i.e., $x \in \mathbf{Cluster}[Z, \Theta]$. Assume that (3) holds, and let $W \in \mathcal{U}(A)$ with $K \in W$. Then there exists $x \in K$ such that $N_\Theta(x) \bowtie W$, i.e., there exists a filter Z such that $N_\Theta(x) \subset Z$ and $W \subset Z$. Since W is an ultrafilter, it follows that $Z = W$, hence $N_\Theta(x) \subset W$. □

The following result follows at once from Lemma 10.5 and Proposition 10.6.

Corollary 10.7 *If (A, Θ) is a compact topological space and $W \in \mathcal{F}(A)$ then $\mathbf{Cluster}[W, \Theta]$ is a nonempty compact subset of A .*

Lemma 10.8 *If (A, Θ) is a Hausdorff topological space, $s, y \in A$, and $N_\Theta(s) \bowtie N_\Theta(y)$, then $s = y$.*

Proof If $s \neq y$, there exists $U \in N_\Theta(s)$ and $V \in N_\Theta(y)$ such that $U \cap V = \emptyset$. Hence $N_\Theta(s) \triangleleft N_\Theta(y)$. □

Theorem 10.9 *If (A, Θ) is a compact Hausdorff topological space, $Z \in \mathcal{F}(A)$, and $y \in A$, then the following conditions are equivalent:*

- (1) $\lim Z = N_\Theta(y)$,
- (2) $\mathbf{Cluster}[Z, \Theta] = \{y\}$.

Proof If (1) holds, then $Z \supset N_\Theta(y)$, hence $y \in \mathbf{Cluster}[Z, \Theta]$. We now show that $\mathbf{Cluster}[Z, \Theta]$ does not contain other points. Indeed, if $s \in \mathbf{Cluster}[Z, \Theta]$ then $N_\Theta(s) \vee Z$ exists and, since $Z \supset N_\Theta(y)$, it follows that $N_\Theta(s) \vee N_\Theta(y)$ exists. Then Lemma 10.8 implies that $s = y$. Hence (2) holds.

If (1) does not hold, then there exists an open set $Q \subset A$ such that $y \in Q$ and $Q \notin Z$. Hence Z is weakly localized in $\mathcal{C}Q$, and Proposition 4.40 then implies that there exists a filter W on A which is localized in $\mathcal{C}Q$ and such that $Z \subset W$. Since Q is open and A compact, it follows that $\mathcal{C}Q$ is compact. Hence Proposition 10.6 implies that there exists $r \in \mathcal{C}Q$ such that $r \in \mathbf{Cluster}[W, \Theta]$. Since $Z \subset W$, it follows that $r \in \mathbf{Cluster}[Z, \Theta]$. Since $r \in \mathcal{C}Q$ and $y \in Q$, it follows that $r \neq y$. Hence $\mathbf{Cluster}[Z, \Theta]$ contains more than one point, i.e., (2) does not hold. □

11 Filters on the Real Line

The goal of this section is to develop appropriate machinery for the study of convergence properties of filters on \mathbb{R} , since, in view of Corollary 4.34, these filters control the convergence properties of real-valued functions defined on a filtered set.

11.1 The Structure of the Cluster Set of Filters on the Real Line (I)

The main application of the notion of cluster set of a filter, introduced in Definition 10.3, is linked to Lemma 10.4 and Theorem 10.9, which imply that, in order to understand whether a given filter on a compact topological space converges, it suffices to control its cluster set. However, real-valued functions or sequences may very well diverge to $+\infty$ or $-\infty$, and indeed, if $Z \in \mathcal{F}(\mathbb{R})$, then the statement that $\lim Z = N_{\mathbb{R}}(+\infty)$ means that $N_{\mathbb{R}}(+\infty) \subset Z$, but then $\mathbf{Cluster}[Z, \mathbb{R}] = \emptyset$. In particular, in this situation, the set $\mathbf{Cluster}[Z, \mathbb{R}]$ does not fully reflect the convergence properties of $Z \in \mathcal{F}(\mathbb{R})$. In order to obtain uniform results, which are useful in dealing with pointwise estimates, as we will see, we set as ambient space the extended real line $\overline{\mathbb{R}} \equiv [-\infty, +\infty]$, a compact space which allows us to apply Theorem 10.9. Accordingly, we enlarge the ambient space which hosts the filters used in the notion of cluster set. In other words, we move from $\mathcal{F}(\mathbb{R})$ to $\mathcal{F}(\overline{\mathbb{R}})$.

If we specialize Definition 10.3 to $\overline{\mathbb{R}} \equiv [-\infty, +\infty]$ we obtain, for $W \in \mathcal{F}(\overline{\mathbb{R}})$

$$\mathbf{Cluster}[W, \overline{\mathbb{R}}] \stackrel{\text{def}}{=} \{x \in [-\infty, +\infty] : W \bowtie N_{\overline{\mathbb{R}}}(x)\}. \tag{11.1}$$

With this definition, if $\lim Z = N_{\mathbb{R}}(+\infty)$ then $\mathbf{Cluster}[Z, \overline{\mathbb{R}}] = \{+\infty\}$, as one would expect.

Observe the difference between the neighborhood filter of $+\infty$ which appears in (11.1), to wit:

$$N_{\mathbb{R}}(+\infty) \stackrel{\text{def}}{=} \{Q \subset [-\infty, +\infty] : Q \supset (a, +\infty] \text{ for some } a \in \mathbb{R}\} \tag{11.2}$$

and the filter $N_{+\infty}(\mathbb{R})$ defined in (1.17). Indeed, on the one hand, $N_{\mathbb{R}}(+\infty) \in \mathcal{F}(\mathbb{R}) \setminus \mathcal{F}(\overline{\mathbb{R}})$ while, on the other hand, $N_{\overline{\mathbb{R}}}(+\infty) \in \mathcal{F}(\overline{\mathbb{R}}) \setminus \mathcal{F}(\mathbb{R})$. We will deal with this difference momentarily.

Recall that closed nonempty intervals in $[-\infty, +\infty]$ have the form $[a, b]$ where $a, b \in \overline{\mathbb{R}}$ and $a \leq b$ (hence possibly $a = b$). In particular, $\{+\infty\} \equiv [+\infty, +\infty]$ and $\{-\infty\} \equiv [-\infty, -\infty]$ are closed nonempty intervals in $[-\infty, +\infty]$. Similarly, $[0, +\infty]$ is a closed nonempty interval in $[-\infty, +\infty]$.

Theorem 11.1 *If $W \in \mathcal{F}(\overline{\mathbb{R}})$, then $\mathbf{Cluster}[W, \overline{\mathbb{R}}]$ is a nonempty compact interval of $[-\infty, +\infty]$.*

Proof Corollary 10.7 says that $\mathbf{Cluster}[W, \overline{\mathbb{R}}]$ is a nonempty compact subset of $\overline{\mathbb{R}}$. In order to show that it is an interval, assume that $r, s \in \mathbf{Cluster}[W, \overline{\mathbb{R}}]$, $r < s$, and $u \in (r, s)$. We claim that $u \in \mathbf{Cluster}[W, \overline{\mathbb{R}}]$. Seeking a contradiction, assume that $u \notin \mathbf{Cluster}[W, \overline{\mathbb{R}}]$. Then there exists an open interval $(\alpha, \beta) \subset \mathbb{R}$ and an element of $\mathfrak{b} \in W$, with $r < \alpha < u < \beta < s$ and $(\alpha, \beta) \cap \mathfrak{b} = \emptyset$. Then either (i) $\mathfrak{b} \subset [\beta, +\infty]$ or (ii) $\mathfrak{b} \subset [-\infty, \alpha]$. If (i) holds then there exists an open neighborhood of r which is disjoint from \mathfrak{b} , hence $r \notin \mathbf{Cluster}[W, \overline{\mathbb{R}}]$. If (ii) holds then a symmetrical reasoning shows that $s \notin \mathbf{Cluster}[W, \overline{\mathbb{R}}]$. \square

Given $Z \in \mathcal{F}(\mathbb{R})$, in order to be able to apply Corollary 10.7, it is necessary to consider the extension of Z from \mathbb{R} to $\overline{\mathbb{R}}$, described in Sect. 4.6 and denoted by Z' .

Indeed, since $Z' \in \mathcal{F}(\overline{\mathbb{R}})$, Theorem 11.1 implies that

Cluster $[Z', \overline{\mathbb{R}}]$ is a nonempty compact interval of $[-\infty, +\infty]$.

We now go back to the difference between the neighborhood filter of $+\infty$ which appears in (11.1) and the filter $N_{+\infty}(\mathbb{R})$ defined in (1.17). Since the starting datum is a real filter, i.e., an element $Z \in \mathcal{F}(\mathbb{R})$, it would be desirable to express the cluster set of the extension of Z directly in terms of Z . This task is achieved by the following definition, where we introduce the “extended real cluster set.”

Definition 11.2 If $Z \in \mathcal{F}(\mathbb{R})$, the *extended cluster set of Z in $[-\infty, +\infty]$* is the following subset of $[-\infty, +\infty]$

$$\mathbf{clusterset}(Z, \overline{\mathbb{R}}) \stackrel{\text{def}}{=} \{r \in [-\infty, +\infty] : Z \bowtie N_{\mathbb{R}}(r)\}. \tag{11.3}$$

Observe that all filters which appear in (11.3) are filters on \mathbb{R} . However, (11.3) has a slightly spurious appearance, since Z is a filter on \mathbb{R} , but the resulting cluster set lies inside $\overline{\mathbb{R}}$. Indeed, the advantage of Definition (11.2) is that the cluster set is expressed directly in terms of the original filter $Z \in \mathcal{F}(\mathbb{R})$ and, moreover, the simpler filter (1.17) (a filter on \mathbb{R}) is used instead of (11.2) (a filter on $\overline{\mathbb{R}}$). This technical convenience has no serious side effects, as shown in the following result.

Lemma 11.3 *If $Z \in \mathcal{F}(\mathbb{R})$ then*

$$\mathbf{Cluster}[Z', \overline{\mathbb{R}}] = \mathbf{clusterset}(Z, \overline{\mathbb{R}}). \tag{11.4}$$

Proof (Proof of $\mathbf{Cluster}[Z', \overline{\mathbb{R}}] \subset \mathbf{clusterset}(Z, \overline{\mathbb{R}})$). Assume that $x \in \mathbf{Cluster}[Z', \overline{\mathbb{R}}]$ and $x \in \mathbb{R}$. Then $Z' \bowtie N_{\overline{\mathbb{R}}}(x)$ and, for each $\epsilon > 0$ and each $b' \in Z'$, the intersection $(x - \epsilon, x + \epsilon) \cap b'$ is not empty. If $b \in Z$ then $b \in Z'$ (by Lemma 4.38) and it follows that $(x - \epsilon, x + \epsilon) \cap b \neq \emptyset$. Thus $x \in \mathbf{clusterset}(Z, \overline{\mathbb{R}})$. Assume that $+\infty \in \mathbf{Cluster}[Z', \overline{\mathbb{R}}]$. Then $Z' \bowtie N_{\overline{\mathbb{R}}}(+\infty)$. Let $b \in Z$. Since $Z \in \mathcal{F}(\mathbb{R})$, it follows that $b \subset \mathbb{R}$. Moreover, $b \in Z'$ (by Lemma 4.38). Let $a \in \mathbb{R}$. Then $b \cap (a, +\infty] \neq \emptyset$ (since $Z' \bowtie N_{\overline{\mathbb{R}}}(+\infty)$). Since $b \subset \mathbb{R}$, it follows that $b \cap (a, +\infty) \neq \emptyset$. Since $b \in Z$ and $a \in \mathbb{R}$ are arbitrary, it follows that $Z \bowtie N_{\mathbb{R}}(+\infty)$. Hence $+\infty \in \mathbf{clusterset}(Z, \overline{\mathbb{R}})$. The proof that if $-\infty \in \mathbf{Cluster}[Z', \overline{\mathbb{R}}]$ then $-\infty \in \mathbf{clusterset}(Z, \overline{\mathbb{R}})$ follows by symmetry. Hence we have proved that $\mathbf{Cluster}[Z', \overline{\mathbb{R}}] \subset \mathbf{clusterset}(Z, \overline{\mathbb{R}})$.

(Proof of $\mathbf{Cluster}[Z', \overline{\mathbb{R}}] \supset \mathbf{clusterset}(Z, \overline{\mathbb{R}})$). Assume that $x \in \mathbf{clusterset}(Z, \overline{\mathbb{R}})$ and $x \in \mathbb{R}$. Hence $Z \bowtie N_{\mathbb{R}}(x)$. This means that for each $\epsilon > 0$ and each $b \in Z$, $b \cap (x - \epsilon, x + \epsilon) \neq \emptyset$. Now let $b' \in Z$ and $U \in N_{\overline{\mathbb{R}}}(x)$. Then there exists $\epsilon > 0$, $b \in Z$ and $I \subset \{+\infty, -\infty\}$ such that $U \supset (x - \epsilon, x + \epsilon)$ and $b' = I \cup b$. Then $b \cap (x - \epsilon, x + \epsilon) \neq \emptyset$ implies that $b' \cap U \neq \emptyset$. Since $b' \in Z$ and $U \in N_{\overline{\mathbb{R}}}(x)$ are arbitrary, it follows that $Z' \bowtie N_{\overline{\mathbb{R}}}(x)$, hence $x \in \mathbf{Cluster}[Z', \overline{\mathbb{R}}]$. Assume that $+\infty \in \mathbf{clusterset}(Z, \overline{\mathbb{R}})$. Then $Z \bowtie N_{\mathbb{R}}(+\infty)$. This means that, if $b \in Z$ and $a \in \mathbb{R}$, then $b \cap (a, +\infty) \neq \emptyset$. Now let $b' \in Z'$ and $U \in N_{\overline{\mathbb{R}}}(+\infty)$. Then there exists $b \in Z$ and $I \subset \{+\infty, -\infty\}$ such that $b' = I \cup b$. Moreover, there exists $a \in \mathbb{R}$ such that $U \supset (a, +\infty]$. Since $b \cap (a, +\infty) \neq \emptyset$, it follows that $b' \cap U \neq \emptyset$. Hence $Z' \bowtie$

$N_{\mathbb{R}}(+\infty)$, and thus $+\infty \in \mathbf{Cluster}[Z', \overline{\mathbb{R}}]$. The proof that if $-\infty \in \mathbf{clusterset}(Z, \overline{\mathbb{R}})$ then $-\infty \in \mathbf{Cluster}[Z', \overline{\mathbb{R}}]$ follows by symmetry. \square

11.2 Cluster Set and Limiting Points

In order to apply the previous results to $Z \in \mathcal{F}(\mathbb{R})$, the following idea is useful.

Lemma 11.4 *If $Z \in \mathcal{F}(\mathbb{R})$ and $y \in [-\infty, +\infty]$, and Z' is the extension of Z from \mathbb{R} to $\overline{\mathbb{R}}$, then the following conditions are equivalent:*

- (1) $\lim Z' = N_{\mathbb{R}}(y)$,
- (2) $\lim Z = N_{\mathbb{R}}(y)$.

Proof (1) \Rightarrow (2) If $y \in \mathbb{R}$, let $\epsilon > 0$ and let $I \stackrel{\text{def}}{=} (y - \epsilon, y + \epsilon)$. Then $I \in N_{\mathbb{R}}(y)$, hence $I \in Z'$. Since $Z' = \iota_*(Z)$, where $\iota : \mathbb{R} \rightarrow \overline{\mathbb{R}}$ is the natural injection, Lemma 4.38 implies that $I \in Z$. If $y = \{+\infty\}$, then let $U \in N_{\mathbb{R}}(+\infty)$. Then there exists $a \in \mathbb{R}$ such that $(a, +\infty) \subset U$. Observe that $(a, +\infty] \in N_{\mathbb{R}}(+\infty)$, hence $(a, +\infty] \in Z'$. Since $(a, +\infty] = (a, +\infty) \cup \{+\infty\}$, Lemma 4.38 implies that $(a, +\infty) \in Z$, hence $U \in Z$. The case $y = -\infty$ is similar.

(2) \Rightarrow (1) If $y \in \mathbb{R}$, let $U \in N_{\mathbb{R}}(y)$. Then there exists $\epsilon > 0$ such that $(y - \epsilon, y + \epsilon) \subset U$. Hence $(y - \epsilon, y + \epsilon) \in Z$, and then (4.15) implies that $(y - \epsilon, y + \epsilon) \in Z'$, hence $U \in Z'$. If $y = \{+\infty\}$, let $U \in N_{\mathbb{R}}(+\infty)$. Then there exists $a \in \mathbb{R}$ such that $(a, +\infty) \subset U$. Then $(a, +\infty) \in N_{\mathbb{R}}(+\infty)$, and it follows that $(a, +\infty) \in Z$, hence $(a, +\infty] \in Z'$, thus $U \in Z'$. The case $y = -\infty$ is similar. \square

Theorem 11.5 *If $Z \in \mathcal{F}(\mathbb{R})$ and $y \in [-\infty, +\infty]$ then the following conditions are equivalent:*

- (1) $\lim Z = N_{\mathbb{R}}(y)$,
- (2) $\mathbf{clusterset}(Z, \overline{\mathbb{R}}) = \{y\}$.

Proof The result follows at once from Lemma 11.3, Theorem 10.9, and Lemma 11.4. \square

11.3 The Filters $N_{\mathbb{R}}(\pm\infty)$ from the Viewpoint of the Natural Topology on $\mathcal{F}(\mathbb{R})$

The following result looks at these matters from the viewpoint of the natural topology of $\mathcal{F}(\mathbb{R})$.

Lemma 11.6 *Consider the $\mathcal{F}(\mathbb{R})$ -valued Moore–Smith sequence $\omega : \mathbb{R} \rightarrow \mathcal{F}(\mathbb{R})$ defined by*

$$\omega(r) \stackrel{\text{def}}{=} N_{\mathbb{R}}(r)$$

for each $r \in \mathbb{R}$. Then

$$\lim_{\leq} \omega = \lim_{r \rightarrow +\infty} N_{\mathbb{R}}(r) = N_{\mathbb{R}}(+\infty) \quad \text{and} \quad \lim_{\geq} \omega = \lim_{r \rightarrow -\infty} N_{\mathbb{R}}(r) = N_{\mathbb{R}}(-\infty).$$

Proof Let U be a neighborhood of $N_{\mathbb{R}}(+\infty)$ in $\mathcal{F}(\mathbb{R})$. We may assume, without loss of generality, that $U = \mathbf{F}_b(\mathbb{R})$ for $b \in N_{\mathbb{R}}(+\infty)$, and that $b = (x, +\infty)$, where $x \in \mathbb{R}$. We claim that

$$x < r \Rightarrow \mathcal{w}(r) \in U.$$

Indeed, if $x < r$ then $b \in N_{\mathbb{R}}(r)$, hence $N_{\mathbb{R}}(r) \in \mathbf{F}_b(\mathbb{R})$, i.e., $\mathcal{w}(r) \in U$. The proof of the second statement is symmetrical. \square

Corollary 11.7 $N_{\mathbb{R}}(+\infty)$ and $N_{\mathbb{R}}(-\infty)$ belong to the closure of $\{N_{\mathbb{R}}(r) : r \in \mathbb{R}\}$ in the natural topology of $\mathcal{F}(\mathbb{R})$.

Proof It suffices to apply Lemma 3.23. \square

11.4 The Structure of the Cluster Set of Filters on the Real Line (II)

We now look at the cluster set of $Z \in \mathcal{F}(\mathbb{R})$ from a more concrete viewpoint, which is useful in dealing with pointwise estimates, and introduce the notion of \limsup and \liminf of a filter on \mathbb{R} . These notions are related, as we will see, to the familiar notions of \liminf and \limsup of a real-valued sequence or function, but formally different, hence it is convenient to use a different notation. Recall from Sect. 9.2 that if Z, W are filters on A then $Z \bowtie W$ means that $Z \vee W$ exists in $\mathcal{F}(A)$, and $Z \triangleleft \triangleright W$ means that $Z \vee W$ does not exist in $\mathcal{F}(A)$. If $b \subset A$, then $b \bowtie W$ [resp. $b \triangleleft \triangleright W$] means that $A_b \bowtie W$ [resp. $A_b \triangleleft \triangleright W$].

Definition 11.8 If $Z \in \mathcal{F}(\mathbb{R})$ then we define

$$\begin{aligned} Z^+ &\stackrel{\text{def}}{=} \{r \in \mathbb{R} : (r, +\infty) \bowtie Z\}, \\ Z^- &\stackrel{\text{def}}{=} \{l \in \mathbb{R} : (-\infty, l) \bowtie Z\}, \\ \limsup Z &\stackrel{\text{def}}{=} \sup Z^+, \\ \liminf Z &\stackrel{\text{def}}{=} \inf Z^-, \end{aligned}$$

with the understanding that $\sup \emptyset = -\infty$ and $\inf \emptyset = +\infty$.

Example 11.9 It is useful to keep in mind the following examples.

- (1) $Z^+ = (-\infty, 0)$ if Z is the filter generated by the filter base in Example 4.13.
- (2) $Z^+ = (-\infty, 0]$ if $Z = N_{\mathbb{R}}(0)$.
- (3) $Z^+ = \mathbb{R}$ and $Z^- = \emptyset$ if $Z = N_{\mathbb{R}}(+\infty)$.
- (4) $Z^+ = \emptyset$ and $Z^- = \mathbb{R}$ if $Z = N_{\mathbb{R}}(-\infty)$.
- (5) $Z^+ = Z^- = \mathbb{R}$ if Z is the filter generated by the filter base in Example 4.14.

In particular, we observe that $\limsup N_{\mathbb{R}}(+\infty) = \liminf N_{\mathbb{R}}(+\infty) = +\infty$. In a similar way, one shows that $\limsup N_{\mathbb{R}}(-\infty) = \liminf N_{\mathbb{R}}(-\infty) = -\infty$.

Definition 11.10 We say that a subset I of \mathbb{R} is a *left-interval* in \mathbb{R} if it has one of the following forms: (i) $I = (-\infty, a)$ for some $a \in \mathbb{R}$; (ii) $I = (-\infty, a]$ for some $a \in \mathbb{R}$; (iii) $I = \mathbb{R}$; (iv) $I = \emptyset$. The notion of *right-interval* is defined by symmetry.

Lemma 11.11 *If $Z \in \mathcal{F}(\mathbb{R})$ then Z^+ is a left-interval in \mathbb{R} , and Z^- is a right-interval in \mathbb{R} .*

Proof The conclusion for Z^+ follows at once from the fact that if $r \in \mathbb{R}$, $(r, +\infty) \bowtie Z$, and $r' < r$, then $(r', +\infty) \bowtie Z$. The reasoning for Z^- is symmetric. \square

Lemma 11.12 *If $Z, W \in \mathcal{F}(A)$ and $x \in \mathbb{R}$ then*

- (1) *If $Z \subset W$ then $Z^+ \supset W^+$ and $Z^- \supset W^-$.*
- (2) *$Z^+ = \emptyset$ if and only if $N_{\mathbb{R}}(-\infty) \subset Z$, and $Z^- = \emptyset$ if and only if $N_{\mathbb{R}}(+\infty) \subset Z$.*
- (3) *$x \notin Z^-$ if and only if $[x, +\infty) \in Z$, and $x \notin Z^+$ if and only if $(-\infty, x] \in Z$.*
- (4) *If $Z \subset W$ then $\liminf Z \leq \liminf W$ and $\limsup W \leq \limsup Z$.*

Proof By symmetry, it suffices to prove the first statement in each part. (1) If $Z \subset W$ and $r \in W^+$ then $(r, +\infty) \cap \mathbf{b} \neq \emptyset$ for each $\mathbf{b} \in W$, hence the same conclusion holds for each $\mathbf{b} \in Z$. (2) It suffices to observe that (i) the statement $Z^+ = \emptyset$ means that $\forall x \in \mathbb{R} \exists \mathbf{b} \in Z$ such that $\mathbf{b} \cap (x, +\infty) = \emptyset$, i.e., $\mathbf{b} \subset (-\infty, x]$, hence $(-\infty, x] \in Z$; (ii) the statement that $\forall x \in \mathbb{R} (-\infty, x] \in Z$ is equivalent to $N_{\mathbb{R}}(-\infty) \subset Z$. (3) The statement $x \notin Z^-$ means that $\exists \mathbf{b} \in Z$ such that $(-\infty, x) \cap \mathbf{b} = \emptyset$, i.e., $\mathbf{b} \subset [x, +\infty)$, hence $[x, +\infty) \in Z$, and conversely. (4) Follows at once from (1). \square

Corollary 11.13 *If $Z \in \mathcal{F}(A)$ and $Z^+ = \emptyset$ then $Z^- = \mathbb{R}$, and if $Z^- = \emptyset$ then $Z^+ = \mathbb{R}$*

Proof It suffices to prove the first statement. If $Z^+ = \emptyset$ and $x \in \mathbb{R} \setminus Z^-$ then (2) and (3) in Lemma 11.12 imply that $N_{\mathbb{R}}(-\infty) \subset Z$ and $[x, +\infty) \in Z$, hence $\emptyset = (-\infty, x - 1) \cap [x, +\infty) \in Z$, a contradiction. \square

Lemma 11.14 *If $\alpha, \beta \in \mathbb{R}$, $\alpha < \beta$, $Z \in \mathcal{F}(A)$ and $c \in Z$, then*

- (1) *If $c \subset [\beta, +\infty)$ then $(\alpha, \beta) \cap Z^- = \emptyset$.*
- (2) *If $c \subset (-\infty, \alpha]$ then $(\alpha, \beta) \cap Z^+ = \emptyset$.*

Proof (1) If $y \in (\alpha, \beta)$ and $(-\infty, y) \bowtie Z$ then, in particular, $(-\infty, y) \cap \mathbf{b} \neq \emptyset$, but this is impossible, since $c \subset [\beta, +\infty)$. The proof of (2) is similar. \square

Lemma 11.15 *If $Z \in \mathcal{F}(A)$, $x \in \mathbb{R}$, and $\epsilon > 0$, then*

$$\text{if } (x - \epsilon, x + \epsilon) \cap Z^- = \emptyset \text{ or } (x - \epsilon, x + \epsilon) \cap Z^+ = \emptyset \text{ then } x \notin \text{clusterset}(Z, \overline{\mathbb{R}}) \tag{11.5}$$

Proof If $(x - \epsilon, x + \epsilon) \cap Z^- = \emptyset$ then, in particular, $x + \frac{\epsilon}{2} \notin Z^-$. Lemma 11.12 implies that $[x + \frac{\epsilon}{2}, +\infty) \in Z$. Since $(x - \frac{\epsilon}{4}, x + \frac{\epsilon}{4}) \cap [x + \frac{\epsilon}{2}, +\infty) = \emptyset$, it follows that $N_{\mathbb{R}}(x) \not\triangleleft Z$, i.e., $x \notin \text{clusterset}(Z, \overline{\mathbb{R}})$. If $(x - \epsilon, x + \epsilon) \cap Z^+ = \emptyset$ then, in particular, $x - \frac{\epsilon}{2} \notin Z^+$. Lemma 11.12 implies that $(-\infty, x - \frac{\epsilon}{2}] \in Z$. Since $(x - \frac{\epsilon}{4}, x + \frac{\epsilon}{4}) \cap (-\infty, x - \frac{\epsilon}{2}] = \emptyset$, it follows that $N_{\mathbb{R}}(x) \not\triangleright Z$, i.e., $x \notin \text{clusterset}(Z, \overline{\mathbb{R}})$. \square

Lemma 11.16 *If $Z \in \mathcal{F}(\mathbb{R})$ then*

$$\text{clusterset}(Z, \overline{\mathbb{R}}) = [\liminf Z, \limsup Z] \tag{11.6}$$

with the understanding that $[+\infty, +\infty] = \{+\infty\}$ and $[-\infty, -\infty] = \{-\infty\}$.

Proof Theorem 11.1 and Lemma 11.3 imply that it suffices to prove that

$$\mathbf{limsup} Z = \max \mathbf{clusterset}(Z, \overline{\mathbb{R}}) \quad \text{and} \quad \mathbf{liminf} Z = \min \mathbf{clusterset}(Z, \overline{\mathbb{R}}).$$

By symmetry, it suffices to prove the first statement, which amounts to show that

- (i) $\mathbf{limsup} Z \in \mathbf{clusterset}(Z, \overline{\mathbb{R}})$ and (ii) if $\mathbf{limsup} Z < x$ then $x \notin \mathbf{clusterset}(Z, \overline{\mathbb{R}})$.

In order to prove (i), we separately examine the following three cases:

- (i.a) $-\infty < \mathbf{limsup} Z < +\infty$; (i.b) $\mathbf{limsup} Z = -\infty$; (i.c) $\mathbf{limsup} Z = +\infty$.

If (i.a) holds, then either $Z^+ = (-\infty, a)$ or $Z^+ = (-\infty, a]$, where $a = \mathbf{limsup} Z \in \mathbb{R}$, but in either case, for each $\epsilon > 0$,

$$(-\infty, a + \epsilon] \in Z \quad \text{and} \quad (a - \epsilon, +\infty) \not\in Z. \tag{11.7}$$

The first statement in (11.7) follows from Lemma 11.12, since $a + \epsilon \notin Z^+$, the second one from the fact that $a - \epsilon \in Z^+$. If $N_{\mathbb{R}}(a) \triangleleft Z$ then there exists $r > 0$ and $b \in Z$ such that $(a - r, a + r) \cap b = \emptyset$, and this means that

$$\text{either } b \subset [a + r, +\infty) \text{ or } b \subset (-\infty, a - r] \tag{11.8}$$

but (11.8) is incompatible with (11.7) with $\epsilon \stackrel{\text{def}}{=} \frac{r}{2}$. Hence $N_{\mathbb{R}}(a) \not\triangleleft Z$, i.e., $a \in \mathbf{clusterset}(Z, \overline{\mathbb{R}})$, and (i) holds. If (i.b) holds, then $Z^+ = \emptyset$, hence $N_{\mathbb{R}}(-\infty) \subset Z$ (by Lemma 11.12), thus $N_{\mathbb{R}}(-\infty) \not\triangleleft Z$, and this means that $-\infty \in \mathbf{clusterset}(Z, \overline{\mathbb{R}})$. If (i.c) holds, then $Z^+ = \mathbb{R}$, i.e., for each $r \in \mathbb{R}$, $(r, +\infty) \triangleleft Z$, hence $N_{\mathbb{R}}(+\infty) \not\triangleleft Z$, thus $+\infty \in \mathbf{clusterset}(Z, \overline{\mathbb{R}})$. The proof of (i) is complete.

In order to prove (ii), it suffices to examine the following two cases:

- (ii.a) $-\infty < \mathbf{limsup} Z < +\infty$; (ii.b) $\mathbf{limsup} Z = -\infty$.

If (ii.a) holds and $\mathbf{limsup} Z < x$, then there exists $\epsilon > 0$ such that $(x - \epsilon, x + \epsilon) \cap Z^+ = \emptyset$, and Lemma 11.15 implies that $x \notin \mathbf{clusterset}(Z, \overline{\mathbb{R}})$. Hence (ii) holds in this case. If (ii.a) holds then $Z^+ = \emptyset$, and Lemma 11.12 implies that $Z \supset N_{\mathbb{R}}(-\infty)$, i.e., $\mathbf{lim} Z = N_{\mathbb{R}}(-\infty)$. Then Theorem 11.5 implies that

$$\mathbf{clusterset}(Z, \overline{\mathbb{R}}) = \{-\infty\}$$

hence (ii) holds in this case as well, and the proof is complete. □

Corollary 11.17 *If $Z \in \mathcal{F}(\mathbb{R})$ then*

$$\mathbf{liminf} Z \leq \mathbf{limsup} Z. \tag{11.9}$$

Theorem 11.18 *If $Z \in \mathcal{F}(\mathbb{R})$ and $y \in \overline{\mathbb{R}}$ then the following conditions are equivalent:*

- (1) $\liminf Z = \limsup Z = y,$
- (2) $\text{cluster}\text{set}(Z, \overline{\mathbb{R}}) = \{y\},$
- (3) $\lim Z = N_{\mathbb{R}}(y).$

Proof The result follows at once from Theorem 11.5 and Lemma 11.16. □

We now present a different description of the $\limsup Z$ and $\liminf Z$.

Lemma 11.19 *If $Z \in \mathcal{F}(\mathbb{R})$ then*

- (1) $\limsup Z = \inf \{\sup \{x : x \in b\} : b \in Z\}$
- (2) $\liminf_{\mathbb{R}} Z = \sup \{\inf \{x : x \in b\} : b \in Z\}$

Proof It suffices to prove the first statement, by symmetry. If $\limsup Z = +\infty$ then $Z^+ = \mathbb{R}$. Let

$$\alpha \stackrel{\text{def}}{=} \inf \{\sup \{x : x \in b\} : b \in Z\}. \tag{11.10}$$

If $\alpha < +\infty$ then there exists $b \in Z$ with $\sup \{x : x \in b\} < +\infty$. Let $\beta \stackrel{\text{def}}{=} \sup \{x : x \in b\}$. Then $b \subset (-\infty, \beta]$, hence $\beta + 1 \notin Z^+$, a contradiction. Hence $\alpha = +\infty$ and (1) holds. Assume that $\limsup Z = -\infty$. We claim that either $\alpha = +\infty$ or $\alpha \in \mathbb{R}$ lead to a contradiction, and hence $\alpha = -\infty$. Indeed, if $\alpha = +\infty$ then $\sup \{x : x \in b\} = +\infty$ for each $b \in Z$, hence $(r, +\infty) \bowtie Z$ for each $r \in \mathbb{R}$, thus $Z^+ = \mathbb{R}$ and hence $\limsup Z = +\infty$, a contradiction. On the other hand, if $\alpha \in \mathbb{R}$ then $\alpha - 1 < \sup \{x : x \in b\}$ for each $b \in Z$, hence $\alpha - 1 \in Z^+$, i.e., $Z^+ \neq \emptyset$ and hence $\limsup Z > -\infty$, a contradiction. Assume that $-\infty < \limsup Z < +\infty$ and let $\beta \stackrel{\text{def}}{=} \limsup Z$. If $\alpha = +\infty$ then $\sup \{x : x \in b\} = +\infty$ for each $b \in Z$, hence $(r, +\infty) \bowtie Z$ for each $r \in \mathbb{R}$, thus $Z^+ = \mathbb{R}$ and hence $\limsup Z = +\infty$, a contradiction. If $\alpha = -\infty$ then there exists $b_0 \in Z$ such that $\sup \{x : x \in b\} < \beta - 1$, hence $b_0 \subset (-\infty, \beta - 1)$, thus $b_0 \cap (\beta - 1, \beta + 1) = \emptyset$, thus $\beta \notin \text{cluster}\text{set}(Z, \overline{\mathbb{R}})$, a contradiction, by Lemma 11.16. It follows that $\alpha \in \mathbb{R}$. We claim that $\alpha = \beta$. Assume that $r \in \text{cluster}\text{set}(Z, \overline{\mathbb{R}})$, and $\epsilon > 0$. Then $N_{\mathbb{R}}(r) \bowtie Z$, thus $(r - \epsilon, r + \epsilon) \cap b \neq \emptyset$ for each $b \in Z$. Hence $r - \epsilon < \sup \{x : x \in b\}$ for each $b \in Z$, thus $r - \epsilon \leq \alpha$, and since $\epsilon > 0$ is arbitrary, it follows that $r \leq \alpha$. Since this inequality holds for each $r \in \text{cluster}\text{set}(Z, \overline{\mathbb{R}})$, Lemma 11.16 implies that $\limsup Z \leq \alpha$. In order to show that equality holds, it suffices to show that $\alpha \in \text{cluster}\text{set}(Z, \overline{\mathbb{R}})$. Suppose not. Then there exists $\epsilon_0 > 0$ and $b_0 \in Z$ with $(\alpha - 2\epsilon_0, \alpha + 2\epsilon_0) \cap b_0 = \emptyset$. Hence either (i) $b_0 \subset (-\infty, \alpha - 2\epsilon_0)$ or (ii) $b_0 \subset [\alpha + 2\epsilon_0, +\infty)$, but (i) would imply that $\sup \{x : x \in b_0\} < \alpha - 2\epsilon_0$, which is impossible by (11.10). Hence (ii) holds. However, (11.10) implies that there exists $b \in Z$ such that $\sup \{x : x \in b\} < \alpha + \epsilon_0$, and this implies that $b \cap b_0 = \emptyset$, which is also impossible. Hence $\alpha \in \text{cluster}\text{set}(Z, \overline{\mathbb{R}})$. □

Recall that if (A, Z) is a filtered set and $w : A \rightarrow \mathbb{R}$ is a function then $w_{\circ}(Z) \in \mathcal{F}(\mathbb{R})$. The following result will be useful in applications.

Theorem 11.20 *If (A, Z) is a filtered set, $w : A \rightarrow \mathbb{R}$ is a function, and $y \in [-\infty, +\infty]$, then the following conditions are equivalent:*

- (1) $\lim_Z \mathscr{U} = y,$
- (2) $\lim_{\mathscr{U}_\diamond}(Z) = N_{\mathbb{R}}(y),$
- (3) $\liminf_{\mathscr{U}_\diamond}(Z) = \limsup_{\mathscr{U}_\diamond}(Z) = y,$
- (4) $\text{clusterset}(\mathscr{U}_\diamond(Z), \mathbb{R}) = \{y\}.$

Proof The equivalence between (1) and (2) is contained in Proposition 9.38. The equivalence between (2), (3), and (4) follows from Theorem 11.18 □

12 Applications of the Natural Topology to Moore–Smith Sequences of Sets

In this section, we present further results pertaining to Moore–Smith sequences of nonempty subsets of a topological space, which may be obtained as an application of the results on filter presented so far.

12.1 Cofinal Subsets in a Directed Set

The notion of *cluster point* of a Moore–Smith sequence is based on the notion of *cofinal* subsets of a directed set. Recall that $\text{Fin}[A]$ is the collection of all final sets in the directed set A and that it is a filter on A_{Set} , by Lemma 3.25.

Definition 12.1 If A is a directed set then a subset of A is called *cofinal* in A if it overlaps with each tail of A . The collection of all cofinal sets in A is denoted by $\text{cof}(A)$.

Observe that

$$\text{Fin}[A] \subset \text{cof}(A)$$

since in a directed set each tail overlaps with every other tail, and indeed (recall Definition 1.7)

$$\text{cof}(A) = \text{wloc}(\text{Fin}[A]) \tag{12.1}$$

since the statement that a given set overlaps with each tail of A is equivalent to the statement that no tail of A is contained in the complement of the given set, i.e., the complement of the set is not a final set in A . In other words, if $Q \subset A$ then $Q \in \text{cof}(A) \Leftrightarrow \complement Q \notin \text{Fin}[A]$.

Lemma 12.2 *If A is a directed set and $Q \subset A$ then Q and $\complement Q$ cannot both fail to be cofinal.*

Proof The result follows from (12.1). Indeed, if Q and $\complement Q$ both fail to be cofinal, then Q and $\complement Q$ both belong to $\text{Fin}[A]$, and this is impossible since $\text{Fin}[A]$ is a filter. □

12.2 The Cluster Set of a Moore–Smith Sequence of Points

Definition 12.3 If $\omega \in \mathcal{S}(Y)$ and Θ is topology on Y , we say that ω clusters at x if for each $U \in \mathcal{N}_\Theta(x)$ the set $\{k \in A: \omega(k) \in U\}$ is cofinal in A , where A is the direction of ω , and define

$$\text{ClusterSet}(\omega, \Theta) \stackrel{\text{def}}{=} \{x \in Y: \omega \text{ clusters at } x\}. \tag{12.2}$$

Lemma 12.4 If $\omega \in \mathcal{S}(Y)$ and Θ is topology on Y , then $\text{ClusterSet}(\omega, \Theta)$ is closed.

Proof Assume that $x \notin \text{ClusterSet}(\omega, \Theta)$. Then there exists $U \in \mathcal{N}_\Theta(x)$ such that the set $\omega^*(U)$ is not cofinal. Let $O \in \Theta$ such that $O \subset U$ and $x \in O$. If $x \in O$ then $O \in \mathcal{N}_\Theta(x)$ and $\omega^*(O)$ is not cofinal. \square

Observe that if $\lim \omega = y$ then $y \in \text{ClusterSet}(\omega, \Theta)$, hence the limiting values of a Moore–Smith sequence ω belong to the cluster set of ω .

12.3 The Cluster Set of Set-Valued Moore–Smith Sequences

Definition 12.5 If $\omega \in \mathcal{S}(\mathcal{P}_\bullet(Y))$, then the shadow projected by $U \subset Y$ along ω is the set

$$\omega^\bullet[U] \stackrel{\text{def}}{=} \{j \in A_{\text{Set}}: s(j) \cap U \neq \emptyset\}$$

where A is the direction of ω .

Definition 12.6 If $\omega \in \mathcal{S}(\mathcal{P}_\bullet(Y))$, then the inner shadow projected by $U \subset Y$ along ω is the set

$$\omega_\bullet[U] \stackrel{\text{def}}{=} \{j \in A: \omega(j) \subset U\},$$

where A is the direction of ω .

Observe that $\omega_\bullet[U] \subset \omega^\bullet[U]$ and, if $\omega \in \mathcal{S}(Y)$, then $\omega_\bullet[U] = \omega^\bullet[U] = \omega^*(U)$.

Definition 12.7 If ω is a $\mathcal{P}_\bullet(Y)$ -valued Moore–Smith sequence and Θ is a topology on Y , we say that ω clusters at $y \in Y$ if, for each $U \in \mathcal{N}_\Theta(y)$ the shadow $\omega^\bullet[U]$ is cofinal in A , where A is the direction of ω .

If $\omega \in \mathcal{S}(Y)$ then this notion recaptures the one introduced in Definition 12.3, and $\text{ClusterSet}(\omega, \Theta)$ is defined just as in (12.2).

Definition 12.8 If ω is a $\mathcal{P}_\bullet(Y)$ -valued Moore–Smith sequence and Θ is a topology on Y , we say that ω converges to $y \in Y$ and write

$$\lim \omega = y$$

if for each $U \in N_{\Theta}(y)$ the inner shadow $\omega_{\bullet}[U]$ is final in A , where A is the direction of ω . If $\omega \in \mathcal{S}(Y)$ then this notion recaptures Definition 3.18.

Recall that if $\omega \in \mathcal{S}(\mathcal{P}_{\bullet}(Y))$ then $T_Y[\omega] \in \mathcal{F}(Y)$ is the filter of tails of ω , introduced in Sect. 6.2. The following result extends Corollary 9.39 to $\omega \in \mathcal{S}(\mathcal{P}_{\bullet}(Y))$.

Lemma 12.9 *If $\omega \in \mathcal{S}(\mathcal{P}_{\bullet}(Y))$ and Θ is a topology on Y then the following conditions are equivalent:*

- (1) $\lim \omega = y$,
- (2) $\lim T_Y[\omega] = N_{\Theta}(y)$.

Proof Let A be the direction of ω . If (1) holds then for each $U \in N_{\Theta}(y)$ there exists $j \in A$ such that if $k \in A$ and $j_{R_A}k$ then $k \in \omega_{\bullet}[U]$, i.e., $\omega(k) \subset U$, and this means that $Tail_j[\omega] \subset U$, i.e., $U \in T_Y[\omega]$, hence (2) holds. Since all these steps are reversible, the converse implication holds as well. □

Proposition 12.10 *If $\omega \in \mathcal{S}(\mathcal{P}_{\bullet}(Y))$ and Θ is a topology on Y then*

$$ClusterSet(\omega, \Theta) = \mathbf{Cluster}[T_Y[\omega], \Theta]. \tag{12.3}$$

Proof Let $y \in Y$ and let A be the direction of ω . Observe that the condition that $y \in ClusterSet(\omega, \Theta)$ means that for each $U \in N_{\Theta}(y)$ and for each $j \in A$ there exists $k \in A$ such that j_{Rk} and $\omega(k) \cap U \neq \emptyset$, i.e., such that $(\bigcup_{j_{Rk}} \omega(k)) \cap U \neq \emptyset$, and since $(\bigcup_{j_{Rk}} \omega(k)) = Tail_j[\omega]$, this means that for each $U \in N_{\Theta}(y)$ and for each $j \in A$ the intersection between $Tail_j[\omega]$ and U is not empty, and this is equivalent to the condition that $y \in \mathbf{Cluster}[T_Y[\omega], \Theta]$. □

12.4 Applications to the Notion of Moore–Smith Subsequence

There is a close analogy with the situation where $\lim W = Z$ and the one where a sequence $w = \{w_n\}_{n \in \mathbb{N}}$ is a subsequence of a sequence $z = \{z_n\}_{n \in \mathbb{N}}$. The following definition makes this analogy more precise.

Definition 12.11 *If ω and ϱ are $\mathcal{P}_{\bullet}(Y)$ -valued Moore–Smith sequences, we say that ω and ϱ are equivalent if $T_Y[\omega] = T_Y[\varrho]$. We say that ϱ is a Moore–Smith subsequence of ω if $\lim T_Y[\varrho] = T_Y[\omega]$.*

If ϱ and ω are Y -valued sequences and ϱ is a subsequence of ω (in the ordinary sense) then ϱ is a Moore–Smith subsequence of ω .

Lemma 12.12 *If $\omega \in \mathcal{S}(\mathcal{P}_{\bullet}(Y))$, Θ is a topology on Y , and $y \in ClusterSet(\omega, \Theta)$, then then the set*

$$A_y^{\Theta}(\omega) \stackrel{\text{def}}{=} \{(j, U) \in A \times N_{\Theta}(y) : \omega(j) \cap U \neq \emptyset\} \subset A \times N_{\Theta}(y),$$

(where A is the direction of ω) is a directed set under the relation $(j, U)R(k, V)$ iff jRk and $U \supset V$.

Proof Reflexivity and transitivity are immediate. Assume that (j, U) and (k, V) are elements of $A_y^\Theta(\omega)$. Since A is directed, there exists $l \in A$ with jRl and kRl . Since $y \in \text{ClusterSet}(\omega, \Theta)$ and $U \cap V \in N_\Theta(y)$, there exists $g \in A$ with lRg and $\omega(g) \cap U \cap V \neq \emptyset$. Hence $(g, U \cap V) \in A_y^\Theta(\omega)$, $(j, U)R(g, U \cap V)$ and $(k, V)R(g, U \cap V)$. \square

In the following result, we extend to the context of Moore–Smith sequences of sets a familiar fact about sequences of points.

Theorem 12.13 *If $\omega \in \mathcal{S}(\mathcal{P}_\bullet(Y))$, $y \in Y$, and Θ is a topology on Y , then the following conditions are equivalent:*

- (1) $y \in \text{ClusterSet}(\omega, \Theta)$,
- (2) $y \in \mathbf{Cluster}[T_Y[\omega], \Theta]$,
- (3) *there exists a $\mathcal{P}_\bullet(Y)$ -valued Moore–Smith sequence ι such that:*
 - (3.1) ι is a Moore–Smith subsequence of ω ,
 - (3.2) $\lim \iota = y$.

Proof Let A be the direction of ω . Since in Proposition 12.10 we proved that (1) and (2) are equivalent, it suffices to show that (3) \Rightarrow (2) and (1) \Rightarrow (3). If (3) holds then $T_Y[\mathcal{A}] \supset T_Y[\omega]$ and, by Lemma 12.9, $T_Y[\mathcal{A}] \supset N_\Theta(y)$, thus $T_Y[\omega] \vee N_\Theta(y)$ exists, hence (2) holds. Finally, we show that (1) implies (3). If (1) holds, apply Lemma 12.12 and obtain the directed set $A_y^\Theta(\omega)$ described therein. Now define a $\mathcal{P}_\bullet(Y)$ -valued Moore–Smith sequence whose direction is $A_y^\Theta(\omega)$ as follows:

$$\iota: A_y^\Theta(\omega) \rightarrow \mathcal{P}_\bullet(Y), \quad \iota(j, U) \stackrel{\text{def}}{=} \omega(j) \cap U.$$

We claim that ι is a Moore–Smith subsequence of ω and that $\lim \iota = y$.

In order to show that ι is a Moore–Smith subsequence of ω , i.e., $T_Y[\omega] \subset T_Y[\mathcal{A}]$, it suffices to show that if $j \in A$ then $\text{Tail}_j[\omega] \in T_Y[\mathcal{A}]$. Let $U \in N_\Theta(y)$. Then there exists $k \in A$ with jRk and $s(k) \cap U \neq \emptyset$. We claim that

$$\text{Tail}_{(k,U)}[\mathcal{A}] \subset \text{Tail}_j[\omega].$$

Indeed, if $r \in \text{Tail}_{(k,U)}[\mathcal{A}]$ then there exists $(g, V) \in A_y^\Theta(\omega)$ with $(k, U)R(g, V)$ and $r \in \mathcal{A}(g, V)$, i.e., $r \in \omega(g) \cap V$. Since jRk and kRg we have jRg . Moreover, $r \in \omega(g, V) \subset \omega(g)$. We have thus proved that $\text{Tail}_{(k,U)}[\mathcal{A}] \subset \text{Tail}_j[\omega]$ and this means that $\text{Tail}_j[\omega] \in T_Y[\mathcal{A}]$, i.e., $T_Y[\omega] \subset T_Y[\mathcal{A}]$.

We now show that $y = \lim \iota$. Let $U \in N_\Theta(y)$. Since $y \in \text{ClusterSet}(\omega, \Theta)$, there exists $j_U \in A$ with $\omega(j_U) \cap U \neq \emptyset$. Now observe that if $(j, V) \in \text{Tail}_{(j_U, U)}[\mathcal{A}]$ then $\mathcal{A}(j, V) = \omega(j) \cap V$ (by definition), $\omega(j) \cap V \neq \emptyset$ (since $(j, V) \in A_y^\Theta(\omega)$), and $V \subset U$ (since $(j_U, U)R(j, V)$). Hence $\mathcal{A}(j, V) \subset U$. \square

13 Applications to the Problem of the Differentiation of Integrals (II)

Some confusion may arise from the fact that filters on $\mathcal{A}(X)$ takes us one level higher in the hierarchy of powersets, in the following sense: if $Z \in \mathcal{F}(X)$ and $b \in Z$ then $b \subset X$, hence Z is a collection of subsets of X ; however, if $Z \in \mathcal{F}(\mathcal{A}(X))$ and $b \in Z$ then $b \subset \mathcal{P}_\bullet(X)$ (since $b \subset \mathcal{A}(X)$), hence b is a collection of subsets of X , and Z is a family of collections of subsets of X (cf. Sect. 2). In particular, one should not confuse a map as in (1.28) (which is, in particular, a map of the form $X \rightarrow \mathcal{P}(\mathcal{P}(\mathcal{A}(X)))$) with a “family of approach regions,” which is a map $X \rightarrow \mathcal{P}(\mathcal{A}(X))$. For more background, see [11].

Observe that the expression $\lim_{\mathbf{G}(x)} f_\omega$ which appears in (1.29) is the limiting value of f_ω along the filter $\mathbf{G}(x)$, introduced in Definition 1.12. We have seen that this limiting value depends on the behavior of the filter $(f_\omega)_\diamond(\mathbf{G}(x)) \in \mathcal{F}(\mathbb{R})$. In order to reduce notational clutter, we will denote the filter $(f_\omega)_\diamond(\mathbf{G}(x))$ by $\mathbf{G}_f^\omega(x)$, hence we define

$$\mathbf{G}_f^\omega : X \rightarrow \mathcal{F}(\mathbb{R})$$

as follows:

$$\mathbf{G}_f^\omega(x) \stackrel{\text{def}}{=} (f_\omega)_\diamond(\mathbf{G}(x))$$

Lemma 13.1 *If \mathbf{G} is a family of filters on $\mathcal{A}(X)$ based on X , $x \in X$, and $f \in \mathcal{L}^1(X)$, then the following conditions are equivalent:*

- (1) \mathbf{G} differentiates f at x ,
- (2) the following inequalities hold:

$$f(x) \leq \liminf_{\mathbb{R}} \mathbf{G}_f^\omega(x) \leq \limsup_{\mathbb{R}} \mathbf{G}_f^\omega(x) \leq f(x). \tag{13.1}$$

Proof It suffices to apply Proposition 9.38 and Theorem 11.18. □

Remark 13.2 Observe that, if \mathbf{G} is a family of filters on $\mathcal{A}(X)$ based on X , as in (1.28), and $f \in \mathcal{L}^1(X)$, then it is not necessarily true that the functions

$$\liminf_{\mathbb{R}} \mathbf{G}_f^\omega(x) \text{ and } \limsup_{\mathbb{R}} \mathbf{G}_f^\omega(x)$$

are measurable as functions of $x \in X$, unless we impose some conditions on \mathbf{G} . This problem will be handled in Sect. 13.1 by the same method employed in [9].

13.1 Measurability Issues (II)

Lemma 13.3 *If $f, g : X \rightarrow \mathbb{R}$ are (not necessarily measurable) functions, in order to show that*

$$f \geq g \text{ a.e. on } X$$

it suffices to show that

$$\forall \alpha > 0, \quad \forall Q \in \mathcal{A}^*(X), \quad \text{if } g(x) > \alpha \quad \forall x \in Q \text{ then } Q \cap \{f \geq \alpha\} \neq \emptyset. \tag{13.2}$$

Proof Assume that $\omega^* (\{f < g\}) > 0$. Let $B_{m,n} \stackrel{\text{def}}{=} \{f < \frac{m-1}{n} < \frac{m}{n} < g\}$, where m, n are integers, and observe that $\{f < g\} = \bigcup_{m,n} B_{m,n}$. Then there exist m_0, n_0 such that $\omega^*(B_{m_0,n_0}) > 0$, and B_{m_0,n_0} contradicts (13.2). □

Lemma 13.4 *If $f \in \mathcal{L}^1(X)$, $\alpha > 0$, $Q \in \mathcal{A}^*(X)$, then, in order to show that*

$$f(x) > \alpha \text{ for a.e. } x \in Q \tag{13.3}$$

it suffices to show that

$$\forall R \in \mathcal{A}^*(Q), \quad f_\omega[R'] > \alpha, \tag{13.4}$$

where R' is a measurable representative of R .

Proof If $R \stackrel{\text{def}}{=} \{x \in Q : f(x) \leq \alpha\} \in \mathcal{A}^*(X)$, then $R \subset \{x \in X : f(x) \leq \alpha\}$ and since f is measurable, it follows that there exists a measurable representative R' of R such that $R' \subset \{x \in X : f(x) \leq \alpha\}$. Then $f_\omega[R'] \leq \alpha$, a contradiction with (13.4). □

13.2 Proof of Theorem 1.27

Recall from Lemma 13.1 that, in order to show that \mathbf{G} differentiates f , it suffices to prove the two inequalities (13.1) for a.e. $x \in X$. Let us examine the inequality on the right. Our task is then to prove that

$$\limsup_{\mathbb{R}} \mathbf{G}_f^\omega(x) \leq f(x), \text{ a.e. on } X \tag{13.5}$$

and apply Lemmas 13.3 and 13.4 with $g \stackrel{\text{def}}{=} \limsup_{\mathbb{R}} \mathbf{G}_f^\omega(x)$. Recall from Lemma 13.3 that, in order to prove that (13.5) holds, it suffices to show that (13.2) holds, where $g \stackrel{\text{def}}{=} \limsup_{\mathbb{R}} \mathbf{G}_f^\omega(x)$. Let us assume that

$$\alpha > 0, Q \in \mathcal{A}^*(X), \quad \forall x \in Q \quad g(x) > \alpha. \tag{13.6}$$

As we observed in Remark 13.2, the function g is not necessarily measurable. The crucial observation is that $g(x) > \alpha$, i.e., $\mathbf{limsup}_{\mathbb{R}} \mathbf{G}_f^\omega(x) > \alpha$, means, according to Definition 11.8, that there exists $r \in \mathbb{R}$ such that $\alpha < r$ and

$$(r, +\infty) \bowtie (f_\omega)_\diamond(\mathbf{G}(x)). \tag{13.7}$$

Observe that (13.7) means that

$$\forall \mathbf{b} \in \mathbf{G}(x), \quad (r, +\infty) \cap (f_\omega)_*(\mathbf{b}) \neq \emptyset \tag{13.8}$$

and this means that

$$\forall \mathbf{b} \in \mathbf{G}(x) \exists R \in \mathbf{b} \quad \text{such that } f_\omega[R] > r. \tag{13.9}$$

It follows that (13.6) implies that

$$\forall x \in Q \quad \forall \mathbf{b} \in \mathbf{G}(x) \exists R \in \mathbf{b} \quad \text{such that } f_\omega[R] > r \tag{13.10}$$

and this means that \mathbf{G} is adapted to f on Q above α . Observe that, a fortiori, this means that, for each $S \in \mathcal{A}^*(Q)$, \mathbf{G} is adapted to f on S above α . Since \mathbf{G} and f are compatible, it follows that the mean-value of f over R lies above α for each $R \in \mathcal{A}^*(Q)$. Lemma 13.4 then implies that (13.3) holds, hence

$$Q \cap \{f \geq \alpha\} \neq \emptyset. \tag{13.11}$$

Hence we have shown that (13.2) holds, and Lemma 13.3 then implies (13.5). The other inequality in (13.1) follows along similar lines.

13.3 The Maximal Operator Associated to a Family of Filters

Stein’s theorem on limits of sequences of operators shows that the role played by the boundedness properties of the maximal operator, associated to the study of problems of almost everywhere convergence, is not coincidental but essential; see [11]. It is natural to wonder whether to a given family \mathbf{G} of filters on $\mathcal{A}(X)$ based on X , as in (1.28), it is possible to associate a maximal operator which would play a similar role. As we will see presently, since filters on $\mathcal{A}(X)$ takes us one level higher in the hierarchy of powersets, as observed at the beginning of Sect. 13, the definition of such a maximal operator also depends on the choice of a generating basis for $\mathbf{G}(x)$, for each $x \in X$.

Definition 13.5 If \mathbf{G} is a family of filters on $\mathcal{A}(X)$ based on X , as in (1.28), and if $W(x)$ is a generating basis for $\mathbf{G}(x)$ for each $x \in X$, we define

$$Mf(x) \stackrel{\text{def}}{=} \sup \left\{ \frac{1}{\omega(Q)} \int_Q |f| \, d\omega : \exists \mathbf{b} \in W(x), Q \in \mathbf{b} \right\}. \tag{13.12}$$

Theorem 13.6 *If there exists a constant $C > 0$ such that*

$$\omega^*({x \in X: Mf(x) > \lambda}) \leq \frac{C}{\lambda} \int f d\omega \quad (13.13)$$

for each $\lambda > 0$ and each $f \in \mathcal{L}^1(X)$, and if there exists a dense subset $C \subset \mathcal{L}^1(X)$ such that \mathbf{G} differentiates C , then \mathbf{G} differentiates $\mathcal{L}^1(X)$.

Proof The proof follows a standard argument, presented for example in [11, Sect. 5.2.5]. \square

14 Miscellaneous Notes

The notion of filter is due to Cartan [8]. In 1909, Frigyes Riesz understood the role played by the objects that are now called *ultrafilters* in the study of the notions of *continuum* and *completeness* [26, p. 23], foreshadowing the use of ultrafilters in the construction of a compactification of certain topological spaces, implicitly used by Marshall Harvey Stone in 1937 and Henry Wallman in 1937 and 1938, and explicitly adopted by Samuel [30]. These ideas, as well as those of Felix Hausdorff, who formulated the abstract definition of neighborhoods [16, p. 213], were picked up by Root [27, 28]. In 1938, Herman Lyle Smith also attained the notion of filter, in order to build a theory that could include cases seemingly not covered by the Moore–Smith convergence. More information can be found in [34].

The existing literature has apparently not yet reached a consensus on how the notion of a Moore–Smith subsequence of a given Moore–Smith sequence should be defined. This is a bit surprising, since the “right” definition is virtually contained in an observation made by H. Cartan in 1937, and later in 1955 in the work by Bartle [2] and more conclusively in 1972 in a work by Aarnes and Andenæs [1]. In Sect. 12.4 we have given the “right” notion of Moore–Smith subsequence of a given Moore–Smith sequence. The reason this is the most appropriate notion is fully articulated in [1].

Funding Open access funding provided by Università degli Studi G. D’Annunzio Chieti Pescara within the CRUI-CARE Agreement.

Declarations

Conflict of Interest There is no conflict of interest.

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